

## Hall voltage sensor

 $Sub-plate\ installation, Crimping\ terminal\ output. Detect\ DC, AC\ and\ pulse\ current,\ High\ insulation\ between\ primary\ side\ and\ the\ vice\ side\ circuit.$ 







zero gain

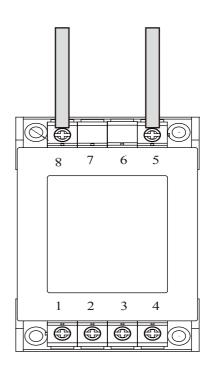
#### Product features

- •Low power consumption
- Good linearity
- No insertion loss
- Fast response time
- Good anti-interference ability

### Product application

- Railway
- Metallurgical
- •Welding machine
- Robot
- Motor
- •Inverter power supply
- · Variable frequency governor
- •Uninterrupted power supply and communication power supply

High side after wiring
Terminal proposal seal processing





# Electrical parameters: ( The following parameters are typical values and actual values will be subject to product testing )

#### Remarks:

$I_{PN}$	Rated input	$\pm50$ V	±100V	±200V	±300V	±400V	±500V	Standard input
Ipm	Input measurement range	±75V	±150V	$\pm300V$	±450V	$\pm600\mathrm{V}$	±750V	Default is 1.5 times of rated input
Vout	Rated output	$2.5V \pm 0.625V$						Standard output
X	Accuracy	1 %						$I = I_{PN}$
εL	Linearity	0.2%						$I=0^{\sim} \pm I_{PN}$
Vс	Supply voltage	+5 V						Supply voltage range±5%
Ιc	Current consumption	$\leq 20\mathrm{mA} + \mathrm{Is}$						Reference will be subject to the measured
R1	Load impedance	≥10KΩ						Collection port impedance while lower voltage affect accuracy
Voe	Zero offset voltage	$\leq \pm 30 \mathrm{mV}$						TA=25°C
Tr	Response time	40 <sup>~</sup> 200 μ s						Reference will be subject to the measured
N.w	Weight	185g						Reference will be subject to the measured
Ta	Operation temperature	-10 ~+70 °C						
Ts	Storage temperature	-25~+70°C						
Bw	Band width	-						Factory test according to DC
Vd	Delectric strength	3.5KV 50Hz 1min						

#### Factory commissioning:

Calculation formula: 2.5V±0.625V 0V datum

- 1. Debugging with 0V as the reference point(acquiescence) Forward direction: 2.5+ ( $I/I_{PN}$ ) \*0.625
- 2. Debug with Vref as the reference point(optional) Reverse direction:  $2.5-(1/I_{PN})$  \*0.625

#### Instruction for use:

- 1. Correct wiring as indicated
- 2. Full scale measurement, response time and following the speed for the best
- 3. Faulty wiring can lead to product damage and output uncertainty

#### Safe operation:

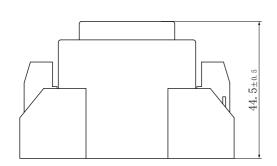
- \*Please read this specification carefully before use.
- \*When you need to move the product, please be sure to disconnect the power and all the connected cables.
- \*If found shell, devices attached to the fixed parts, wire, or have any damaged, please immediately deal with hidden dangers.
- \*If there is any doubt about the safe operation of the equipment, the equipment and the corresponding accessories should be closed immediately, and the fastest time for troubleshooting.

#### Proclamations:

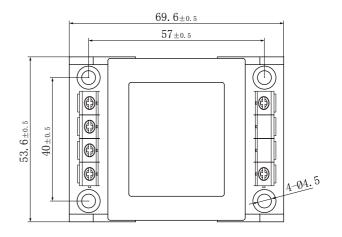
As our products are constantly being improved and updated, we reserve the right to modify the content of this specification at any time without prior notice.



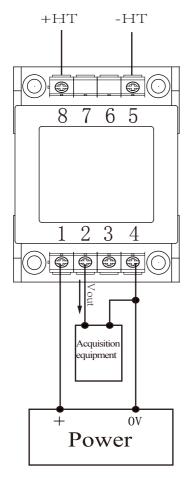
#### Dimensions(in $mm\pm0.5$ ):



Side view



Top view



## Terminal definition:

1: +V

2: Vout

3: Vref

4: 0V

5: -HT 6: Air terminal

8: +HT 7: Air terminal

### **X** Detection:

- ①Choose the auxiliary power supply with small ripple ( $\leq 10 \text{mV}$ )
- ②Switch on auxiliary power
- 3 The auxiliary power is connected to the sensor
- 4 The sensor detects the primary current