



CESSNA-152 Assembly Guide

Thanks for buying Hunter Cessna-152 training airplane, please read this guide carefully to understand correctly the assembly procedure before assembling, wish you have a fun fly!



Product Name: Cessna-152

Dimension: L420mm/H150mm/Wingspan600mm

Motor: Brushless 1104 / 4500KV

ESC: 12A

Battery: 220mah 7.4V Lipo (13~25g)

Servo: 4.3G x 2

Propeller: 75mm

Weight(PNP): 65g

Weight(take-off): 80g

Package size: 370mm x 210mm x 60mm/ ARF 500mm x 210mm x 70mm

Feature:

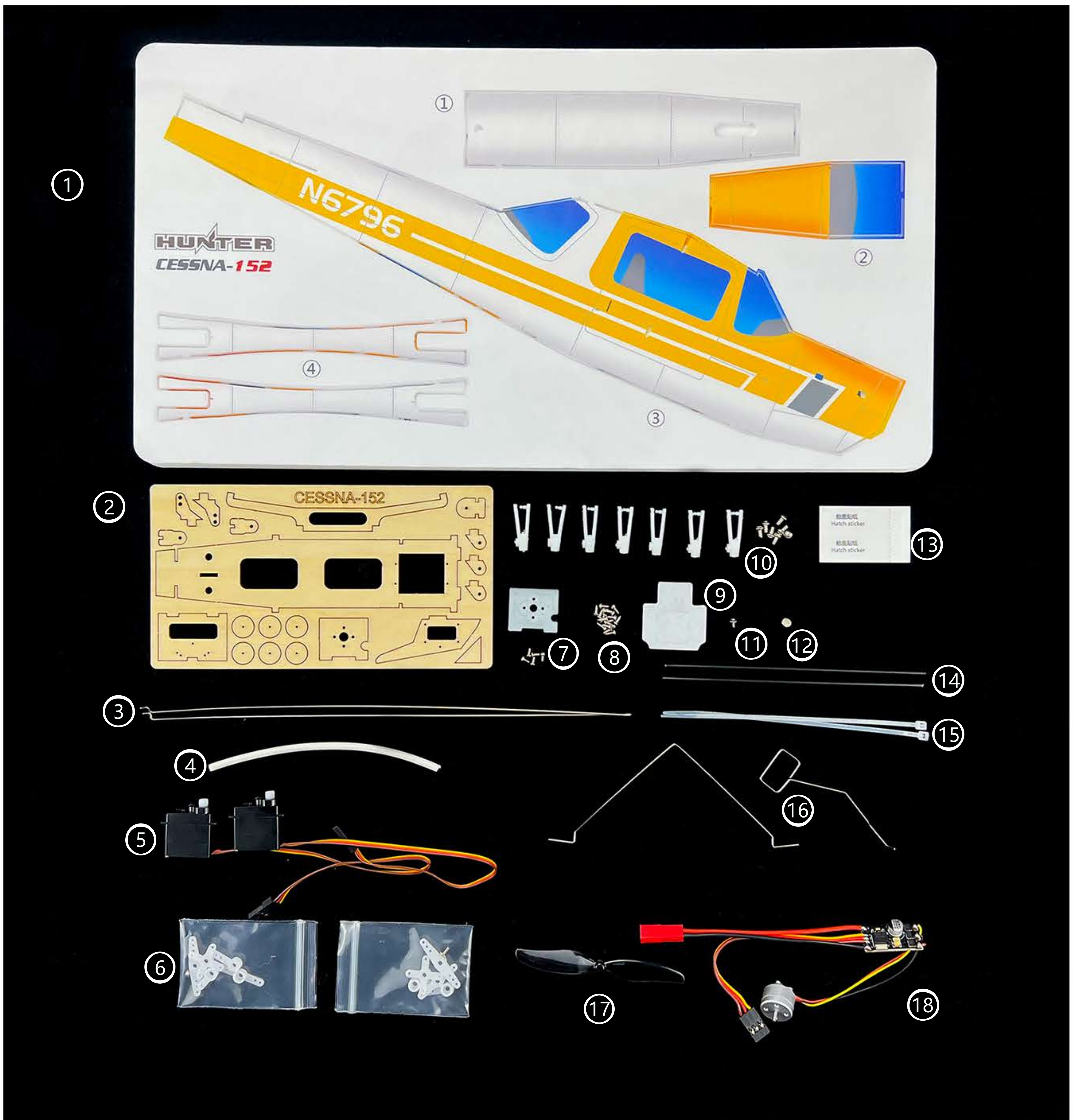
This products are producing by MPP magic board, UV print and laser cutting. With gorgeous workmanship and exquisite appearance, this incredible creative RC plane machine is made of lightweight and super durable material, tough and high strength, which is very suitable for the DIY of airplane model enthusiasts. Electronic combo comes with brushless motor and esc, providing powerful performance. We set ARF version which is coming with flight controller, self-stabilizer and manual flight mode can offer you an wonderful experience to fly!

Tools Required

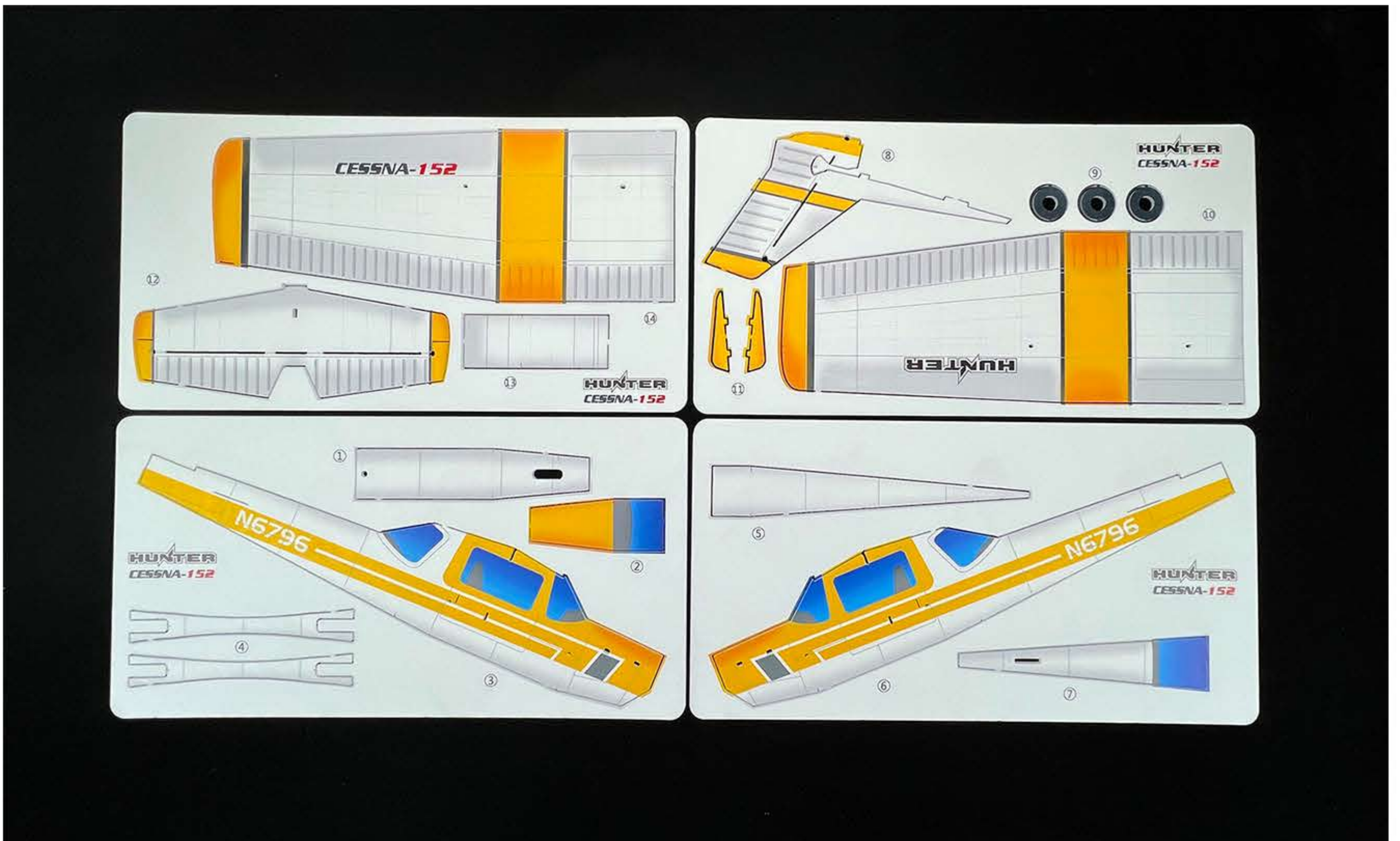
Sharp hobby Knife (Children under 12 years must be assisted by adult), clean towel or Non-woven Fabric(to wipe excessive glue), Phillips Screw driver, Foam glue and 502 glue

