

DM320 2H320 Stepper motor driver controller PULSE 12800 microstep motor brushless DC motor shell for 28 35 42 stepper drivers



Product features

1. Supply voltage : DC12-36V or AC12-24V
2. Drive current: 0.3-2.0A
3. Subdivision precision: 1-128 Subdivision options
4. opto-isolated signal input
5. Motor noise optimization function
6. Can drive any 2.0A below current 2-phase or 4-phase hybrid stepper motor
7. 200KHz chop frequency

Electrical characteristics

| | |
|-----------------------|--|
| Input current | 12V-36V DC power supply, Typical value: DC36V |
| Output current | 0.3A-2.0A, 8 gears adjustable |
| Drive mode | Double constant current PWM drive output |
| insulation resistance | Normal pressure and temperature >500M Ω |
| Insulation strength | Normal pressure and temperature 500V/min |
| Weight | About 140g |

Environmental requirements

| | |
|------------------|---|
| Cooling method | Natural cooling |
| Use occasion | Avoid dust, oil mist and corrosive gases |
| Use temperature | 0°C ~ +50°C |
| Ambient humidity | <80%RH, No condensation, no frost |
| Shake | Maximum not more than 5.7m/s ² |

Input signal interface function

| Symbol mark | Function | Detailed description |
|-------------|--|--|
| PVL | Step pulse signal | The falling edge is valid, and the motor takes a step each time the pulse is changed from high to low. $-5.5V \leq \text{Low level} \leq 0.3V, 3.6V \leq \text{High level} \leq 5.5V, \text{pulse width} > 2.5\mu S$ |
| DIR | Directional control signal | Change the direction of the motor. $-5.5V \leq \text{Low level} \leq 0.3V, 3.6V \leq \text{High level} \leq 5.5V, \text{pulse width} > 2.5\mu S$ |
| VCC | Input signal photoelectric isolation positive terminal | Connect +5V power supply, +5V~+24 can drive, higher than +5V need connect current-limiting resistance. 12V connect 1K, 24V connect 2K |
| EN | Motor release signal | When effective (low level), the motor coil current is switched off, the drive stops working, and the motor is in free state. |

Current output setting table

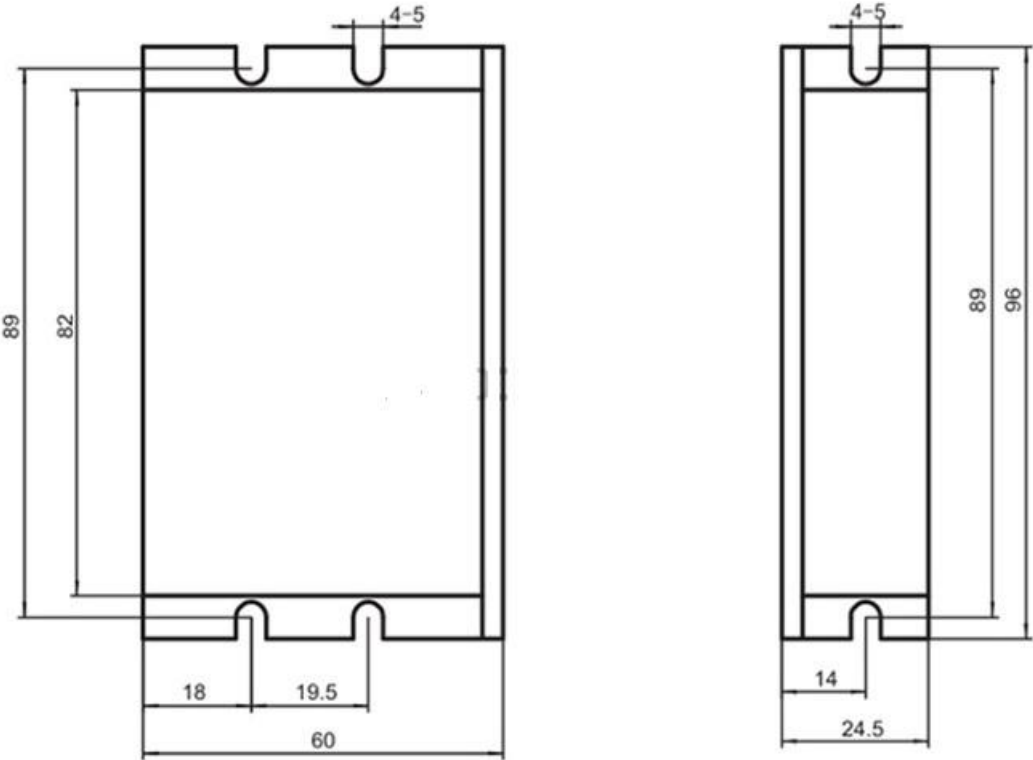
| Output peak current | Sw1 | Sw2 | Sw3 |
|---------------------|-----|-----|-----|
| 0.3A | on | on | on |
| 0.4A | off | on | on |
| 0.5A | on | off | on |
| 0.6A | off | off | on |
| 1.0A | on | on | off |
| 1.2A | off | on | off |
| 1.5A | on | off | off |
| 2.0A | off | off | off |

