

Hall open loop current sensor

PCB mounting, Detect DC, AC and pulse current, High insulation between primary side and the vice side circuit.



Front view

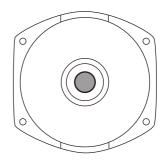


Epoxy view

Product features

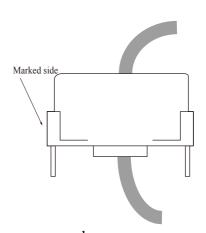
- ·Light weight
- •Low power consumption
- Good linearity
- •No insertion loss
- Fast response time
- •Good anti-interference ability

Installation diagram



Product application

- Railway
- Metallurgical
- Welding machine
- Robot
- Motor
- •Inverter power supply
- Variable frequency governor
- •Uninterrupted power supply and communication power supply





$Electrical\ parameters: (\ The\ following\ parameters\ are\ typical\ values\ and\ actual\ values\ will\ be\ subject\ to\ product\ testing\)$

Remarks:

I_{PN}	Rated input	±10A	±20A	±30A	± 50 A	±60 A	$\pm 80A$	Standard input
Ipm	Input measurement range	±15A	±30A	$\pm 45 \text{A}$	±75A	±90A	±100A	Default is 1.5 times of rated input, and maximum ≤100A (saturation)
Vout	Rated output	$2.5V \pm 0.625V$						Standard output
X	Accuracy	1 %						$I = I_{PN}$
εL	Linearity	1 %						$I=0^{\sim} \pm I_{PN}$
Vс	Supply voltage	+ 5 V						Supply voltage range±5%
Ιc	Current consumption	≤15mA						Reference will be subject to the measured
R1	Load impedance	≥10KΩ						Collection port impedance while lower voltage affect accuracy
Voe	Zero offset voltage	$\leq \pm 15 \mathrm{mV}$						TA=25°C
Tr	Response time	≤5 μ s						Reference will be subject to the measured
N.w	Weight	6 g						Reference will be subject to the measured
Ta	Operation temperature	-10~+70°C						
Ts	Storage temperature	-25~+70°C						
Bw	Band width	$\mathrm{DC}^{\sim}100\mathrm{KHz}$						Factory test according to DC
Vd	Delectric strength	2.5KV 50Hz 1min						

Calculation formula: 2.5V±0.625V 0V datum

Forward direction: 2.5+ (I/I_{PN}) *0.625

Reverse direction: $2.5-(I/I_{PN})*0.625$

Instructions for use:

- 1. According to the connection mode of correct connection
- 2. The direction shown by the arrow is positive
- 3. With hole measurement, response time and following the speed for the best
- 4. Faulty wiring can lead to product damage and output uncertainty

Safe operation:

- *Please read this specification carefully before use.
- *When you need to move the product, please be sure to disconnect the power and all the connected cables.
- *If found shell, devices attached to the fixed parts, wire, or have any damaged, please immediately deal with hidden dangers.
- *If there is any doubt about the safe operation of the equipment, the equipment and the corresponding accessories should be closed immediately, and the fastest time for troubleshooting.

Proclamations:

As our products are constantly being improved and updated, we reserve the right to modify the content of this specification at any time without prior notice.

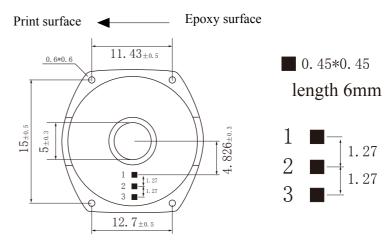


Dimensions(in mm±0.5):

18±0.5

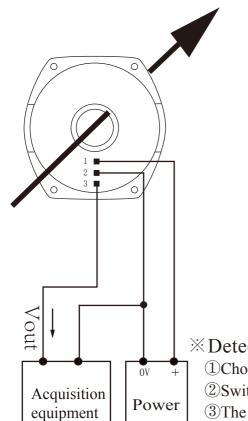
Front view

Current direction



Bottom view (Epoxy surface)

Wiring diagram (based on 0 V)



Pin definition:

1: +V

2: 0V

3: Vout

X Detection:

①Choose the auxiliary power supply with small ripple ($\leq 10 \text{mV}$)

②Switch on auxiliary power

3 The auxiliary power is connected to the sensor

4 The sensor detects the primary current