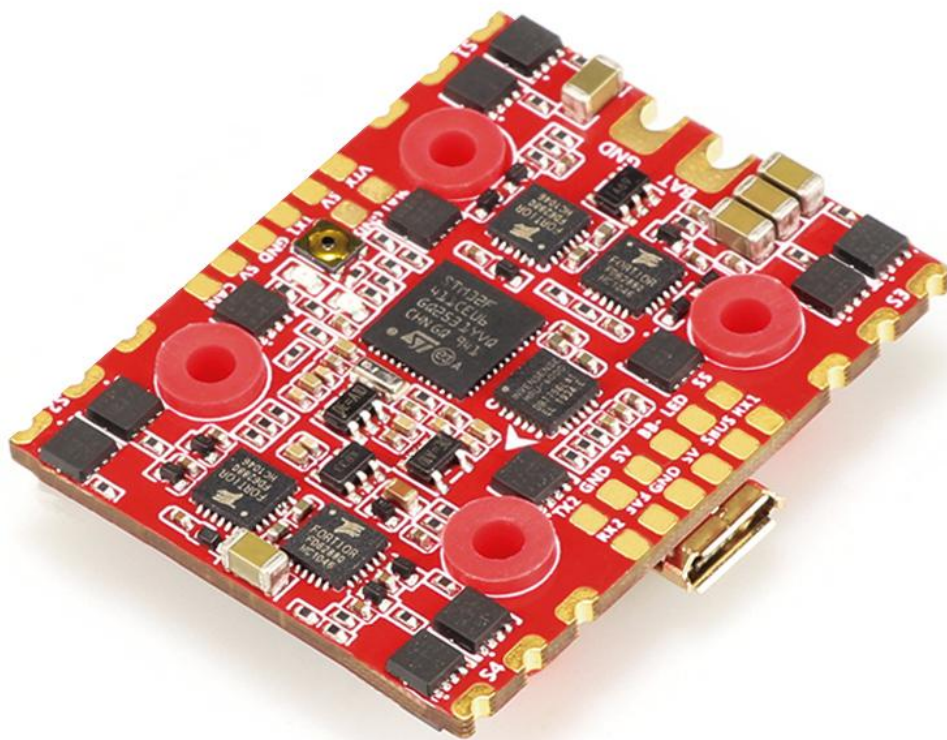


# Zeus35

# Flight Controller

# Manual





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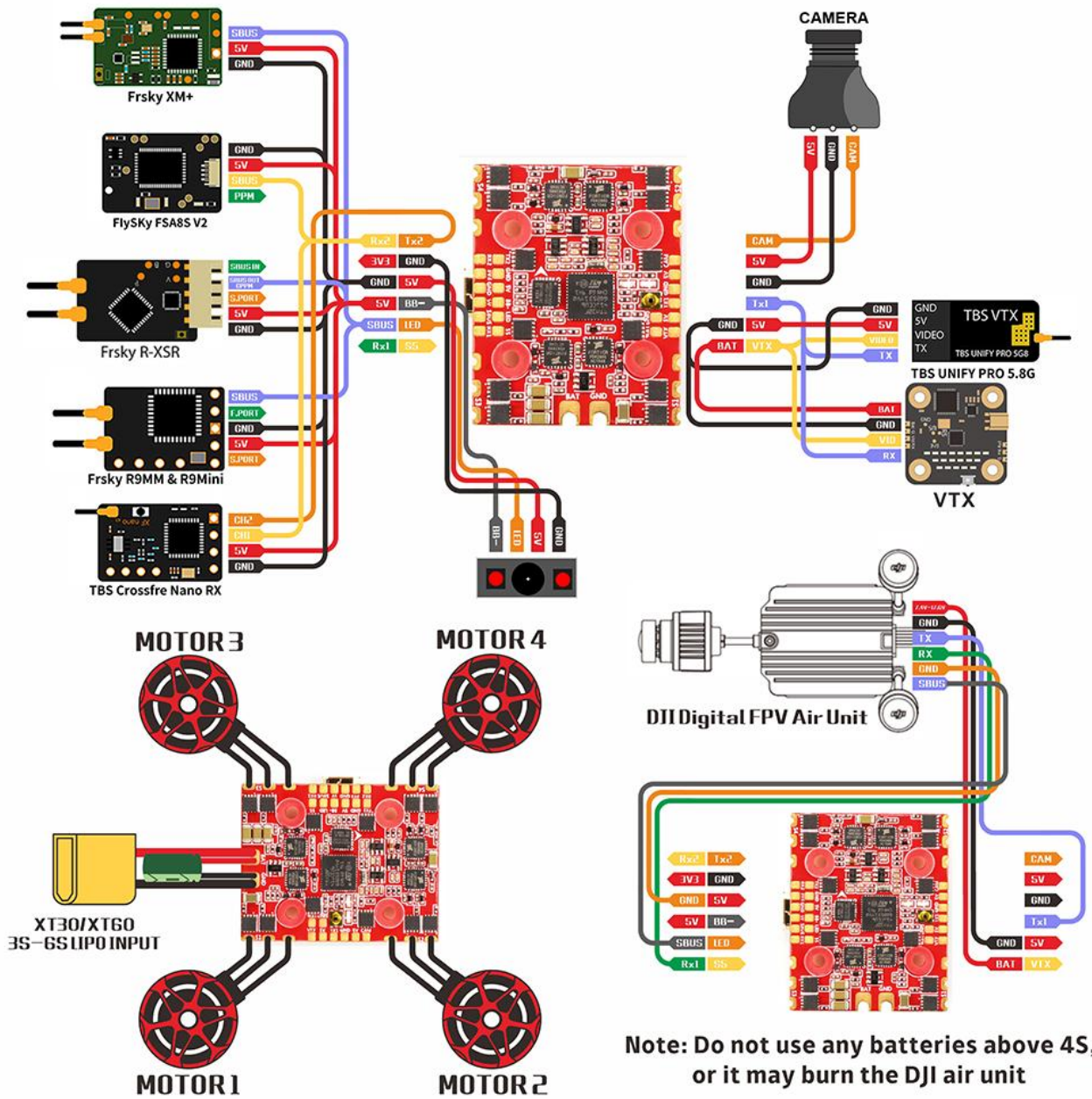
## Package Included