—、Assembly

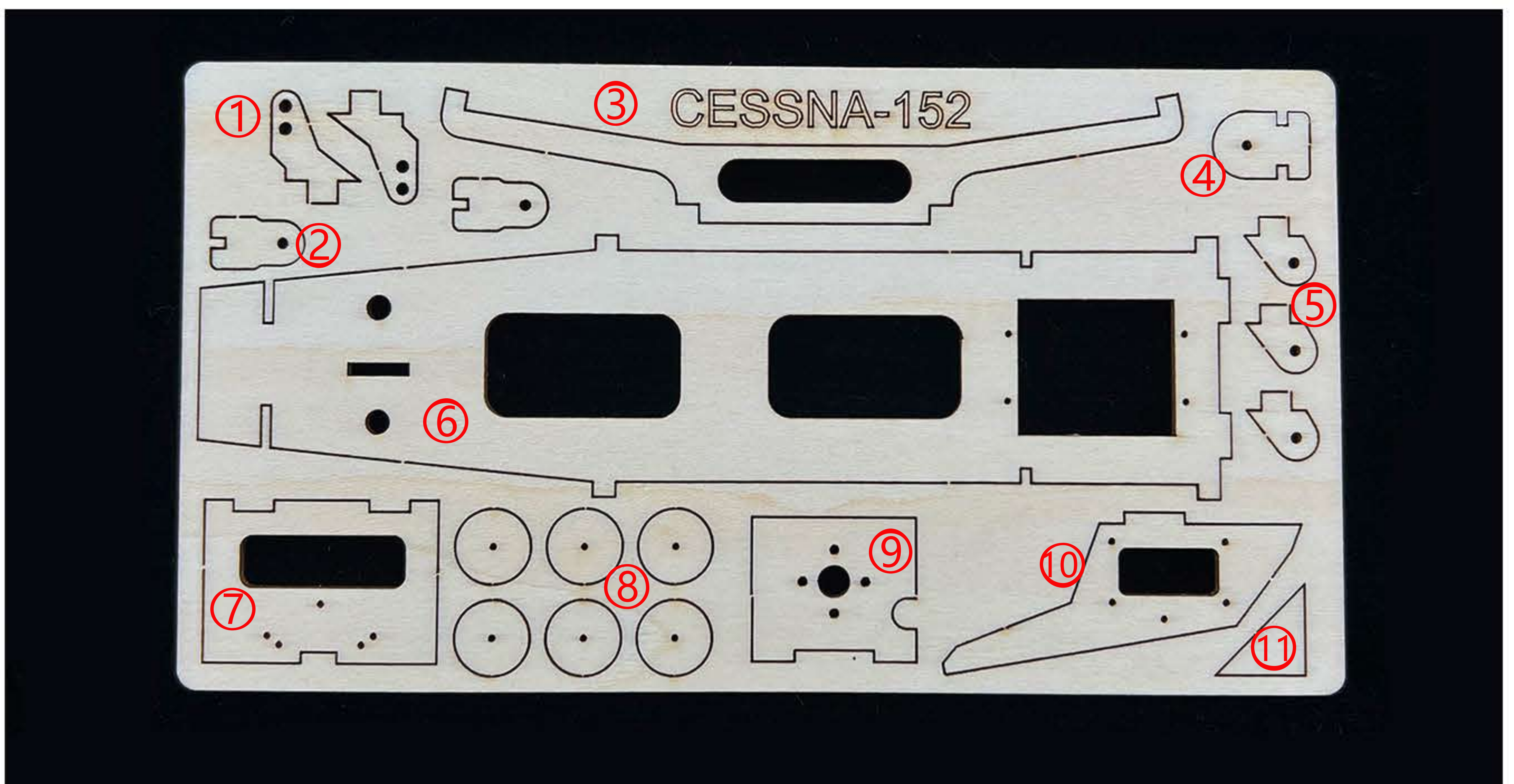
1.Packing list(As below shown) Accessories



1. PP board 2.Wooden board 3.Linkages 4.Heat shrink tube 5.Servos
 6.Servo arms 7.Motor mount+screws 8.screws 9.Double-side tape
 10. Nylon chuck+screws 11.Hatch screws 12.Magnet 13.Hatch decal
 14.Wing brace rod 15.Nylon ties 16.Landing gear 17. Propeller
 18.Motor + ESC



- 1.Hatch plate 2.Fuselage upper plate 3.Right frame 4.Wing brace plate
 5. Tail bottom plate 6.Left frame 7.Tail upper plate 8.Vertical tail 9.Landing wheels
 10.Right wing 11.Frame brace plates 12.Horizontal tail 13.Wings connecting plate
 14.Left wing



- 1.Servo horns 2.Wing brace rod mounting plate(fuselage side) 3.Wings mounting plate
 4.Hatch mounting plate 5.Wing brace rod mounting plate(wing side)
 6.Electronic fixing plate 7.Rear landing gear mounting plate 8.Wheels axle
 9.Motor mounting plate(optional:3D print part) 10.Front landing gear mounting plate
 11.Square ruler

