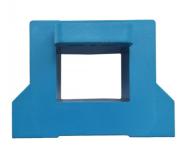
# HKS4030



## Hall open loop current sensor

sub-plate mount, terminal output.Detect DC,AC and pulse current, High insulation between primary side and the vice side circuit.







Front view

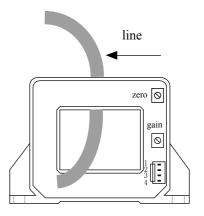
Epoxy view

Fixed hole view

### Product features

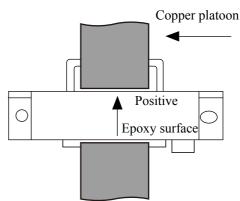
- •Light weight
- •Low power consumption
- •Good linearity
- •No insertion loss
- Fast response time
- •Good anti-interference ability

# Installation diagram



## Product application

- •Railway
- Metallurgical
- •Welding machine
- Robot
- Motor
- Inverter power supply
- Variable frequency governor
- •Uninterrupted power supply and communication power supply





Electrical parameters: ( The following parameters are typical values and actual values will be subject to product testing )								Remarks:
т	Rated input	$\pm 200 \text{A}$	±500A	+ 8001	$\pm 10001$	+ 19004	$\pm 1500 \text{A}$	Standard input
I <sub>PN</sub> Ipm	Input measurement range	± 300A	$\pm 750$ A	_	-	_	$\pm 2250 \text{A}$	Default is 1.5 times of rated input
Vout	Rated output	2.5V $\pm$ 0.625V						Standard output
Х	Accuracy	1%						I=I <sub>PN</sub>
εL	Linearity	1%						$I=0^{\sim}\pm I_{PN}$
Vс	Supply voltage	+ 5 V						Supply voltage range±5%
Ιc	Current consumption	$\leq 16 \mathrm{mA}$						Reference will be subject to the measured
R1	Load impedance	$\geq 10$ K $\Omega$						Collection port impedance while lower voltage affect accuracy
Voe	Zero offset voltage	$\leq \pm 15 \mathrm{mV}$						TA=25 ℃
Tr	Response time	<5 µ s						Reference will be subject to the measured
N.w	Weight	266g						Reference will be subject to the measured
Ta	Operation temperature	$-10 \sim +70 \ ^{\circ}\text{C}$						
Ts	Storage temperature	$-25 \sim +70 ^{\circ}\mathrm{C}$						
Bw	Band width	DC <sup>~</sup> 25KHz						Factory test according to DC
Vd	Delectric strength	4.5KV 50Hz 1min						

#### Factory commissioning :

#### Calculation formula: 2.5V±0.625V 0V datum

Reverse direction: 2.5-  $(I/I_{PN})$  \*0.625

- 1. Debugging with 0V as the reference point(acquiescence) Forward direction: 2.5+  $(I/I_{PN})$  \*0.625
- 2. Debug with Vref as the reference point(optional)

#### Instructions for use:

- 1. According to the connection mode of correct connection
- 2. The direction shown by the arrow is positive
- 3. With hole measurement, response time and following the speed for the best
- 4. Faulty wiring can lead to product damage and output uncertainty

#### Safe operation:

\*Please read this specification carefully before use.

\*When you need to move the product, please be sure to disconnect the power and all the connected cables.

\*If found shell, devices attached to the fixed parts, wire, or have any damaged, please immediately deal with hidden dangers.

\*If there is any doubt about the safe operation of the equipment, the equipment and the corresponding accessories should be closed immediately, and the fastest time for troubleshooting.

#### Proclamations:

As our products are constantly being improved and updated, we reserve the right to modify the content of this specification at any time without prior notice.



 $46\pm0.5$ 

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