Subdivision schedule

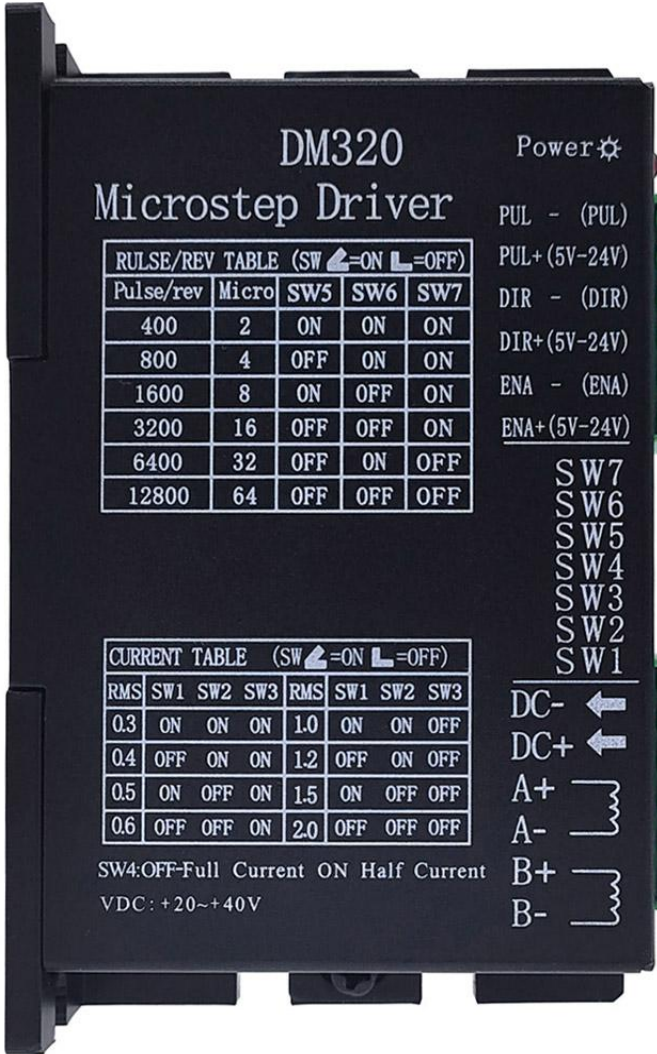
| Step number/Circle | Micro | Sw5 | Sw6 | Sw7 |
|--------------------|-------|-----|-----|-----|
| 200 | 1 | on | on | on |
| 400 | 2 | off | on | on |
| 800 | 4 | on | off | on |
| 1600 | 8 | off | off | on |
| 3200 | 16 | on | on | off |
| 6400 | 32 | off | on | off |
| 12800 | 64 | on | off | off |
| 25600 | 128 | off | off | off |

SW4: When set to ON, the standby current is set current, and when set to OFF, the standby current is half of the set current, and the heating is reduced.

Installation size



*Recommended for side mounting, better heat dissipation.



PUL - (PUL)
PUL+ (5V-24V)
DIR - (DIR)
DIR+ (5V-24V)
ENA - (ENA)
ENA+ (5V-24V)

SW7
SW6
SW5
SW4
SW3
SW2
SW1

DC- ←
DC+ ←
A+
A-
B+
B-



- Pulse-(without resistance)
- Pulse+(5-24V)
- Direction-(without resistance)
- Direction+(5-24V)
- Enable-(without resistance)
- Enabling+(5-24V)

- SW5,SW6,SW7
pulse subdivision Settings
- SW1,SW2,SW3
current subdivision Settings

- Input power supply (DC 20-40V)

- MotorA+,A-wiring

- MotorB+,B-wiring

