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EP66

FREQUENCY INVERTER

0.4kW - 90kW / 0.5HP - 120HP



EP66 0.4 kW - 90 kW / 0.5HP - 120HP FREQUENCY INVERTER

HIGHLIGHTS

DSP based high-tech motor control concept, suitable for V/Hz, SENSORLESS VECTOR, PMM synchronous motor control,SPEED/TORQUE control mode

Intelligent AUTOTUNING functions for quick and easy set-up

Rugged construction, IP66/NEMA 4X

Flexible configurable 4 line character display – ready for any common field bus

Removable cable conduit plate, including vent with humidity barrier

Space inside the drive for customer options like, main/emergency switch, start/stop selectors, potentiometer and brake resistor

Optional BYPASS switch built in

C3 class filter standard – optional C1 EMC filter build in for 1. Environment (residential area)

All standard inverter functions built in, to make it suitable for various industrial, civil, and retrofit applications

Smart PC-tools, for inverter control, parametrization and troubles hooting. parameter-duplication stick Ready for the worldwide market, due to approved international standards







SO 9001

Naming rule

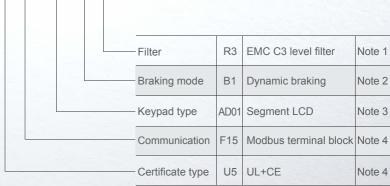
Model naming rule

EP66 - 0007 T3 I1

			Mark	Structure Code					
		_	I1∼I6 Frame Size						
			Mark	Inp	out Po	wer T	уре		
			S2	S2 1-phase 220~240VAC					
			T2	3-phase 220~240VAC					
			Т3	3-phase 380~480VAC					
			Motor power						
			Mark		0007	0015	0022		
			Motor po	wer(kW)	0.75	1.5	2.2		
			Product series: EP66						

Function naming rule

U5 F15 AD01 B1 R3



Note 1: R3: EMC C3 level, test condition: power cable is 25m shielded wire.

Note 2: Dynamic braking: The inverter model for S2 and T2 is optional; The inverter model for T3:

Standard (≤15kW); Optional (≥18.5kW)

Note 3: EP66 supports 4 kinds of keypad type, user can select as needed;

Keypad code	Keypad definition
AD01	AD English 1-line LCD keypad without potentiometer
AD02	AD English 4-line LCD keypad without potentiometer

Note 4: certification and communication type

Structure code	Certificate	Certificate code	Communication	Communication code
I1∼I3	U5	CE+UL	F2	Modbus
11, 513	U1	CE	F15	CAN communication (free protocol) +Modbus
I4~I6	U1	CE	F15	CAN communication (free protocol) +Modbus

Technical Specifications

	Items	Contents					
Input	Rated Voltage Range	T3 380V-480V +10%/-15%; S2/T2 220V-240V ±15%					
mpat	Rated Frequency	50/60Hz					
Output	Rated Voltage Range	3-phase 0-Input					
Output	Frequency Range	0.50~650.0Hz					
	Carrier Frequency	800~16000Hz; Fixed carrier-wave and random carrier-wave can be selected by F159					
	Input Frequency Resolution	Digital setting: 0.01Hz; Analog setting: Max frequency 0.1%					
	Control Mode	Sensorless Vector Control (open-loop vector control) V/F control, PMSM sensorless vector control					
	Start Torque	0.5 Hz / 150% (SVC), 5% of rated speed / 100% of rated torque (PMSM)					
	Speed-control Scope	1:100 (SVC), 1:20 (PMSM)					
	Steady Speed Precision	±0.5% (SVC)					
	Torque Control Precision	±5% (SVC)					
	Overload Capacity	150% rated current, 60 seconds.					
Control Mode	Torque Elevating	Auto torque promotion, manual torque promotion includes 1-20 curves.					
	V/F Curve	3 kinds of modes: beeline type, square type and under-defined V/F curve.					
	Startup mode	Direct startup, speed track startup (V/F control)					
	DC Braking	DC braking frequency: 0.2~50.00 Hz, braking time: 0.00~30.00s					
	Jogging Control	Jogging frequency range: Min frequency~ Max frequency, Jogging acceleration/deceleration time: 0.1~30.00s					
	Auto Circulating Running and multi-stage speed running	Auto circulating running or terminals control can realize 15-stage speed running.					
	Built-in PID adjusting	Easy to realize a system for process closed-loop control					
	Auto voltage regulation (AVR)	When the source voltage changes, the modulation rate will be adjusted automatically, resulting in an unchanged output voltage					
	Frequency Setting	Potentiometer or external analog signal (0~5V, 0~10V, 0~20mA); keypad (terminal / ▼ keys, external control logic and automatic circulation setting.					
	Start/Stop Control	Terminal control, keypad control or communication control.					
Operation	Running Command Channels	3 kinds of channels from keypad panel, control terminal and MODBUS.					
Function	Frequency Source	Frequency sources: given digit, given analog voltage, given analog current and given MODBUS					
	Accessorial frequency Source	6 kinds of accessorial frequency					
Optional	Built-in EMI filter, built-in brakin	g unit, Modbus, tele-control panel					
Protection Function		e loss, input under-voltage, DC over-voltage, over-current, inverter over-load, motor over- ternal disturbance, under-load, pressure control, analog line disconnected, oPEn fault,					
Display	1 1 32	(rpm/min), output current, output voltage, DC bus voltage, PID feedback value, PID pes of faults, and parameters for the system and operation; LED indicators showing the er.					
	3						
Environment Conditions	Equipment Location	In harsh conditions, prevent dust of other thing from entering inverter totally. Completely protected against jets of water and heavy waves. Meeting EN 60529 standard.					