ARF version including Radio and receiver



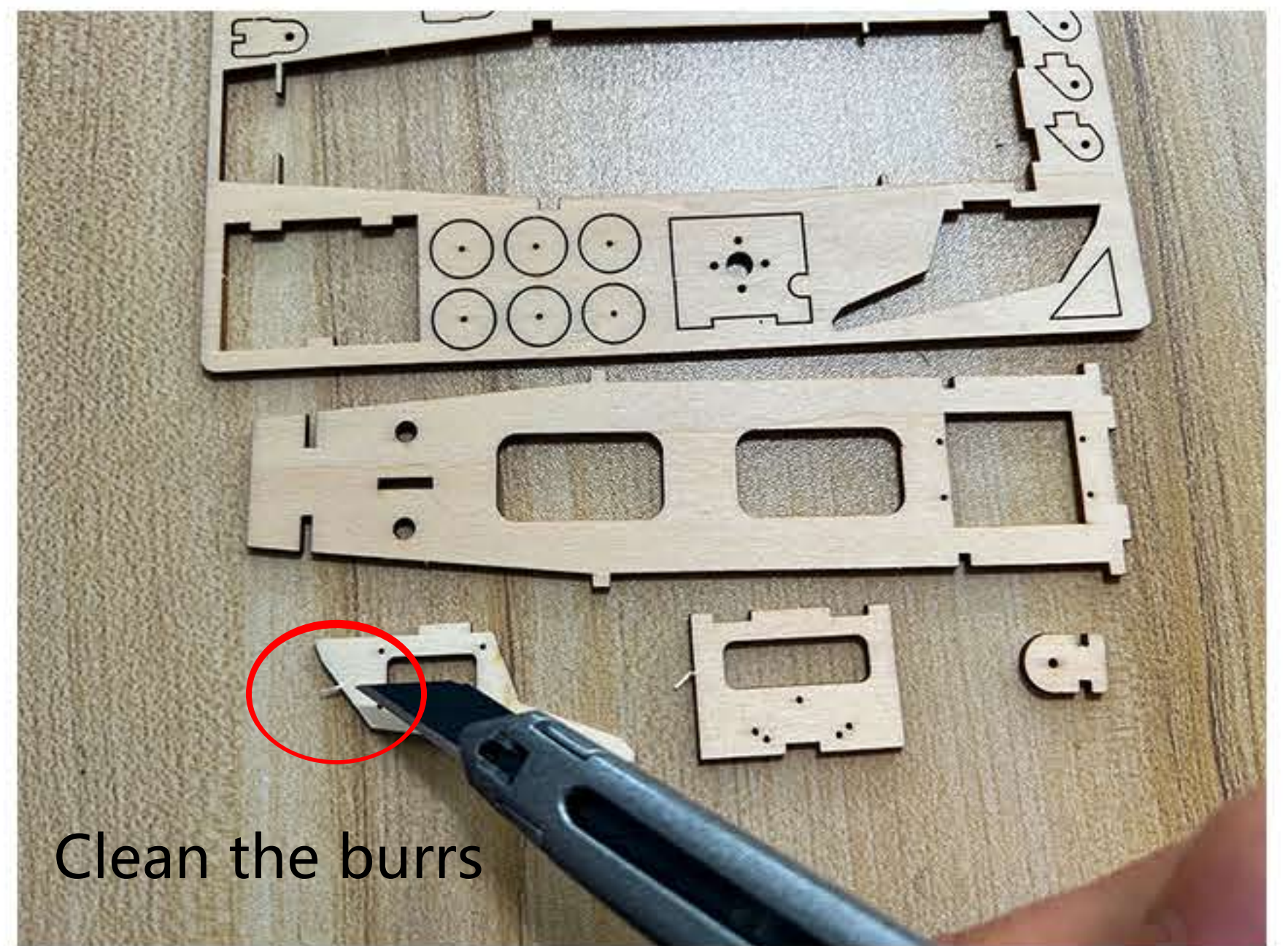
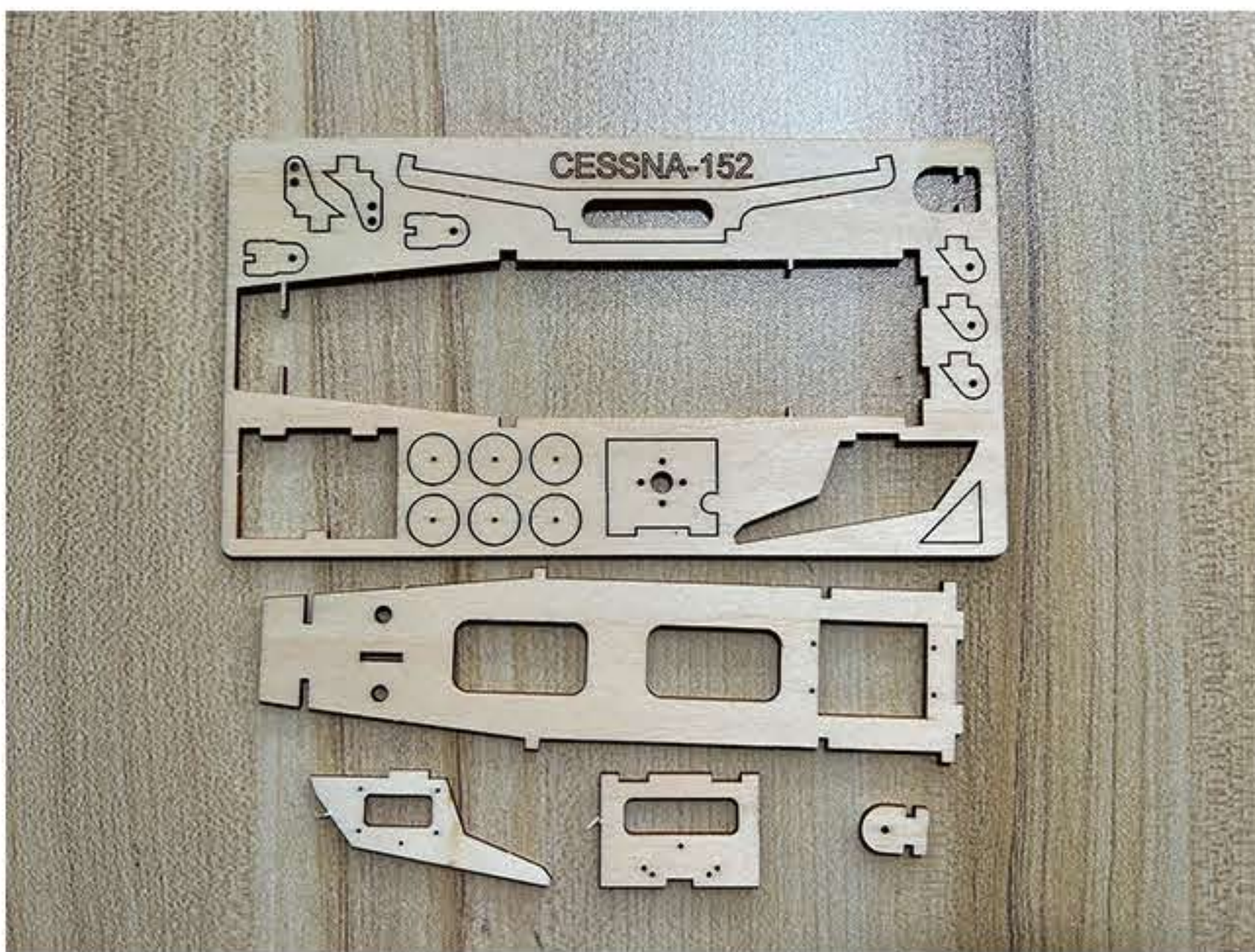
X6 radio



RX-1.0 receiver with FC

2. Fuselage inner electronics assembly

Take out the electronic fixing plate, front landing gear mounting plate, rear landing gear mounting plate and hatch mounting plate. Use the knife to fix all burrs to ensure clean and easy to bond.