HGLRC Zeus35 FC*1	Accessory Bag*1
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# 1. Product Specifications

Product parameters	
Model	Zeus35 AIO Flight Controller
Weight	10g
Input Voltage	3-6S
Usage	for 100mm-250mm Frame Kit
Installing Hole	20x20mm/M2/M3
Dimensions	40x32mm
FC Firmware	BF HGLRCF411(HGLR)
CPU	STM32F411
MPU	MPU6000
BEC	5V/2A
BlackBox	16M
UARTS	2
ESC Firmware	BLS
Current Sensor	Support
Constant Current	35A
Peak Current	40A (10s)

# 2. Interface Description

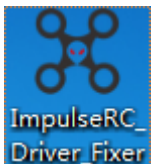


## 3. Check the flight control drive

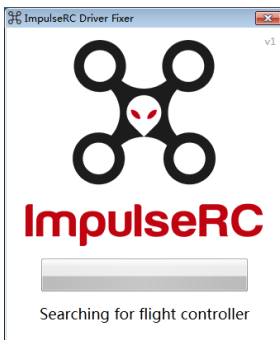
1. Long Press BOOT buttons.connect USB.The system automatically install the driver



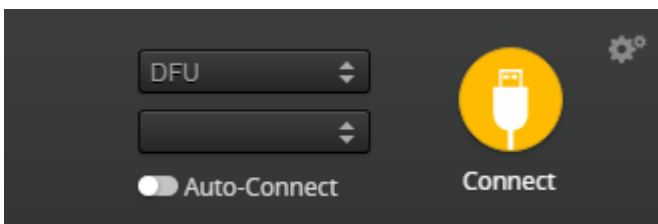
2.Driver cannot be installed, please download ImpulseRC\_Driver\_Fixer



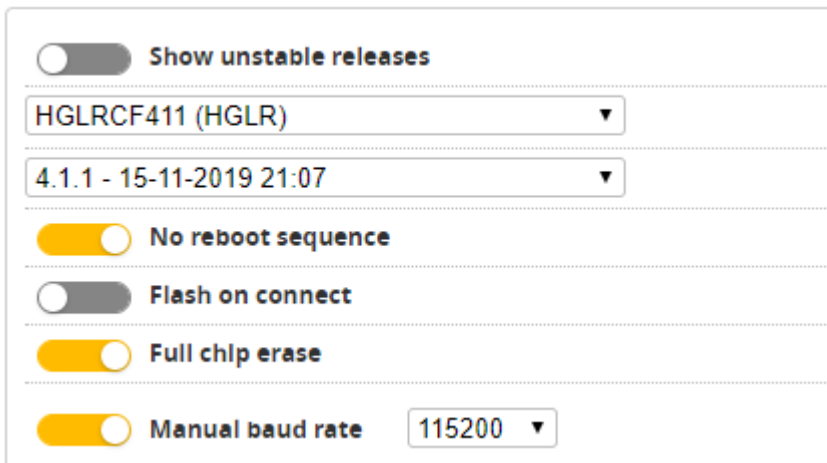
3.Double-click on the run(Plug in the flight controller to automatically install the driver)



4.open betaflyght configurator , enter DFU mode



5. Click **Firmware Flasher** Select firmware version




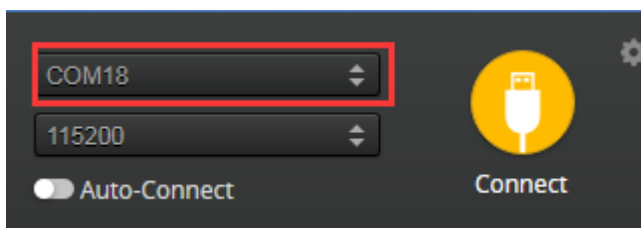
The screenshot shows the Firmware Flasher interface with the following settings:

- Show unstable releases:
- Firmware: HGLRCF411 (HGLR)
- Version: 4.1.1 - 15-11-2019 21:07
- No reboot sequence:
- Flash on connect:
- Full chip erase:
- Manual baud rate: 115200


6. Click **Load Firmware [Online]** Load firmware. **Flash Firmware** Waiting for completion **Erasing ...** It will be prompted upon completion.

**Programming: SUCCESSFUL**

7. open betaflyght configurator . Controller plugged into the computer. Betaflight Automatically assigned port. click "Connect" Enter setup interface ( Different computer COM )

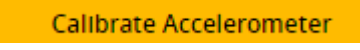


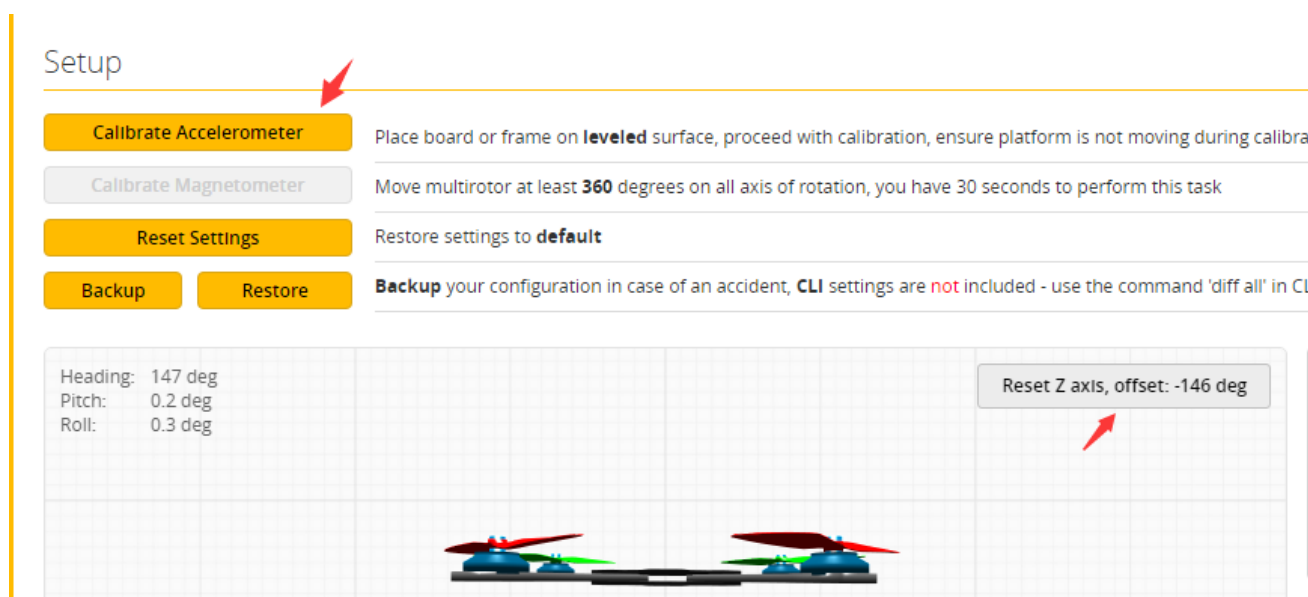
The screenshot shows the Betaflight configurator interface with the following settings:

