

Hall open loop current sensor

PCB mounting, Detect DC, AC and pulse current, High insulation between primary side and the vice side circuit.



Front view



Epoxy view

Product features

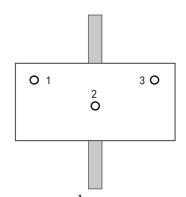
- ·Light weight
- •Low power consumption
- Good linearity
- No insertion loss
- Fast response time
- Good anti-interference ability

Installation diagram



Product application

- Railway
- Metallurgical
- Welding machine
- Robot
- Motor
- •Inverter power supply
- Variable frequency governor
- •Uninterrupted power supply and communication power supply





Electrical parameters: (The following parameters are typical values and actual values will be subject to product testing)

Remarks:

Ιp	Rated input	± 10 A	$\pm 20 A$	$\pm 30A$	±50 A	±60 A	$\pm 80 A$	Standard input
Ipm	Input measurement range	±15A	$\pm 30 \mathrm{A}$	±45 A	±75 A	$\pm90\mathrm{A}$	$\pm 100 A$	Default is 1.5 times of rated input, and maximum \(\le 100A \) (saturation)
Vout	Rated output	$2.5V \pm 0.625V$						Standard output
X	Accuracy	1 %						I=IP
εL	Linearity	1 %						$I=0^{\sim} \pm IP$
Vс	Supply voltage	+5V						Supply voltage range±5%
Ιc	Current consumption	≤15mA						Reference will be subject to the measured
R1	Load impedance	≥10KΩ						Collection port impedance while lower voltage affect accuracy
Voe	Zero offset voltage	$\leq \pm 15 \mathrm{mV}$						TA=25°C
Tr	Response time	≤5 μ s						Reference will be subject to the measured
N.w	Weight	6 g						Reference will be subject to the measured
Ta	Operation temperature	-10 ~+70 °C						
Ts	Storage temperature	-25 ∼ $+70$ °C						
Bw	Band width	$DC^{\sim}100 \mathrm{KHz}$						Factory test according to DC
Vd	Delectric strength	2.5KV 50Hz 1min						

Calculation formula: 2.5V±0.625V 0V datum

Forward direction: 2.5+ (I/IP) *0.625

Reverse direction: 2.5-(I/IP)*0.625

Instructions for use:

- 1. According to the connection mode of correct connection
- 2. The direction shown by the arrow is positive
- 3. With hole measurement, response time and following the speed for the best
- 4. Faulty wiring can lead to product damage and output uncertainty

Safe operation:

- *Please read this specification carefully before use.
- *When you need to move the product, please be sure to disconnect the power and all the connected cables.
- *If found shell, devices attached to the fixed parts, wire, or have any damaged, please immediately deal with hidden dangers.
- *If there is any doubt about the safe operation of the equipment, the equipment and the corresponding accessories should be closed immediately, and the fastest time for troubleshooting.

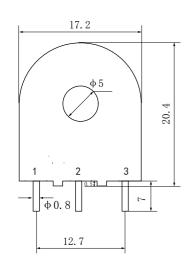
Proclamations:

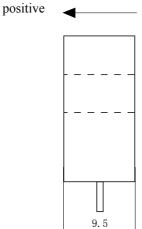
As our products are constantly being improved and updated, we reserve the right to modify the content of this specification at any time without prior notice.

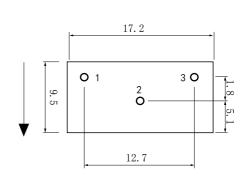


Dimensions(in mm±0.5):

Current direction





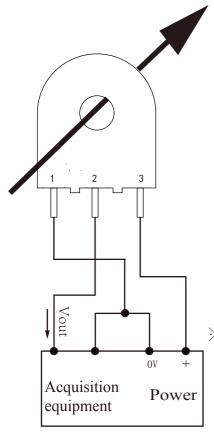


Front view

Side view

Bottom view

Wiring diagram (based on 0 V)



Pin definition:

Epoxy surface

1: 0V

2: Vout

3: +V

X Detection:

- ①Choose the auxiliary power supply with small ripple ($\leq 10 \text{mV}$)
- ②Switch on auxiliary power
- 3)The auxiliary power is connected to the sensor
- **4** The sensor detects the primary current