Clean the burrs

Install the front landing gear

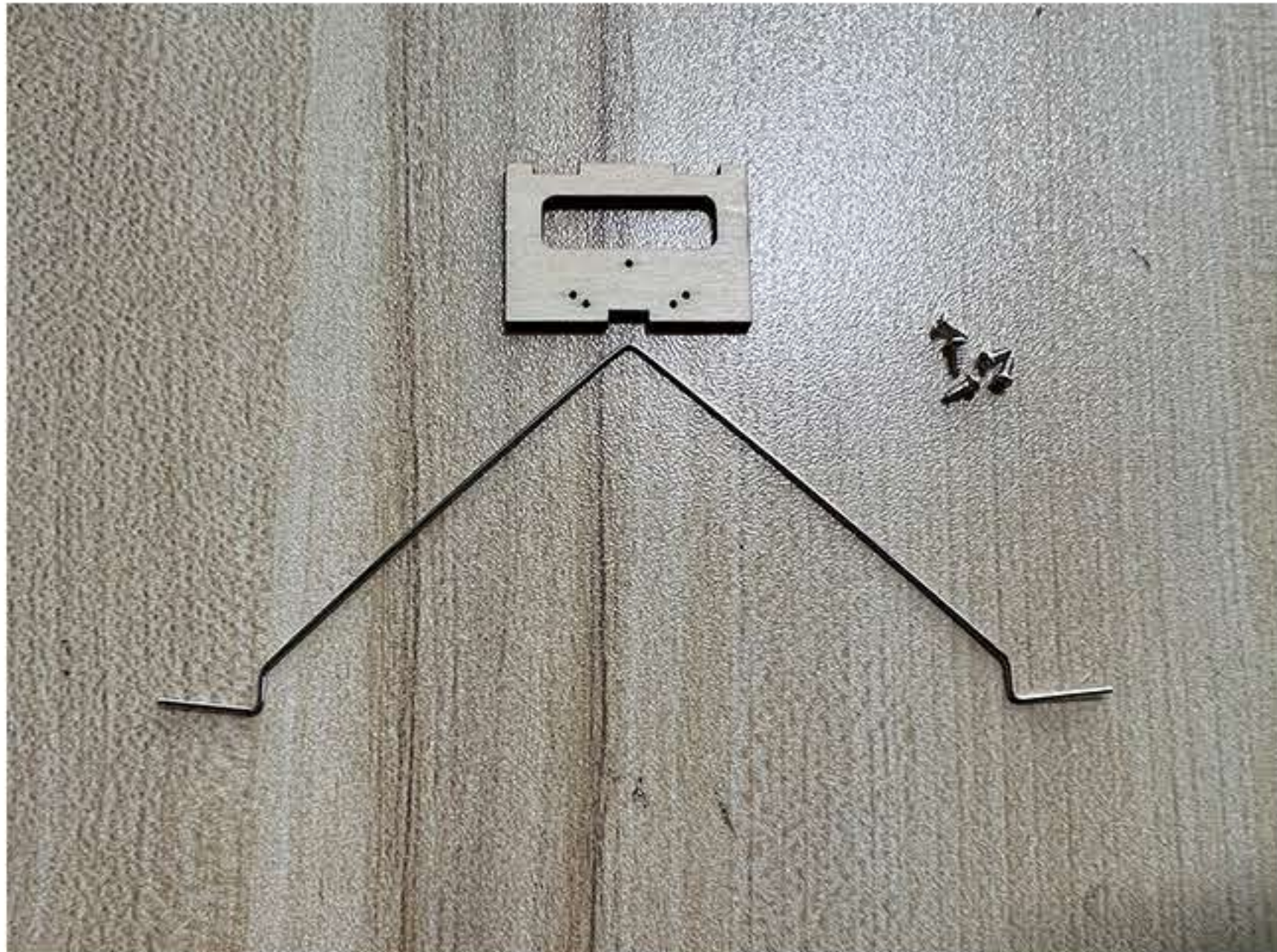


Use 1.5*4 screws



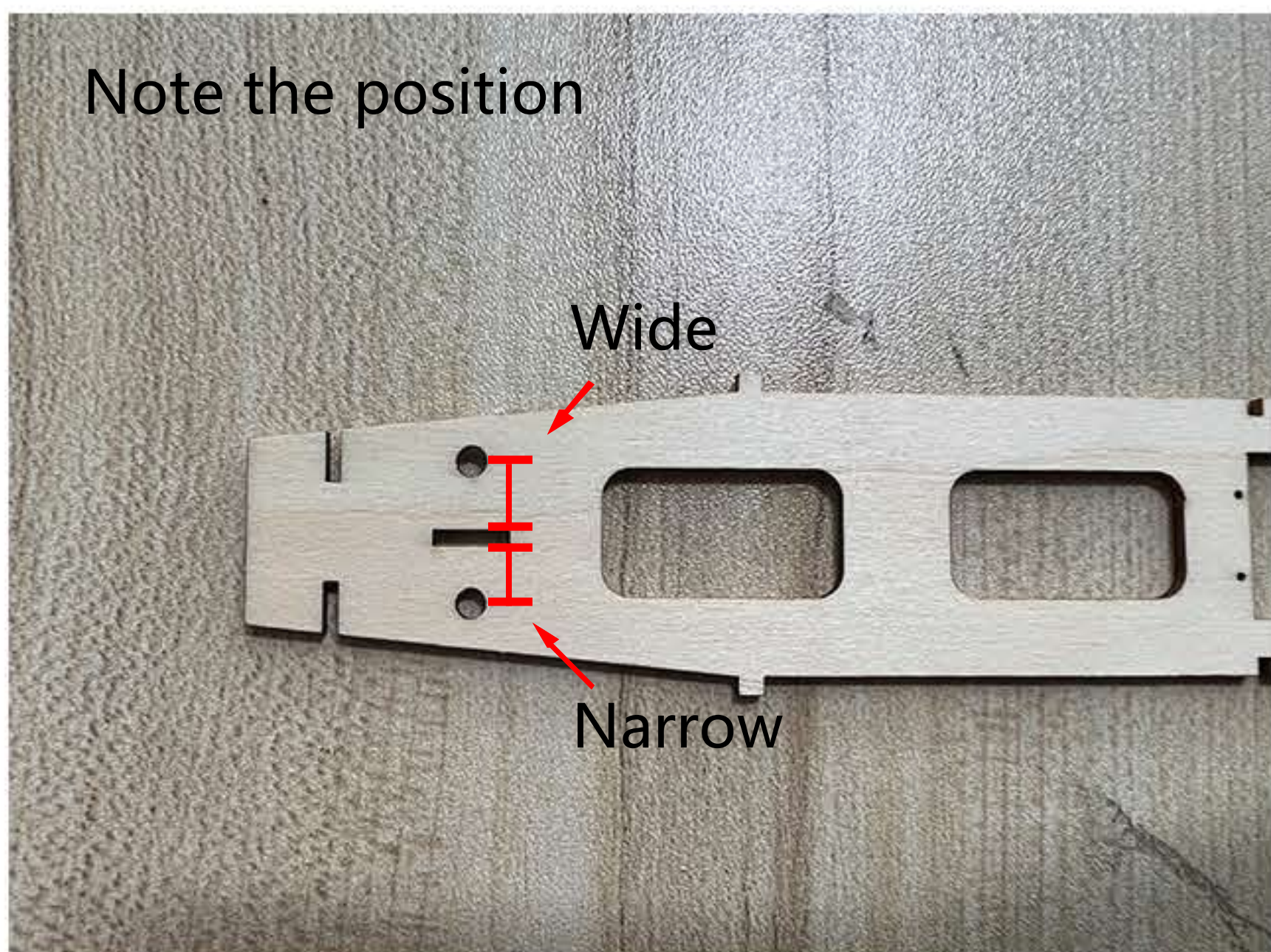
Note: tighten the screws just enough
yo hold the wires