- COM: COM18
- Baud rate: 115200
- Auto-Connect:
- Connect button: 

## 4. Calibration accelerometer

1. Put the aircraft horizontal and click “Reset Z axis”

Click again 




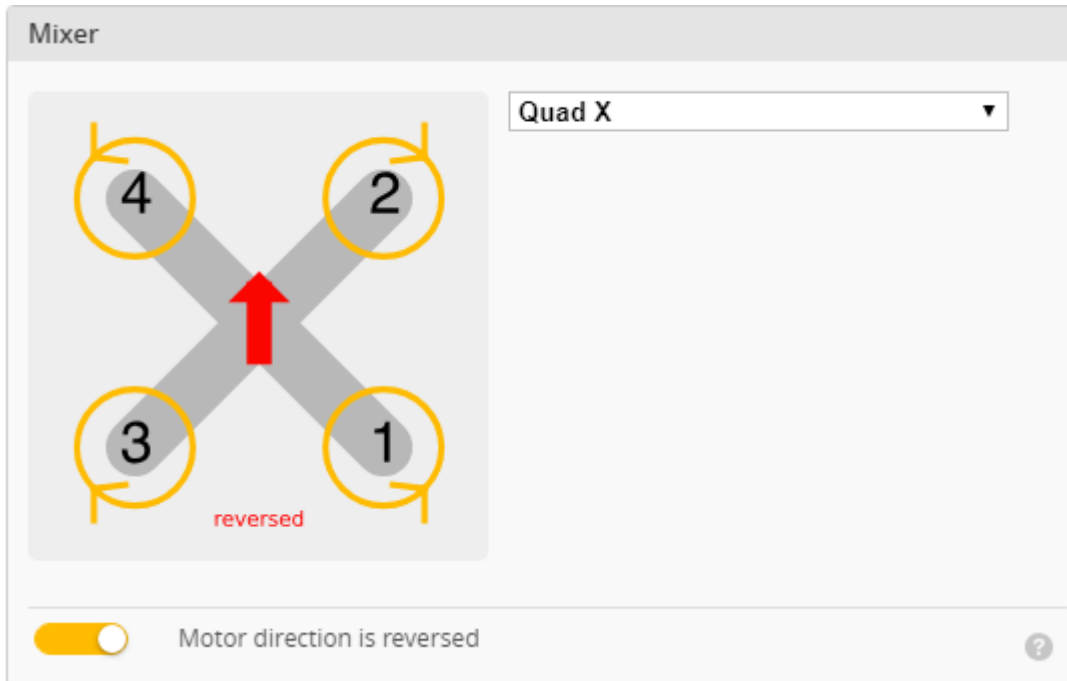
## 5. URAT serial port use


1. URAT1 uses the VTX/DJI

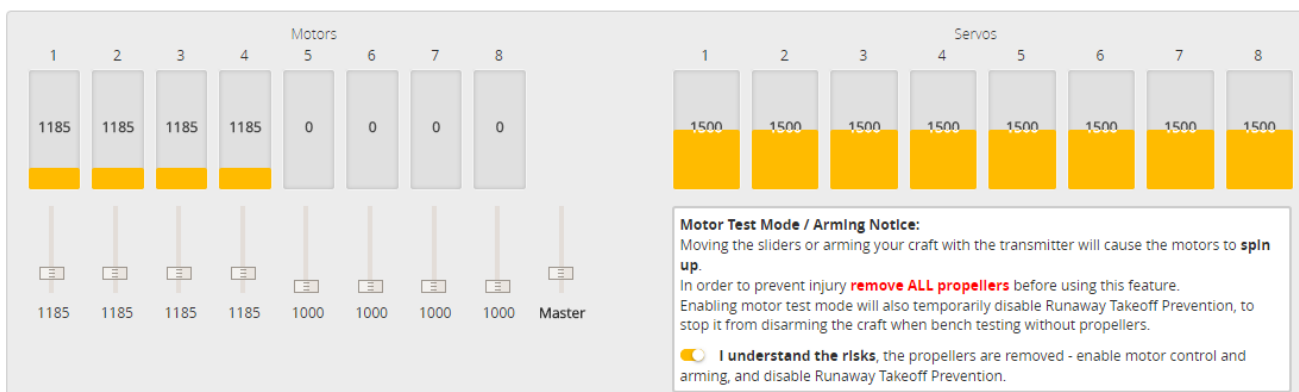
2. URAT2 uses Receiver (SBUS/iBUS/DSM/CRSF/R9MM)

# 6. Select aircraft model

1. Click  Configuration Select model



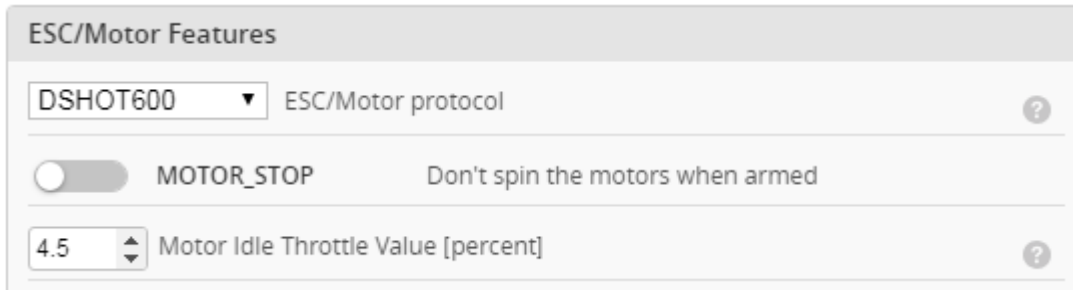
2. Click  Motors Click “**I understand the risks**” Push Master to check motor steering “**Master**” Steering can be changed at [BLHeliSuite](#)





