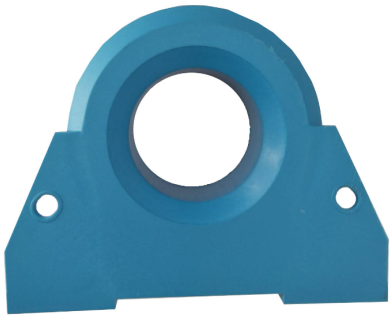
HKS2032

Hall open loop current sensor

sub-plate mount, terminal output.Detect DC,AC and pulse current, High insulation between primary side and the vice side circuit.



Front view

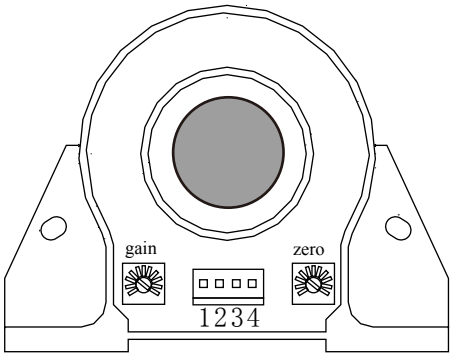
Epoxy view

Fixed hole view

Product features

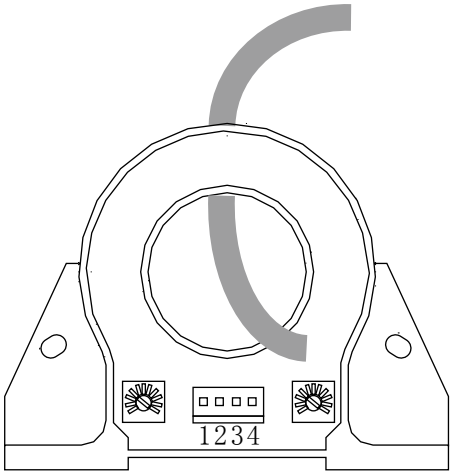
- Light weight
- Low power consumption
- Good linearity
- No insertion loss
- Fast response time
- Good anti-interference ability

Installation diagram



Product application

- Railway
- Metallurgical
- Welding machine
- Robot
- Motor
- Inverter power supply
- Variable frequency governor
- Uninterrupted power supply and communication power supply



Electrical parameters: (The following parameters are typical values and actual values will be subject to product testing)

I_{PN}	Rated input	±100A	±200A	±300A	±400A	±500A	±600A	Standard input
Ipm	Input measurement range	±150A	±300A	±450A	±600A	±750A	±900A	Default is 1.5 times of rated input, and maximum ≤1000A (saturation)
Vout	Rated output	2.5V±0.625V						Standard output
X	Accuracy	1%						$I=I_{PN}$
εL	Linearity	1%						$I=0\sim\pm I_{PN}$
Vc	Supply voltage	+5V						Supply voltage range±5%
Ic	Current consumption	≤12mA						Reference will be subject to the measured
Rl	Load impedance	≥10KΩ						Collection port impedance while lower voltage affect accuracy
Voe	Zero offset voltage	≤±15mV						TA=25℃
Tr	Response time	≤5μs						Reference will be subject to the measured
N.w	Weight	215g						Reference will be subject to the measured
Ta	Operation temperature	-10～+70℃						
Ts	Storage temperature	-25～+70℃						
Bw	Band width	DC~10KHz						Factory test according to DC
Vd	Delectric strength	6KV 50Hz 1min						

Remarks:

Factory commissioning :

1. Debugging with 0V as the reference point(acquiescence)
2. Debug with Vref as the reference point(optional)

Calculation formula：2.5V±0.625V 0V datum

Forward direction：$2.5+(I/I_{PN})*0.625$

Reverse direction：$2.5-(I/I_{PN})*0.625$

Instructions for use:

1. According to the connection mode of correct connection
2. The direction shown by the arrow is positive
3. With hole measurement, response time and following the speed for the best
4. Faulty wiring can lead to product damage and output uncertainty

Safe operation:

*Please read this specification carefully before use.