Install the rear landing gear



As picture shown to tight the screws

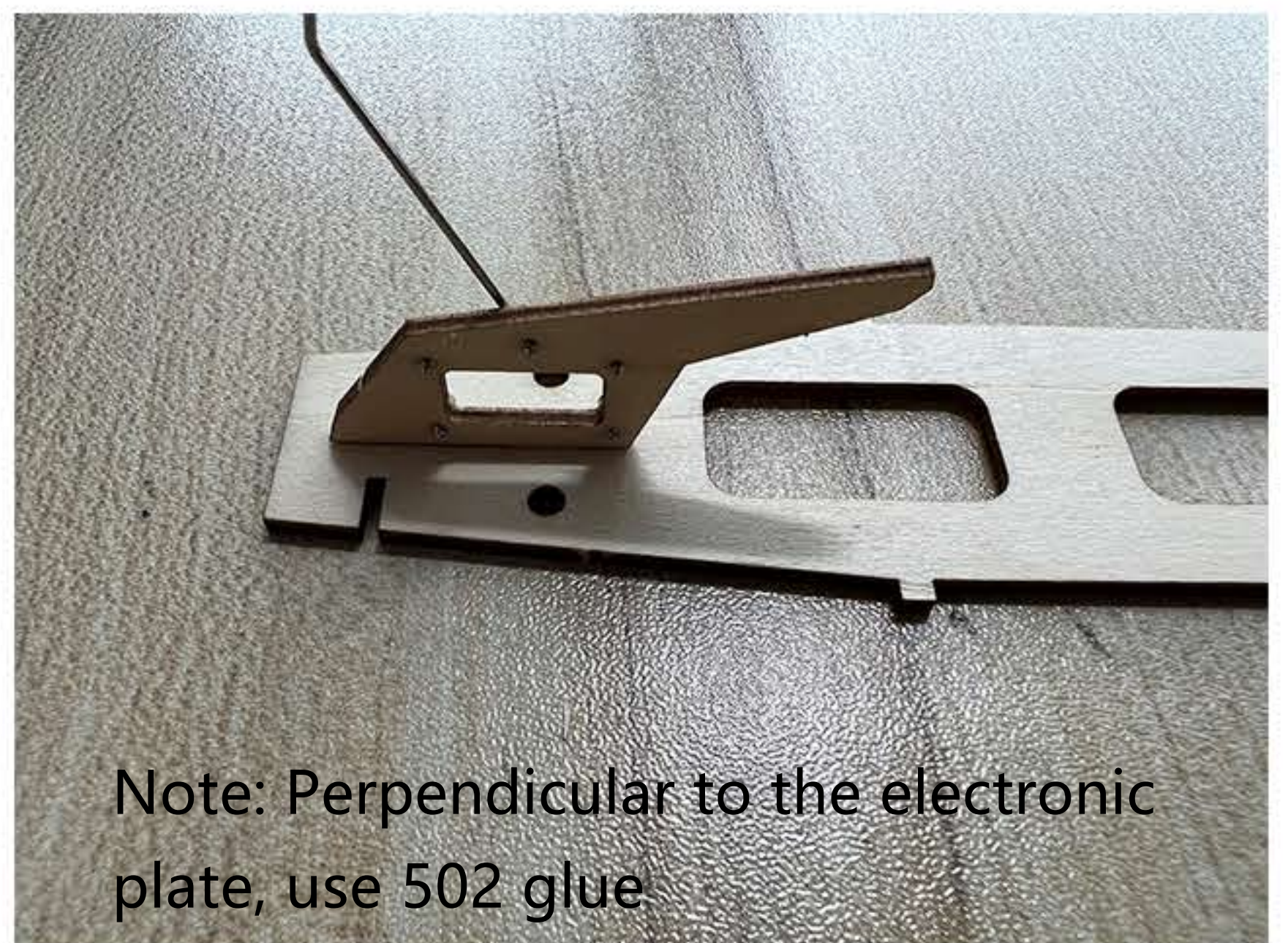
Use 502Gule to bond the front and rear landing gear mounting plate to the electronic fixing plate.