# 7. Choose ESC protocol

1. Choose the right ESC protocol, the optional universal protocol DSHOT600.



ESC/Motor Features

DSHOT600 ESC/Motor protocol

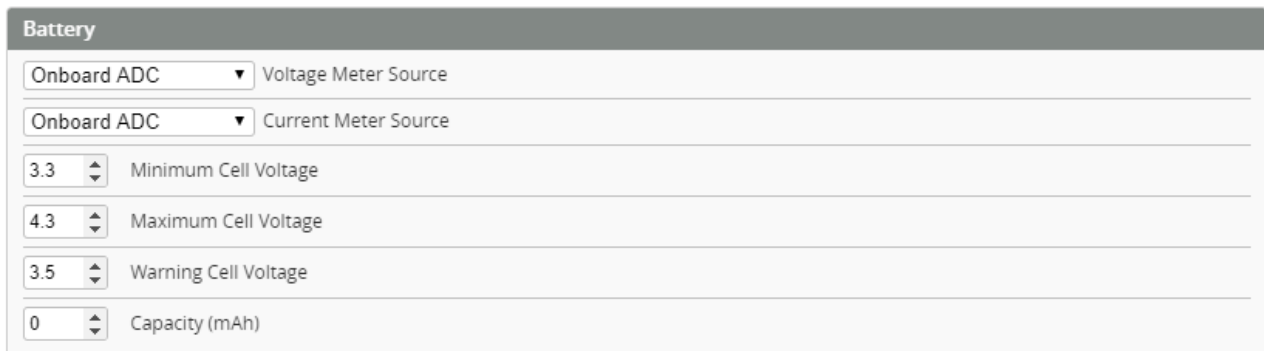
MOTOR\_STOP Don't spin the motors when armed