	Items	Contents			
Environment	Vibration Strength	Below 0.5g (acceleration)			
Conditions	Height above sea level	1000m or below (derating use if higher than 1000m)			
Protection level	IP66/NEMA 4X				
Class of pollution	PD2				
Applicable Motor	0.4~90kW				

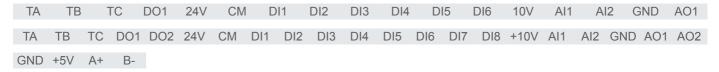
Functions of Control Terminals

Terminal	Туре	Description	Function				
DO1	Output	Multifunctional output terminal 1	When token function enabled, the value between this terminal and CM is 0V, 24V when disabled; The max output frequency is 100KHz when high-frequency output; DO1 is high frequency output and it is not recommended to use intermediate relay.	The functions of output terminals shall be defined per			
DO2	signal	Multifunctional output terminal2	When the token function is valid, the value between this terminal and CM is 0V; when disabled, the value is 24V.	manufacturer's value. Their initial state may be changed through			
TA TB TC		Relay contact	TC is a common point, TB-TC are normally closed contacts, TA-TC are normally open contacts. The contact capacity of 15Kw and below 15Kw inverter is 10A/125VAC, N0/NC 3A or 250VAC/30VDC.	changing function			
AO1 ^{note1}	Analog	Running frequency	It is connected with frequency meter, speedometer or ammeter expole is connected with GND. See F423 \sim F426 for details.	ternally, and its minus			
AO2 ^{note1}	output	Current display	It is connected with ammeter externally, and its minus pole is connected with GND. Se F427 \sim F430 for details.				
10V	Analog power supply	Self contained power supply	Internal 10V self-contained power supply. When used externally, it the power supply for voltage control signals with restricted current be				
Al1 ^{note2}	Input	Voltage analog input port	When analog speed control is adopted, the voltage signal is terminal. The range of voltage input is $0\sim10\text{V}$, grounding: GND speed control is adopted, this terminal is connected with center connected to GND.	When potentiometer			
Al2 ^{note2}	Input Signal		When analog speed control is adopted, the voltage or current sign terminal. The range of voltage input is 0~5V or 0~10V and the current input resistor is 500Ohm, and grounding: GND. If the input i realized through adjusting parameter F406. The voltage or current by coding switch. See table 4-2 for details, the current channe before delivery.	rent input is $0\sim20$ mA, s $4\sim20$ mA, it can be signal can be chosen			
24V	Power supply	Control power supply	Power: 24±1.5V, grounding is CM; current is restricted below 50mA	for external use.			
СМ	Common port	Grounding of control power supply	The grounding of 24V power supply and other control signals.				
DI1	Digital input control terminal	Jogging terminal	When this terminal is valid, the inverter will have jogging running. The jogging function of this terminal is valid under both at stopped and running status. This terminal can also be used as high-speed pulse input port. The max frequency is 50K.	The functions of			
DI2		External Emergency Stop	When this terminal is valid, "ESP" malfunction signal will be displayed. $\label{eq:malfunction} % \begin{center} \end{center} % \begin{center} center$	input terminals shall be defined			
DI3		"FWD" Terminal	When this terminal is valid, inverter will run forward.	per manufacturer's			
DI4		"REV" Terminal	When this terminal is valid, inverter will run reversely.	value. Other			
DI5		Reset terminal	Make this terminal valid under fault status to reset the inverter.	functions can also be			
DI6		Free-stop	Make this terminal valid during running can realize free stop.	defined by changing			
DI7 ^{note3}		Running terminal	When this terminal is in the valid state, inverter will run by the acceleration time. $ \\$				
DI8 ^{note3}		Stop terminal	Make this terminal valid during running can realize stop by the deceleration time. $ \\$				

Те	rminal	Туре	Description	Function
(GND	Analog grounding	Self-contained Power supply Ground	Ground terminal of external control signal (voltage control signal or current source control signal) is also the ground of 10V power supply of this inverter.
	+5V	Power	Self-contained power	Grounding for digital signal
	A+	485	Positive polarity of differential signal	Standard: TIA/EIA-485(RS-485) Communication protocol: Modbus
	B-	terminals	Negative polarity of Differential signal	Communication rate: 1200/2400/4800/9600/19200/38400/57600bps