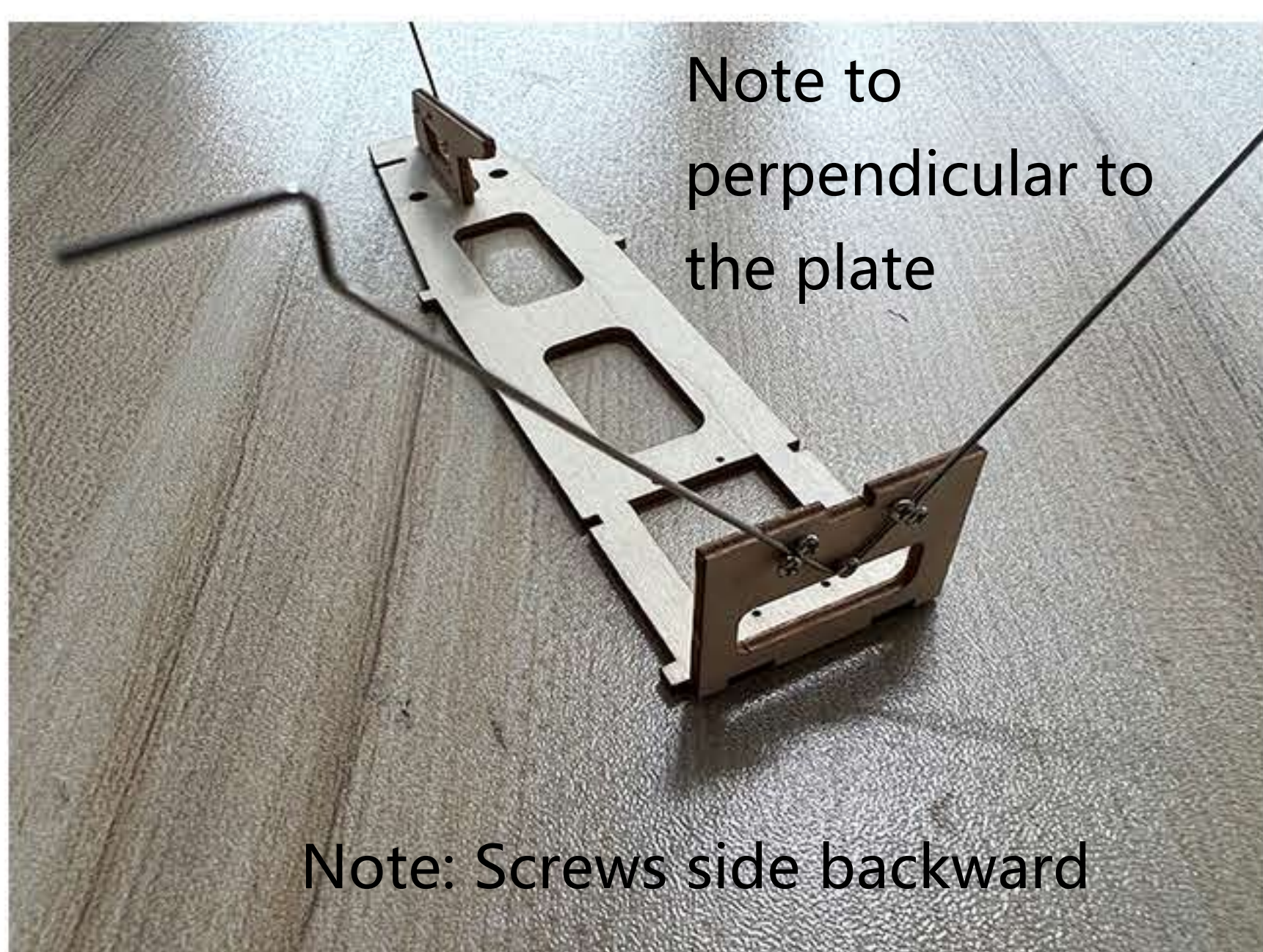
Note the position

Wide

Narrow

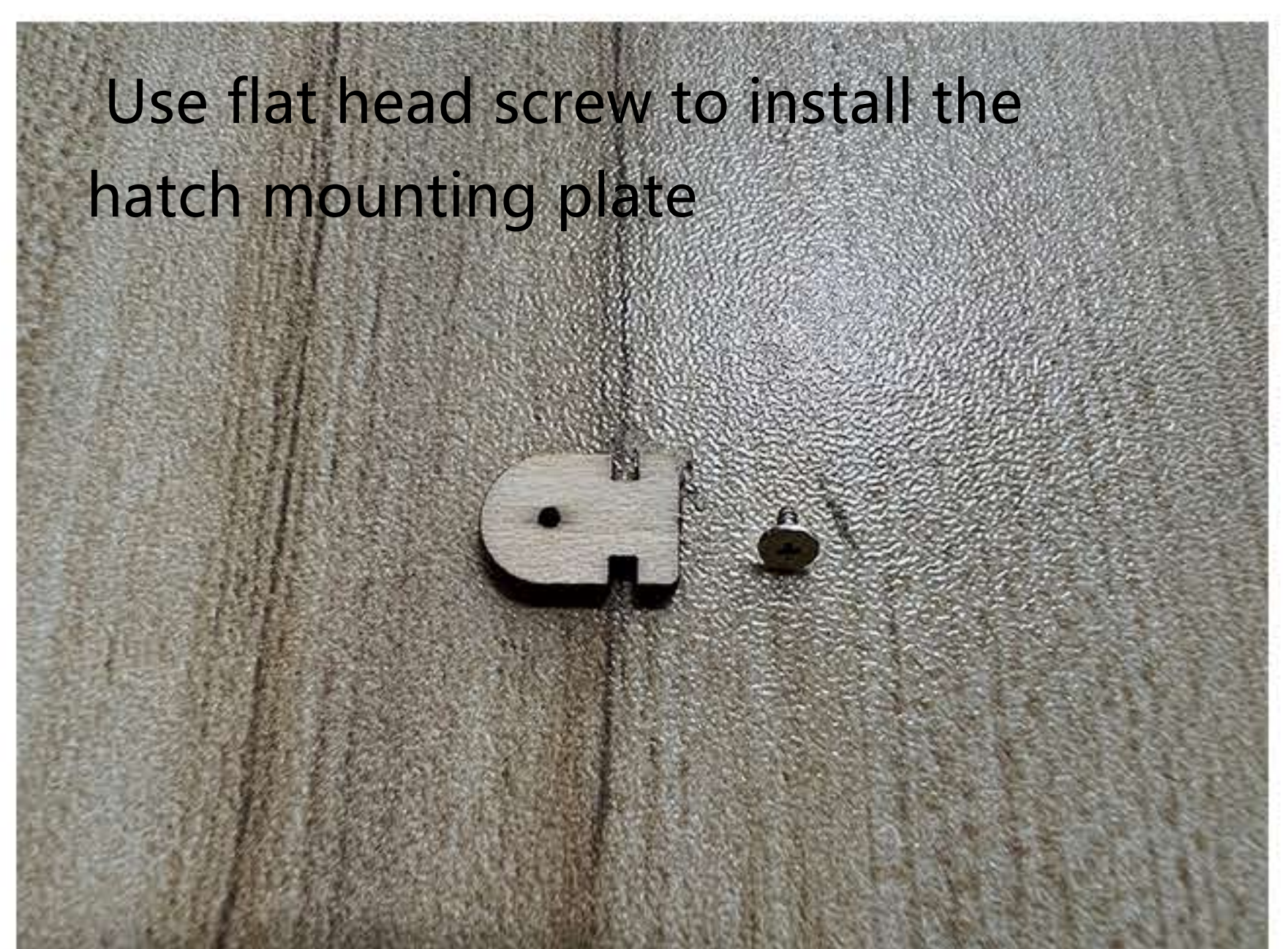


Note: Perpendicular to the electronic plate, use 502 glue