4.5 Motor Idle Throttle Value [percent]

# 8. Voltage and current parameters setting

1. Click **Power & Battery** Setting parameters

Power & Battery



Battery

Onboard ADC Voltage Meter Source

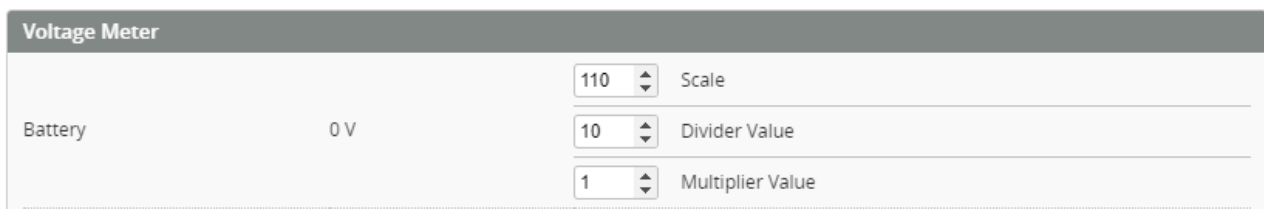
Onboard ADC Current Meter Source

3.3 Minimum Cell Voltage

4.3 Maximum Cell Voltage

3.5 Warning Cell Voltage

0 Capacity (mAh)



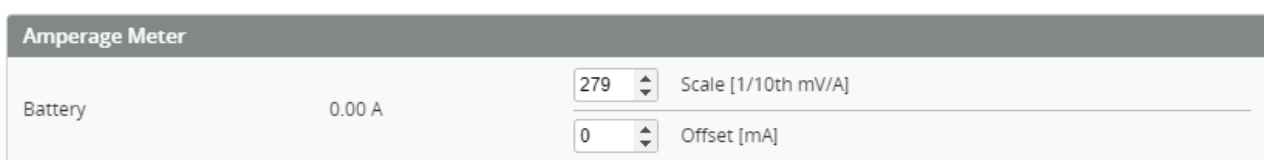
Voltage Meter

Battery 0 V

110 Scale

10 Divider Value

1 Multiplier Value



Amperage Meter

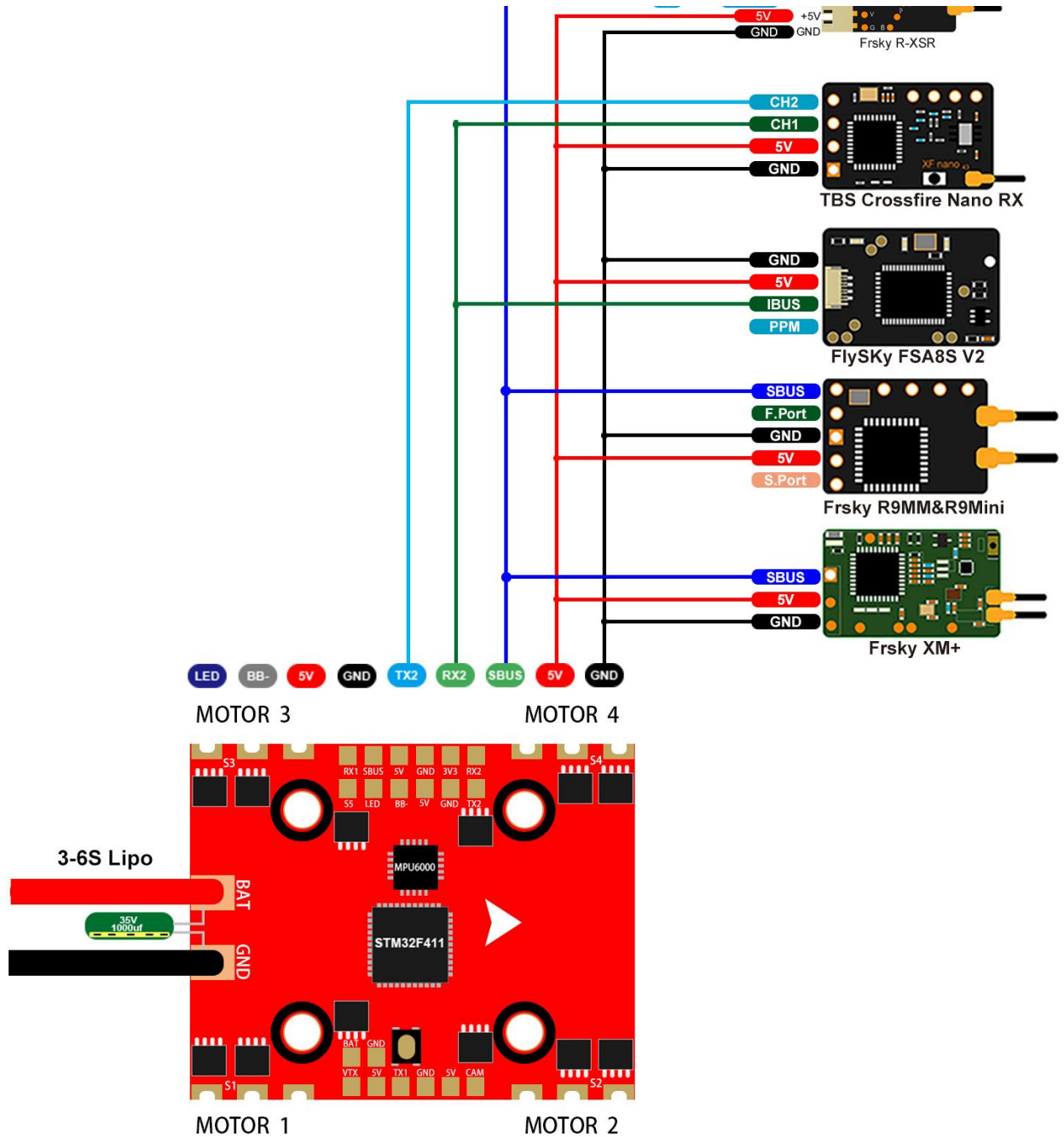
Battery 0.00 A

279 Scale [1/10th mV/A]

0 Offset [mA]

# 9. Setting up the receiver

## 1. Receiver connection diagram



2. Click have found “UART2” Open the receiver serial port

Identifier	Configuration/MSP	Serial Rx	Telemetry Output	Sensor Input	Peripherals
USB VCP	<input type="checkbox"/> 115200	<input type="checkbox"/>	Disabled   AUTO	Disabled   AUTO	Disabled   AUTO
UART1	<input type="checkbox"/> 115200	<input type="checkbox"/>	Disabled   AUTO	Disabled   AUTO	VTX (IRC Tran   AUTO
UART2	<input type="checkbox"/> 115200	<input checked="" type="checkbox"/>	Disabled   AUTO	Disabled   AUTO	Disabled   AUTO

### 3. Set the SBUS receiver

Receiver

Serial-based receiver (SPEKSAT, 5 ▼) Receiver Mode

**Note:** Remember to configure a Serial Port (via Ports tab) and choose a Serial Receiver Provider when using RX\_SERIAL feature.

SBUS ▼ Serial Receiver Provider

### 4. Set the DSMX receiver

Receiver

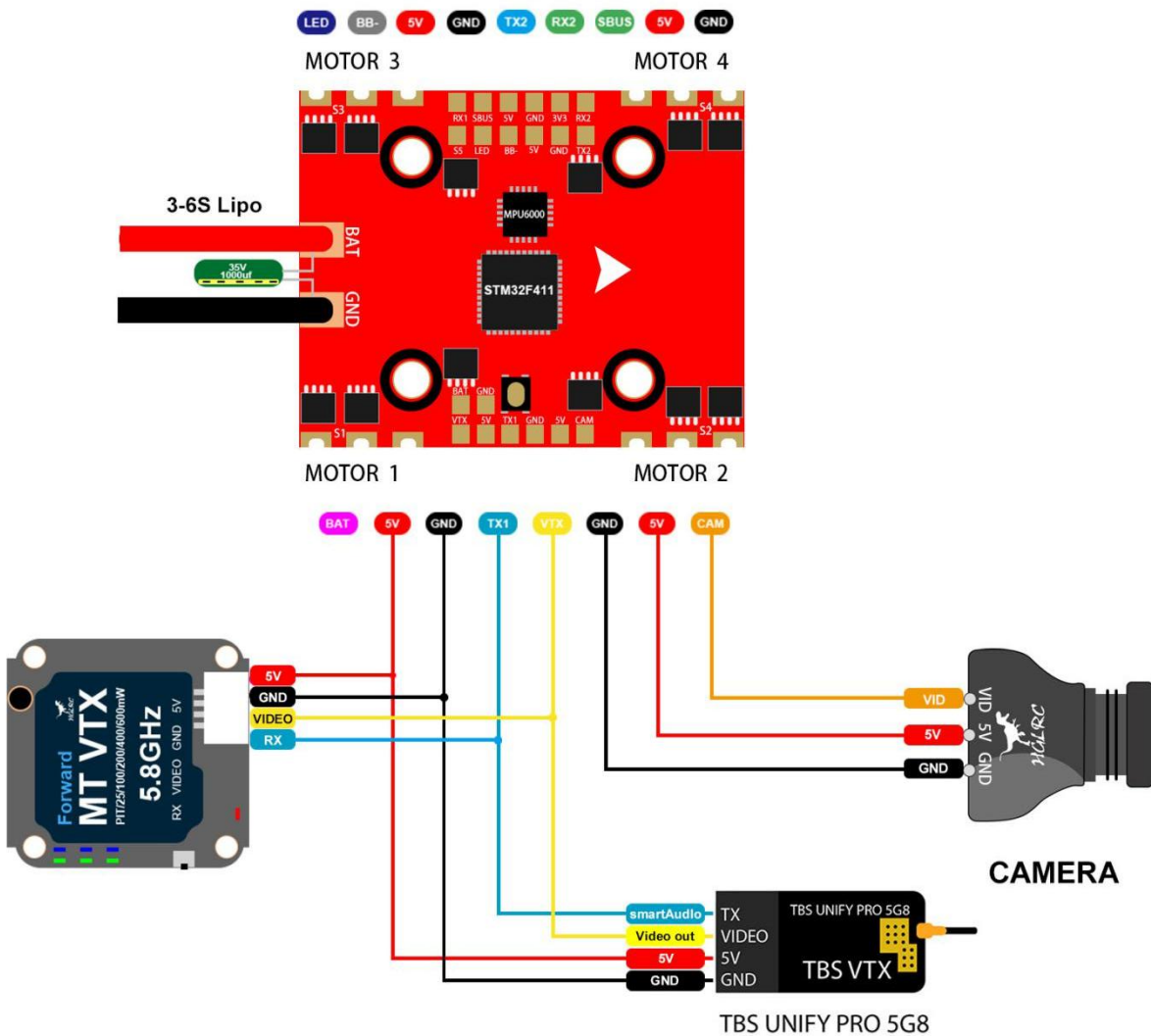
Serial-based receiver (SPEKSAT, 5 ▼) Receiver Mode