Note:

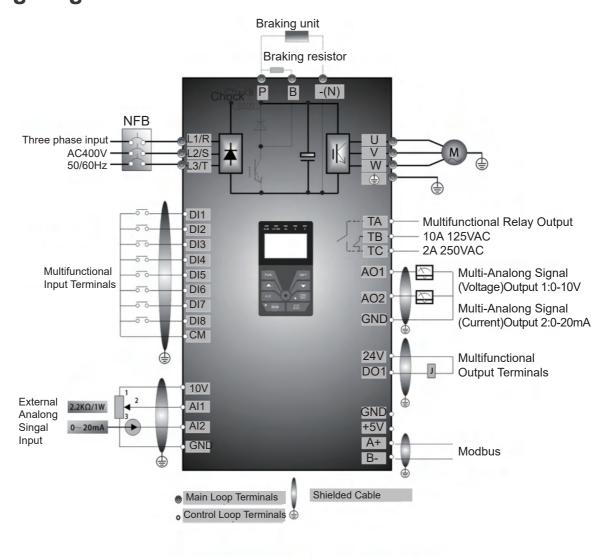
- 1.AO1 can output voltage and current signal, and AI2 can only output current.
- 2.Al1 can only accept voltage signal, Al2 can only accept voltage signal and current signal.
- 3.15 kW and below 15 kW inverters have no DO2, AO2, DI7 and DI8 terminals.



Product List

Model	Rated current R	emote Keypad	Structure code	Weight (kg)	Dmensions (W×H×D-mm)	Cooling mode	Remarks
EP66-0004S2	0.4kW-2.5A-0.3HP		I1	6.2	200×412×198	Self cooling	
EP66-0007S2	0.75kW-4.5A-1HP		I1	6.2	200×412×198	Self cooling	1-phase
EP66-0015S2	1.5kW-7A-2HP		I1	6.2	200×412×198	Self cooling	plastic hanging
EP66-0022S2	2.2kW-10A-3HP		I1	6.2	200×412×198	Air cooling	
EP66-0004T2	0.4kW-2.5A-0.5HP		I1	6.2	200×412×198	Self cooling	
EP66-0007T2	0.75kW-4.5A-1HP		I1	6.2	200×412×198	Self cooling	
EP66-0015T2	1.5kW-7A-2HP		I1	6.2	200×412×198	Self cooling	
EP66-0022T2	2.2kW-10A-3HP		I1	6.2	200×412×198	Air cooling	
EP66-0004T3	0.4kW-1.2A-0.5HP		I1	6.2	200×412×198	Self cooling	
EP66-0007T3	0.75kW-2A-1HP		I1	6.2	200×412×198	Self cooling	
EP66-0015T3	1.5kW-4A-2HP		I1	6.2	200×412×198	Self cooling	3-phase
EP66-0022T3	2.2kW-6.5A-3HP	AD-A-1	I1	6.2	200×412×198	Air cooling	plastic hanging
EP66-0030T3	3.0kW-7A-4HP	Or	I1	6.2	200×412×198	Air cooling	
EP66-0040T3	4.0kW-9A-5.5HP		I1	6.2	200×412×198	Air cooling	
EP66-0055T3	5.5kW-12A-7.5HP	AD-A-2	12	8.2	242×418×198	Air cooling	
EP66-0075T3	7.5kW-17A-10HP		12	8.2	242×418×198	Air cooling	
EP66-0110T3	11kW-23A-15HP		13	11.3	242×471×228	Air cooling	
EP66-0150T3	15kW-32A-20HP		13	11.3	242×471×228	Air cooling	
EP66-0185T3	18.5kW-38A-25HP		14	25	242×650×325	Air cooling	
EP66-0220T3	22kW-44A-30HP		14	25	242×650×325	Air cooling	
EP66-0300T3	30kW-60A-40HP		14	25	242×650×325	Air cooling	
EP66-0037T3	37kW-75A-50HP		15	40	308×680×379	Air cooling	3-phase
EP66-0450T3	45kW-90A-60HP		15	40	308×680×379	Air cooling	metal hanging
EP66-0550T3	55kW-110A-75HP		15	40	308×680×379	Air cooling	
EP66-0750T3	75kW-150A-100HF		16	57	370×770×404	Air cooling	
EP66-0900T3	90kW-180A-120HF		16	57	370×770×404	Air cooling	

Wiring diagram



Basic Wiring Diagram for Three-phase AC drives (NPN type

Note:

- 1. Connect power terminals L1 and L2 with power grid for single-phase inverters.
- 2. Remote-control panels are connected with 8 core telephone wire. 485 communication port is on the control terminals.
- 3. 485 communication port has built-in standard MODBUS communication protocol. The terminal sequence is GND, +5V, A+, B-.
- 4. Inverter(≤15kW) has 6 multifunctional input terminals DI1~DI6.
- 5. The contact capacity of inverter is 10A/125VAC, NO/NC: 3A 250VAC/30VDC.

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