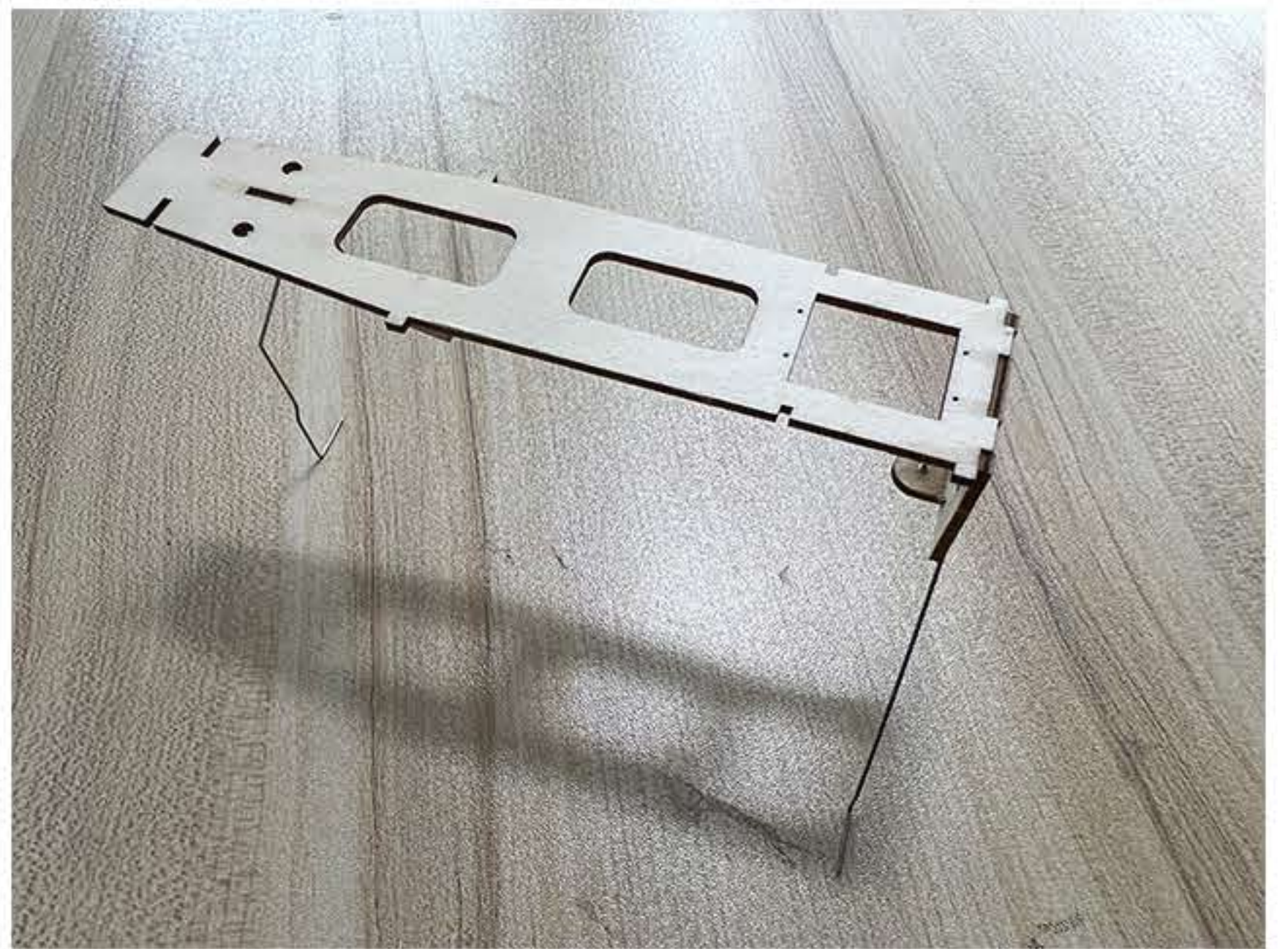
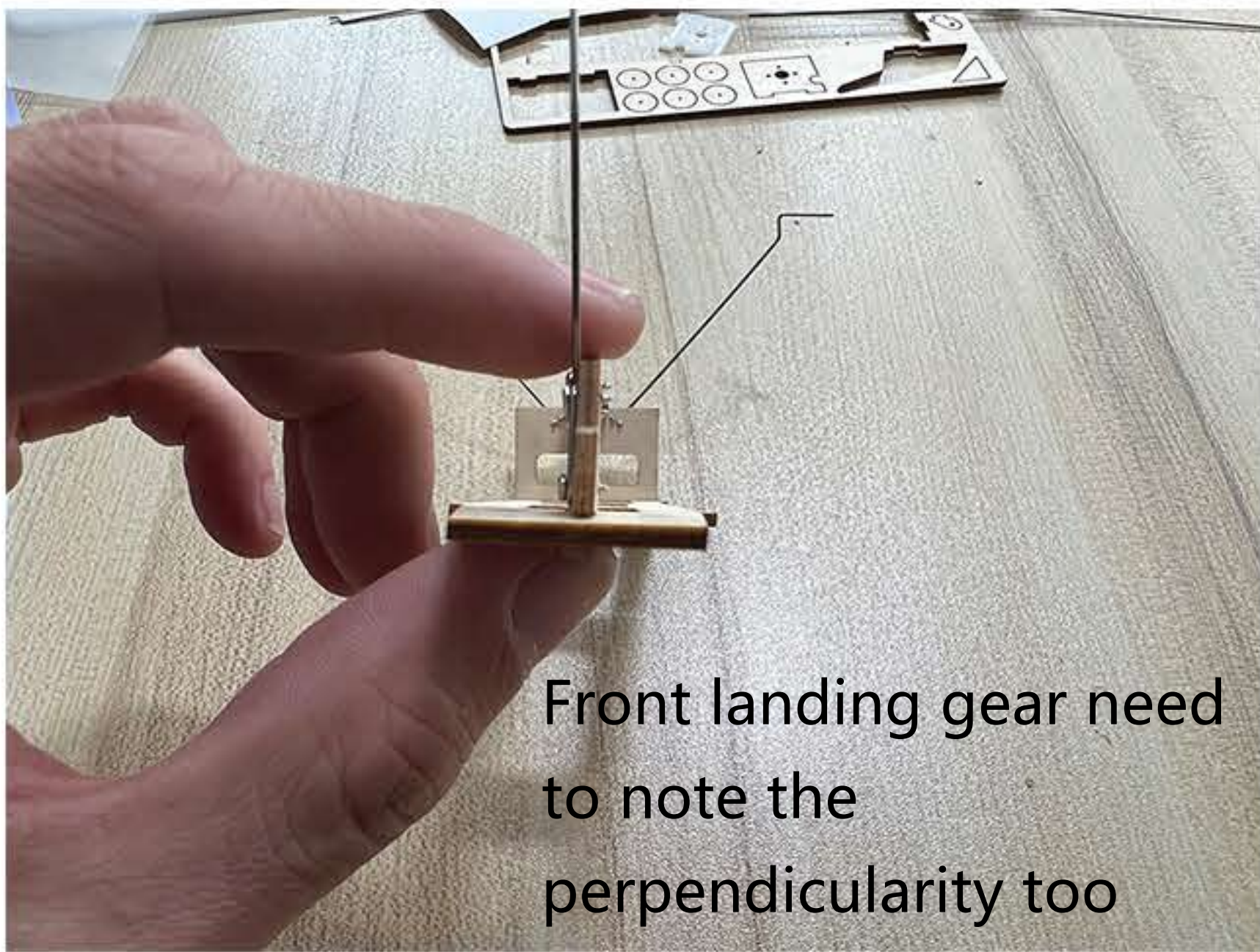
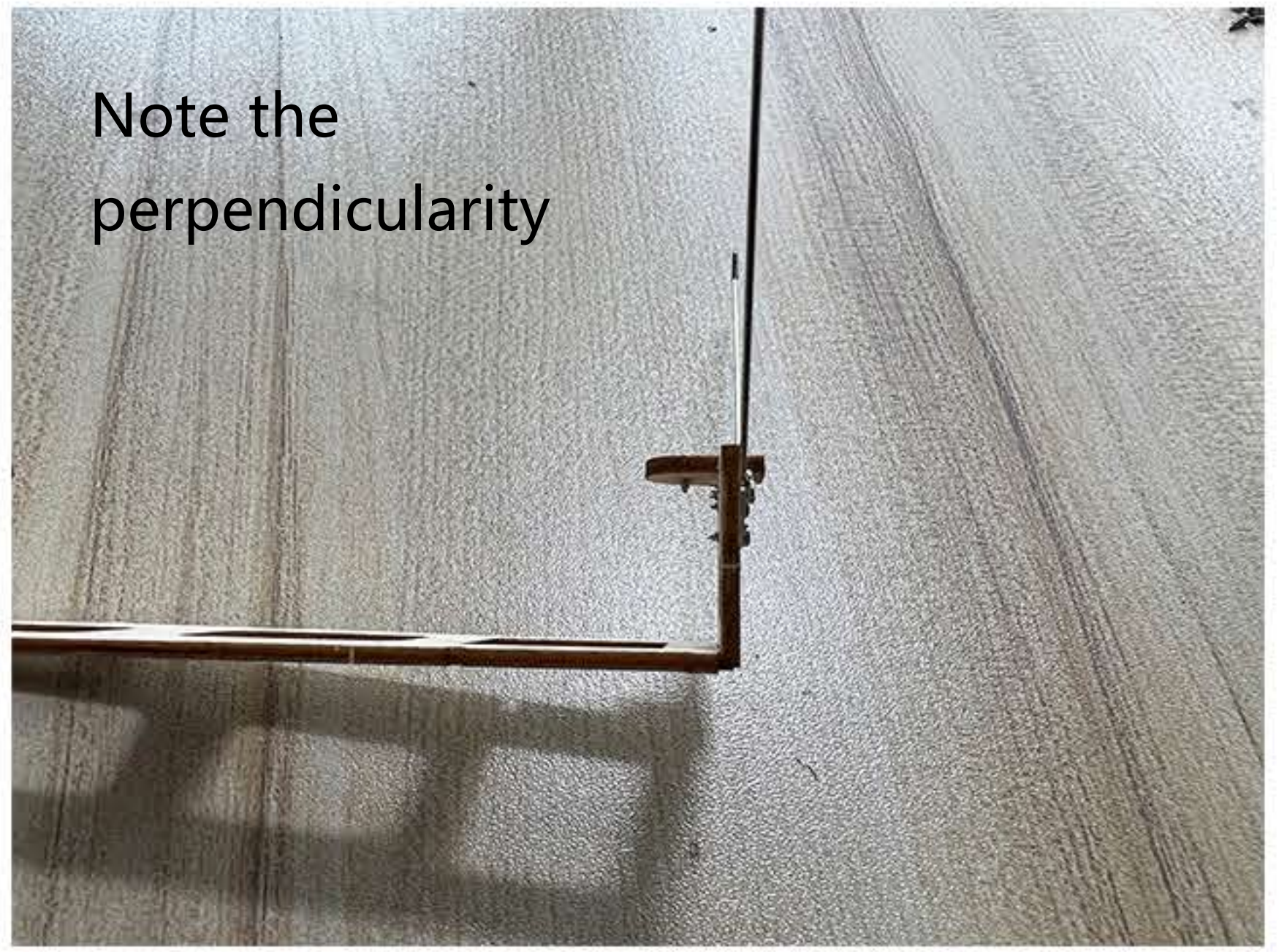
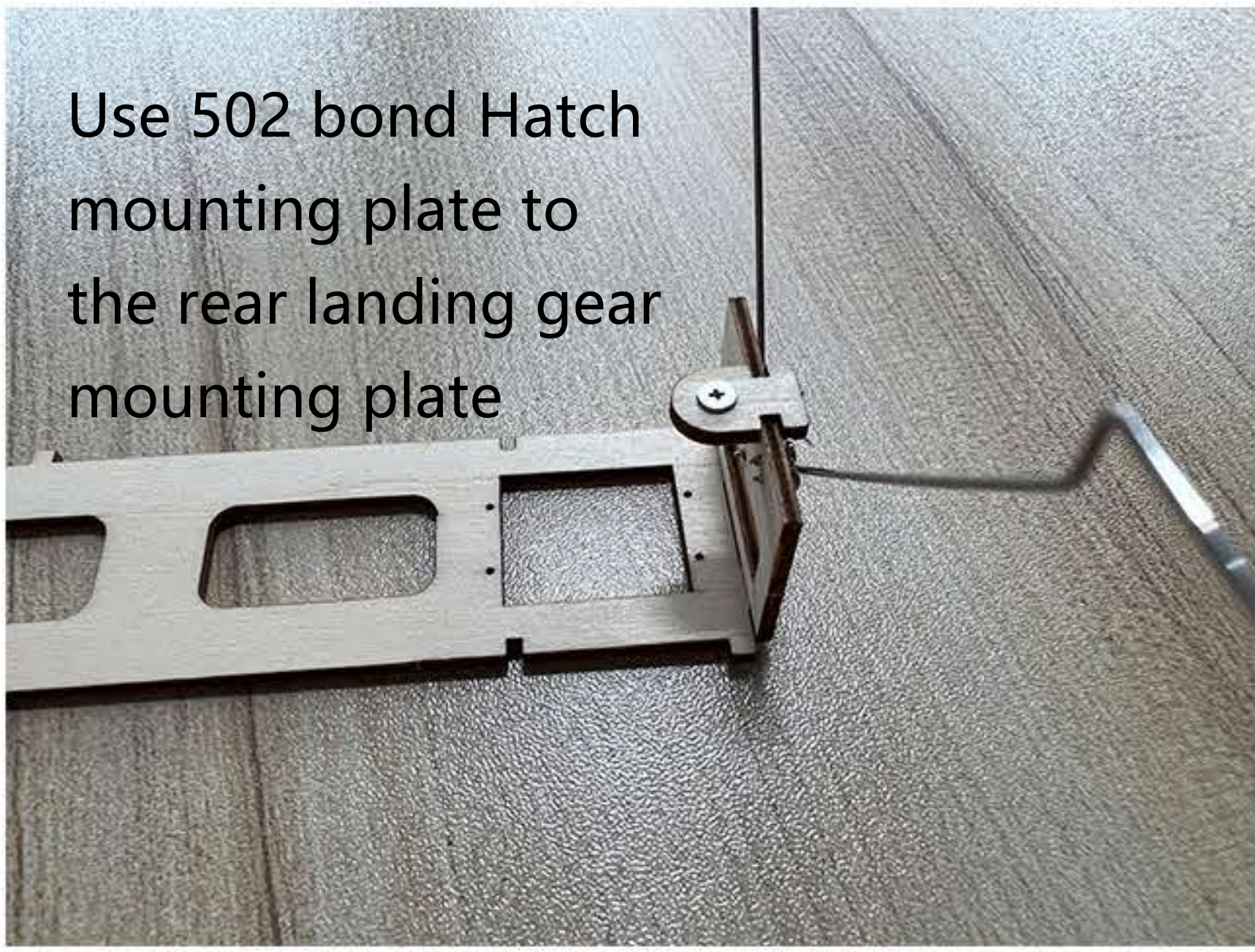