**Note:** Remember to configure a Serial Port (via Ports tab) and choose a Serial Receiver Provider when using RX\_SERIAL feature.

SPEKTRUM2048 ▼ Serial Receiver Provider

# 10. VTX serial port use. VTX uses OSD smart audio

## 1. VTX connection diagram



2.VTX serial port opens. The protocol is selected according to its own VTX protocol.

Identifier	Configuration/MSP	Serial Rx	Telemetry Output	Sensor Input	Peripherals
USB VCP	<input checked="" type="checkbox"/> 115200	<input type="checkbox"/>	Disabled   AUTO	Disabled   AUTO	Disabled   AUTO
UART1	<input type="checkbox"/> 115200	<input type="checkbox"/>	Disabled   AUTO	Disabled   AUTO	<div style="border: 1px solid red; padding: 2px;">           VTX (IRC Tran)   AUTO            Disabled            Blackbox logging            VTX (TBS SmartAudio)            VTX (IRC Tramp)            Camera (RunCam Protocol)            Benewake LIDAR         </div>
UART2	<input type="checkbox"/> 115200	<input checked="" type="checkbox"/>	Disabled   AUTO	Disabled   AUTO	

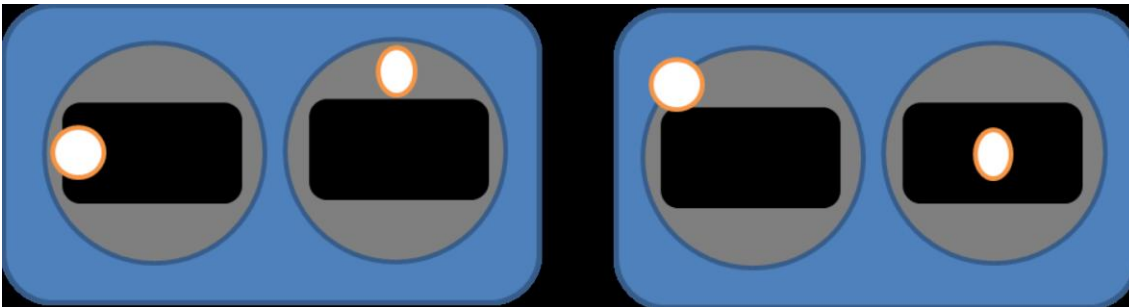
3.Use OSD to adjust VTX



which displays information like battery voltage and mAh consumed while you fly. In addition, the Betaflight OSD can be used to configure the quadcopter, making in-field adjustments and tuning more convenient.

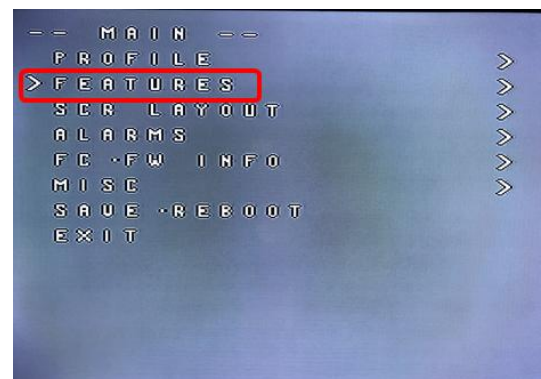
MODE2

MODE1



The graphics above show the stick command to bring up the OSD menu. The stick command is: throttle centered, yaw left, pitch forward. The exact stick command therefore depends on which mode your transmitter sticks are in.

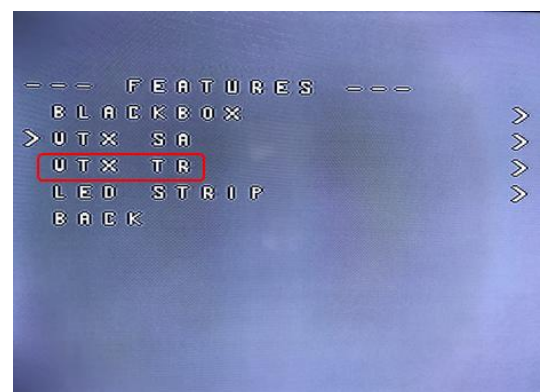
In the OSD menu, use pitch up/down to move the cursor between menu items. When a menu option has a > symbol to the right of it, this indicates that it contains a sub-menu. Roll-right will enter the sub-menu. For example, in the screen to the right, moving the cursor to “Features” and then moving the roll stick to the right will enter the “Features” sub-menu.



If you are using a video transmitter that supports remote configuration, enter the “Features” menu to configure the vTX. From there, enter either “VTX SA” if you are using SmartAudio (TBS Unify) or “VTX TR” if you are using IRC Tramp Telemetry.

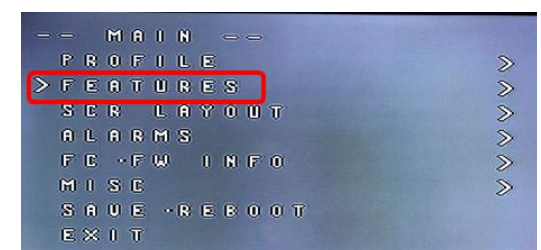
To adjust PIDs, rates, and other tuning-related parameters, enter the “Profile” sub-menu.

