

# Hall open loop current sensor

Pressure plate installation, terminal output. Detect DC, AC and pulse current, High insulation between primary side and the vice side circuit.



Front view

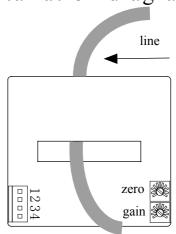


Back view

### Product features

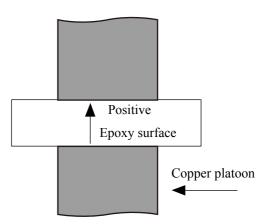
- ·Light weight
- •Low power consumption
- · Good linearity
- No insertion loss
- Fast response time
- Good anti-interference ability

## Installation diagram



## Product application

- Railway
- Metallurgical
- · Welding machine
- Robot
- Motor
- •Inverter power supply
- Variable frequency governor
- Uninterrupted power supply and communication power supply





# Electrical parameters: ( The following parameters are typical values and actual values will be subject to product testing )

#### Remarks:

Ip	Rated input	±100A	±200A	±300A	$\pm 500$ A	±600A	±800A	Standard input
Ipm	Input measurement range	±150A	$\pm 300 A$	$\pm 450 \mathrm{A}$	$\pm750$ A	±800A	±800A	Default is 1.5 times of rated input, and maximum \( \le 800A \) (saturation)
Vout	Rated output	$2.5V \pm 0.625V$						Standard output
X	Accuracy	1%						I=Ip
εL	Linearity	1%						$I=0^{\sim} \pm Ip$
Vс	Supply voltage	+5 V						One or the other Supply voltage range±5%
Ιc	Current consumption	≤15mA						Reference will be subject to the measured
R1	Load impedance	≥10KΩ						Collection port impedance while lower voltage affect accuracy
Voe	Zero offset voltage	$\leq$ $\pm$ 15 m V						TA=25°C
Tr	Response time	≤5 μ s						Reference will be subject to the measured
N.w	Weight	100g						Reference will be subject to the measured
Ta	Operation temperature	$-10$ $\sim$ $+70$ $^{\circ}$ C						
Ts	Storage temperature	-25 ∼ + $70$ °C						
Bw	Band width	$\mathtt{DC}^{\sim}25\mathtt{KHz}$						Factory test according to DC
Vd	Delectric strength	2.5KV 50Hz 1min						

#### Factory commissioning:

Calculation formula: 2.5V±0.625V 0V datum

- 1. Debugging with 0V as the reference point(acquiescence) Forward direction: 2.5+ (I/IP) \*0.625
- 2. Debug with Vref as the reference point(optional)

Reverse direction: 2.5-(I/IP)\*0.625

### Instructions for use:

- 1. According to the connection mode of correct connection
- 2. The direction shown by the arrow is positive
- 3. With hole measurement, response time and following the speed for the best
- 4. Faulty wiring can lead to product damage and output uncertainty

#### Safe operation:

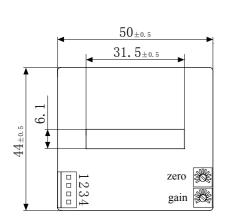
- \*Please read this specification carefully before use.
- \*When you need to move the product, please be sure to disconnect the power and all the connected cables.
- \*If found shell, devices attached to the fixed parts, wire, or have any damaged, please immediately deal with hidden dangers.
- \*If there is any doubt about the safe operation of the equipment, the equipment and the corresponding accessories should be closed immediately, and the fastest time for troubleshooting.

#### Proclamations:

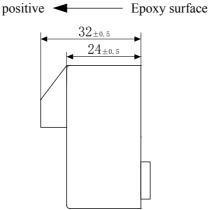
As our products are constantly being improved and updated, we reserve the right to modify the content of this specification at any time without prior notice.

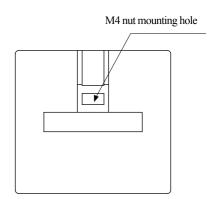


#### Dimensions(in mm±0.5):



Current direction



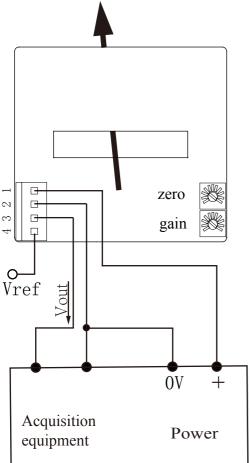


Front view

Side view

Back view

## Wiring diagram (based on 0 V)



Connector Illustration:



Quick plug which spacing 2.54 mm

## Terminal definition:

1: +V

2: 0V

3: Vout

4: Vref (It can be suspended, not grounded)

# Potentiometer definition:

Up: zero

Down: gain

#### **X** Detection:

- ①Choose the auxiliary power supply with small ripple ( $\leq 10$ mV)
- ②Switch on auxiliary power
- 3 The auxiliary power is connected to the sensor
- 4)The sensor detects the primary current