

# Hall open loop current sensor

PCB mounting, Detect DC, AC and pulse current, High insulation between primary side and the vice side circuit.







Front view

Epoxy view

Bottom view

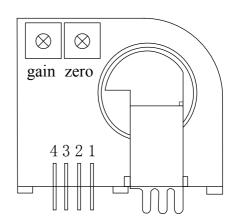
#### Product features

- ·Light weight
- •Low power consumption
- Good linearity
- •No insertion loss
- Fast response time
- Good anti-interference ability

### Product application

- Railway
- Metallurgical
- Welding machine
- Robot
- Motor
- •Inverter power supply
- · Variable frequency governor
- Uninterrupted power supply and communication power supply

### Installation diagram



String the sensor bus into the circuit under test



## Electrical parameters: (The following parameters are typical values and actual values

ectrical parameters: ( The following parameters are typical values and actual values will be subject to product testing )						Remarks:
Rated input	±50A	±100A	+200A	±300A	±400A	Standard input
-	_	_		_	_	•
Input measurement range	$\pm75A$	$\pm 150$ A	$\pm 300A$	$\pm 450$ A	$\pm 600A$	Default is 1.5 times of rated input
Rated output	± 4 V					Standard output
Accuracy	1%					$I = I_{PN}$
Linearity	1%					$I=0^{\sim} \pm I_{PN}$
Supply voltage	$\pm$ 12V/ $\pm$ 15V					One or the other Supply voltage range±5%
Current consumption	$\pm$ 15mA				Reference will be subject to the measured	
Load impedance	≥10KΩ				Collection port impedance while lower voltage affect accuracy	
Zero offset voltage	$\leq$ $\pm$ 15mV					TA=25°C
Response time	€3 μ s					Reference will be subject to the measured
Weight	29 g					Reference will be subject to the measured
Operation temperature	$-10$ $\sim$ $+70$ $^{\circ}$ C					
Storage temperature	-25 ∼ + $70$ °C					
Band width	$DC^{\sim}50KHz$					Factory test according to DC
Delectric strength	2.5KV 50Hz 1min					

#### Instructions for use:

 $I_{PN}$ 

Ipm

εL

Vс

Ιc

R1

Voe

Tr

N.w

Тa

Ts

Bw Vd

Vout Rat

- 1. According to the connection mode of correct connection
- 2. The direction shown by the arrow is positive
- 3. With hole measurement, response time and following the speed for the best
- 4. Faulty wiring can lead to product damage and output uncertainty

#### Safe operation:

- \*Please read this specification carefully before use.
- \*When you need to move the product, please be sure to disconnect the power and all the connected cables.
- \*If found shell, devices attached to the fixed parts, wire, or have any damaged, please immediately deal with hidden dangers.
- \*If there is any doubt about the safe operation of the equipment, the equipment and the corresponding accessories should be closed immediately, and the fastest time for troubleshooting.

#### Proclamations:

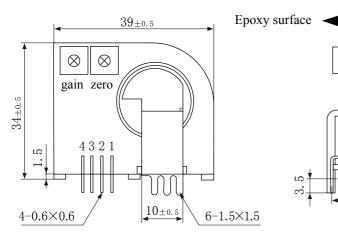
As our products are constantly being improved and updated, we reserve the right to modify the content of this specification at any time without prior notice.

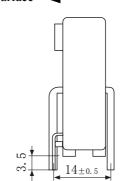


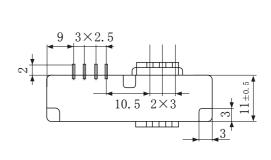
#### Dimensions (in $mm\pm0.5$ ):

#### Current direction

positive





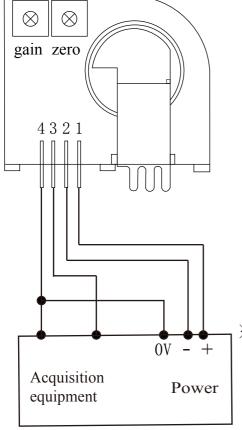


Front view

Side view

Bottom view

### Wiring diagram



## Pin definition:

1: +V

2: -V

3: Vout

4: 0V

# Potentiometer definition:

Left: gain

Right: zero

#### 

- ①Choose the auxiliary power supply with small ripple ( $\leq 10 \text{mV}$ )
- ②Switch on auxiliary power
- 3 The auxiliary power is connected to the sensor
- (4) The sensor detects the primary current