In the “Scr Layout” sub-menu, you can move the OSD elements (like battery voltage, mAh, and so forth) around on the screen.



The “Alarms” sub-menu lets you control when the OSD will try to alert you that battery voltage is too low or mAh consumed is too high.

When a parameter can be modified, the parameter’s current

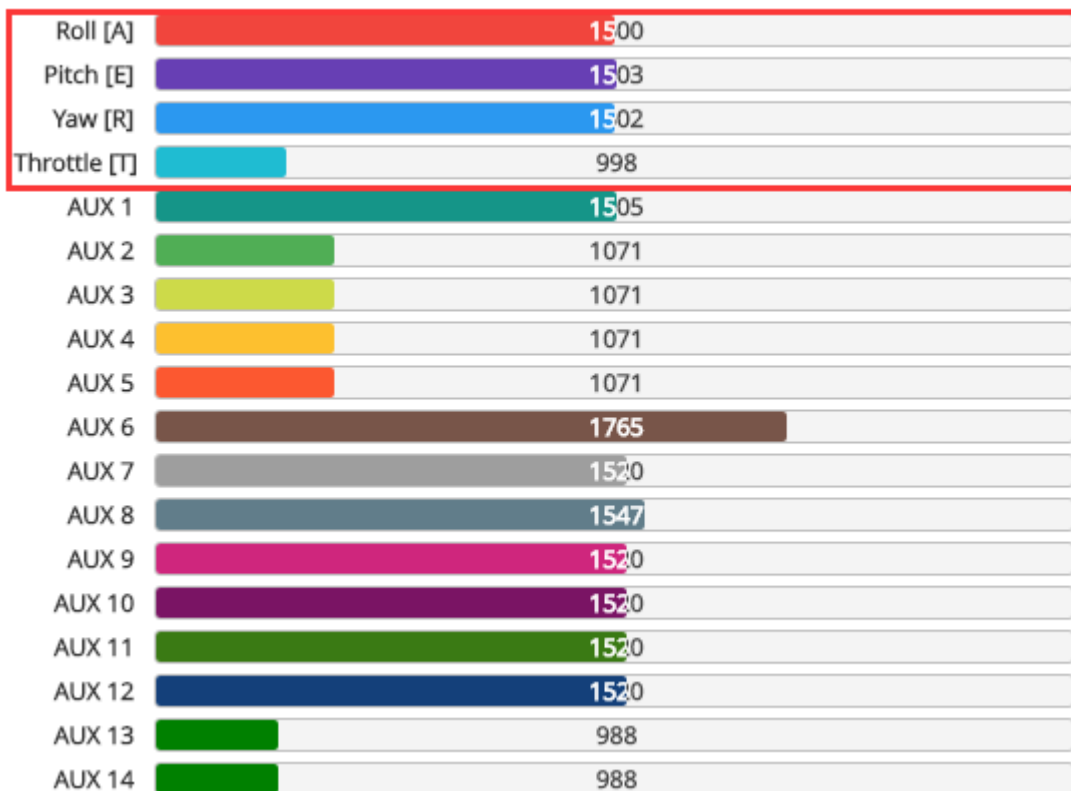


value will be shown on the right-hand side of the screen. In this case, roll left/right will adjust the parameter up and down.

The screen to the right shows the current vTX settings. From here, you can change the frequency band, channel, and power level of the video transmitter. After making the changes, move the cursor to “Set” and press roll-right to confirm the settings.


## 11. Check receiver signal

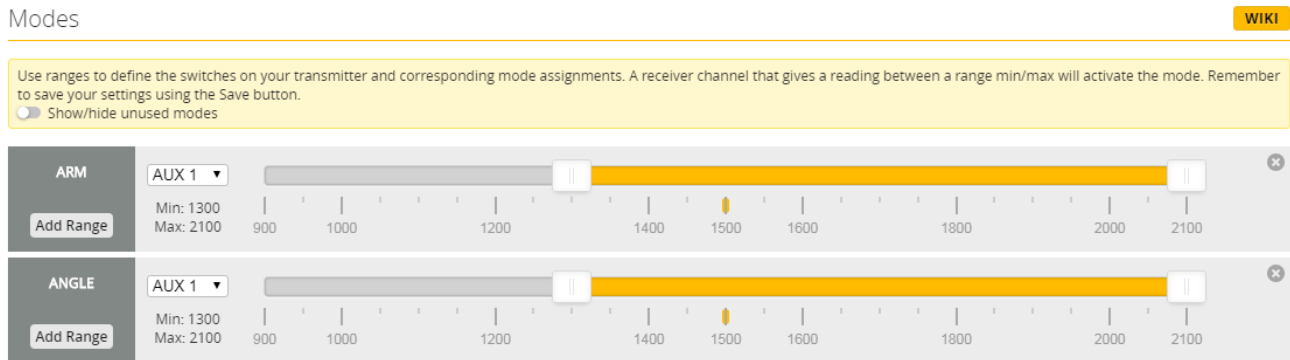
1. Click  Receiver Check the remote control output signal