*When you need to move the product, please be sure to disconnect the power and all the connected cables.

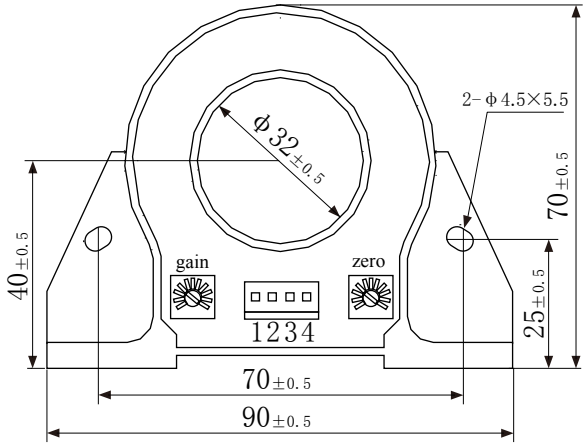
*If found shell, devices attached to the fixed parts, wire, or have any damaged, please immediately deal with hidden dangers.

*If there is any doubt about the safe operation of the equipment, the equipment and the corresponding accessories should be closed immediately, and the fastest time for troubleshooting.

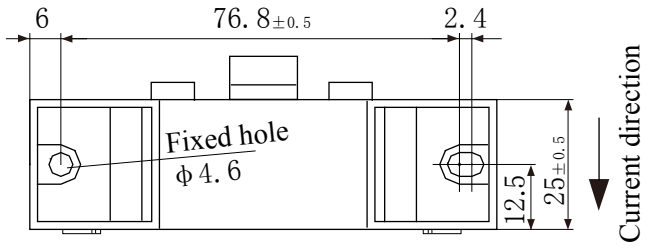
Proclamations:

As our products are constantly being improved and updated, we reserve the right to modify the content of this specification at any time without prior notice.

Dimensions(in mm±0.5）：

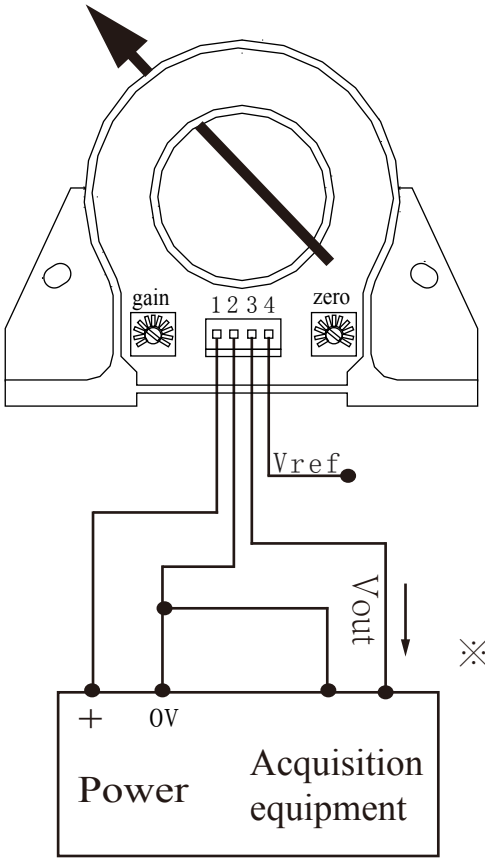


Front view

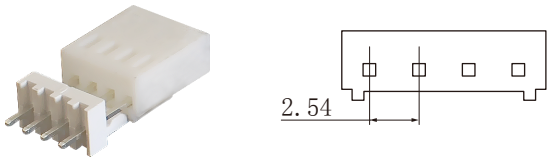


Bottom view

Wiring diagram (based on 0 V)



Connector Illustration:



Spacing 2.54 mm

Terminal definition:

1: +V

2: 0V

3: Vout

4: Vref（It can be suspended, not grounded）

Potentiometer definition:

left: gain

right: zero

※Detection:

①Choose the auxiliary power supply with small ripple (≤10mV)

②Switch on auxiliary power

③The auxiliary power is connected to the sensor

④The sensor detects the primary current