## 12. Select flight mode startup

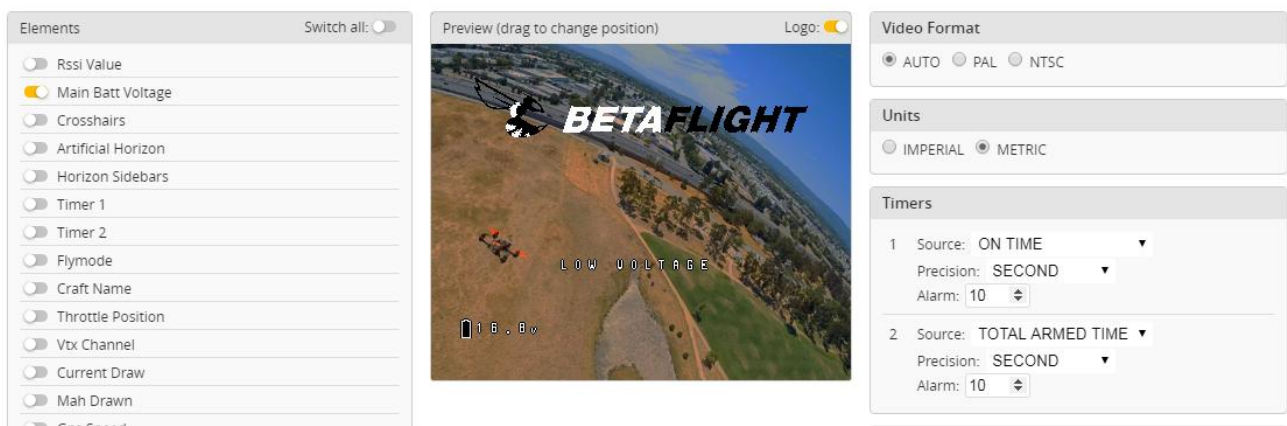
# mode

1. Click  Modes set up the function of remote control switch across the channel (below are for reference only)



# 13.OSD settings

1. Click  OSD the OSD Settings, according to the need to choose, drag the OSD schematic diagram of the parameters can be adjusted.

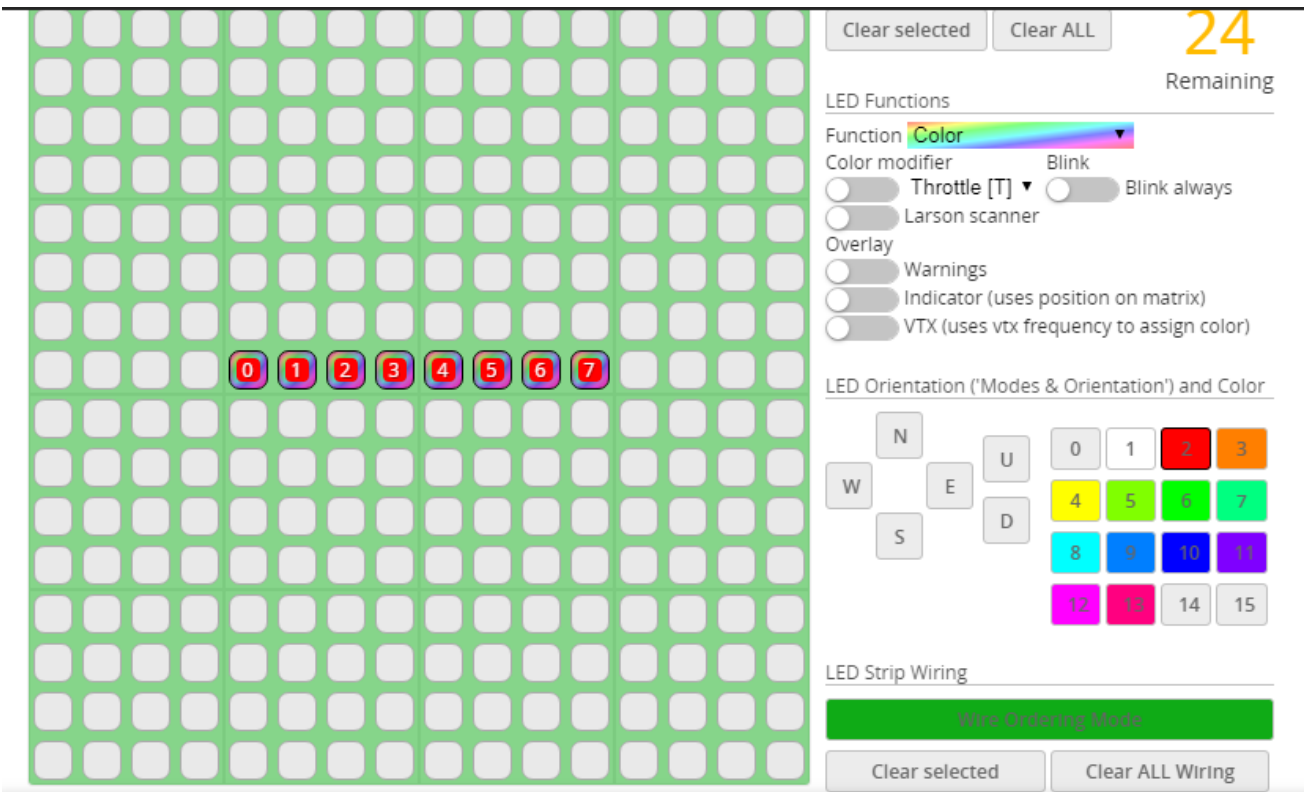


# 14.LED settings

1. Click **Configuration** Turn on LED support



2. Click **LED Strip**. Click **Wire Ordering Mode** set according to need



Clear selected Clear ALL **24** Remaining

LED Functions  
Function **Color**  
Color modifier  Blink  
 Throttle [T]  Blink always  
 Larson scanner

Overlay  
 Warnings  
 Indicator (uses position on matrix)  
 VTX (uses vtx frequency to assign color)

LED Orientation ('Modes & Orientation') and Color

	N						
		U	0	1	2	3	
W		E	4	5	6	7	
		D	8	9	10	11	
			12	13	14	15	

LED Strip Wiring  
**Wire Ordering Mode**  
Clear selected Clear ALL Wiring

# 15. Troubleshooting



## **Warning:**

Please read the cautions as follows, otherwise stability of your flight controller cannot be ensured, your flight controller will even get damaged.

- Keep focus on the polarity. Check carefully before power supply.
- Cut off the power when you connect, plug and pull anything.
- The refresh rate of PID and Gyroscope is up to 32K/16K.

## **after sales question:**

1. After receiving the goods, it is found that the product can not be used normally. If the return to the factory is a quality problem, the repair service will be provided free of charge.
2. If the product is damaged due to improper operation, the repair service may be provided under the condition that the inspection can be repaired.
3. For domestic customers, please contact the after-sales service personnel. For overseas customers, please contact the official website for after-sales service.

## **Product daily problems**

1.OSD garbled:



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If you find garbled characters, please open Betaflight, click “OSD” .and click “Font Manager” clicks on “Upload Font” to update

1. When plugged in the battery, the aircraft does not pass the self-test

without "BBB" sound. There is only one sound.

Please check if the ESC agreement is correct

3.The spin of the aircraft keeps spinning

1. Please check if the propeller is correct

2. Please check if the motor direction is correct