Note to perpendicular to the plate

Note: Screws side backward

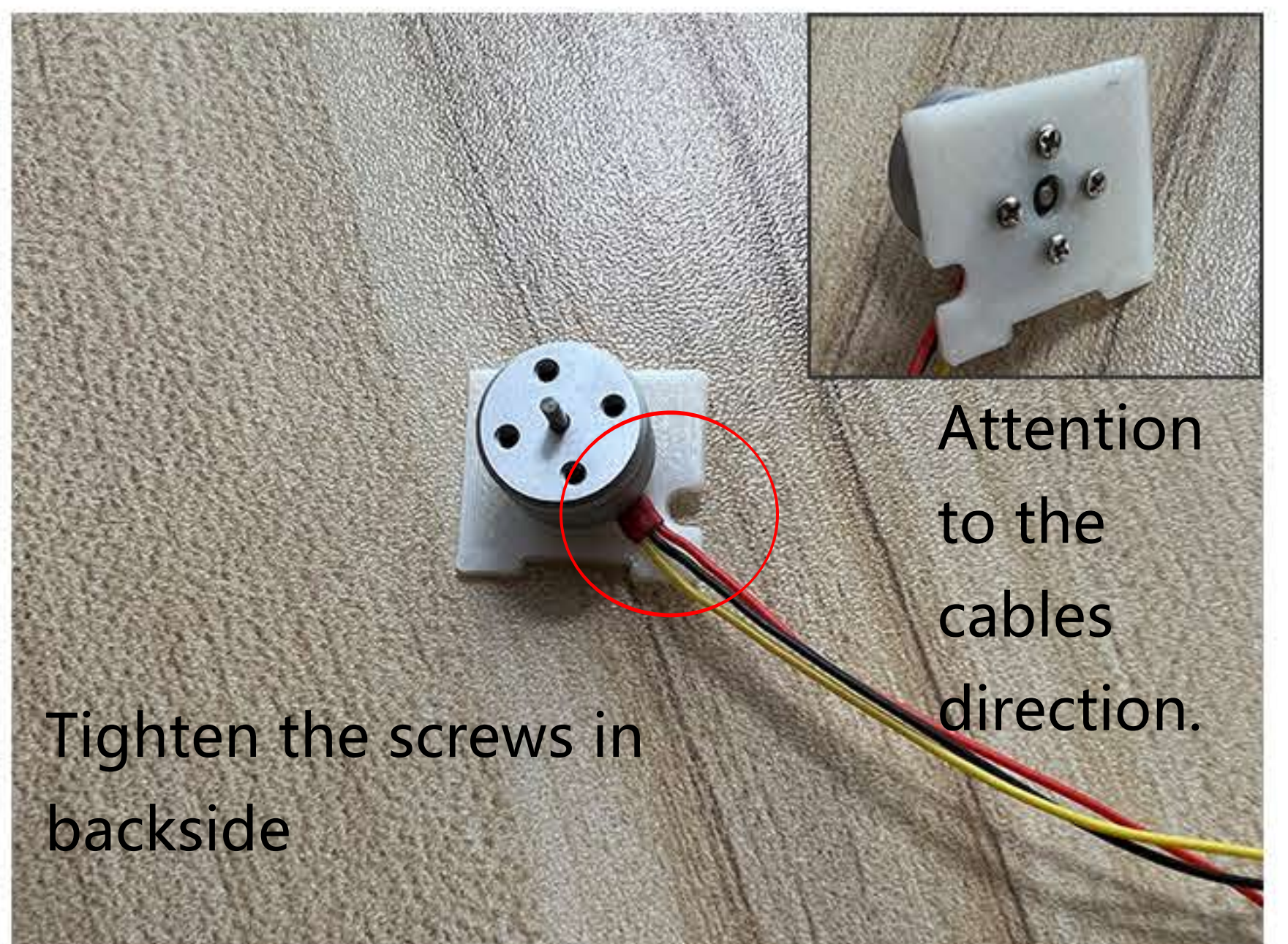


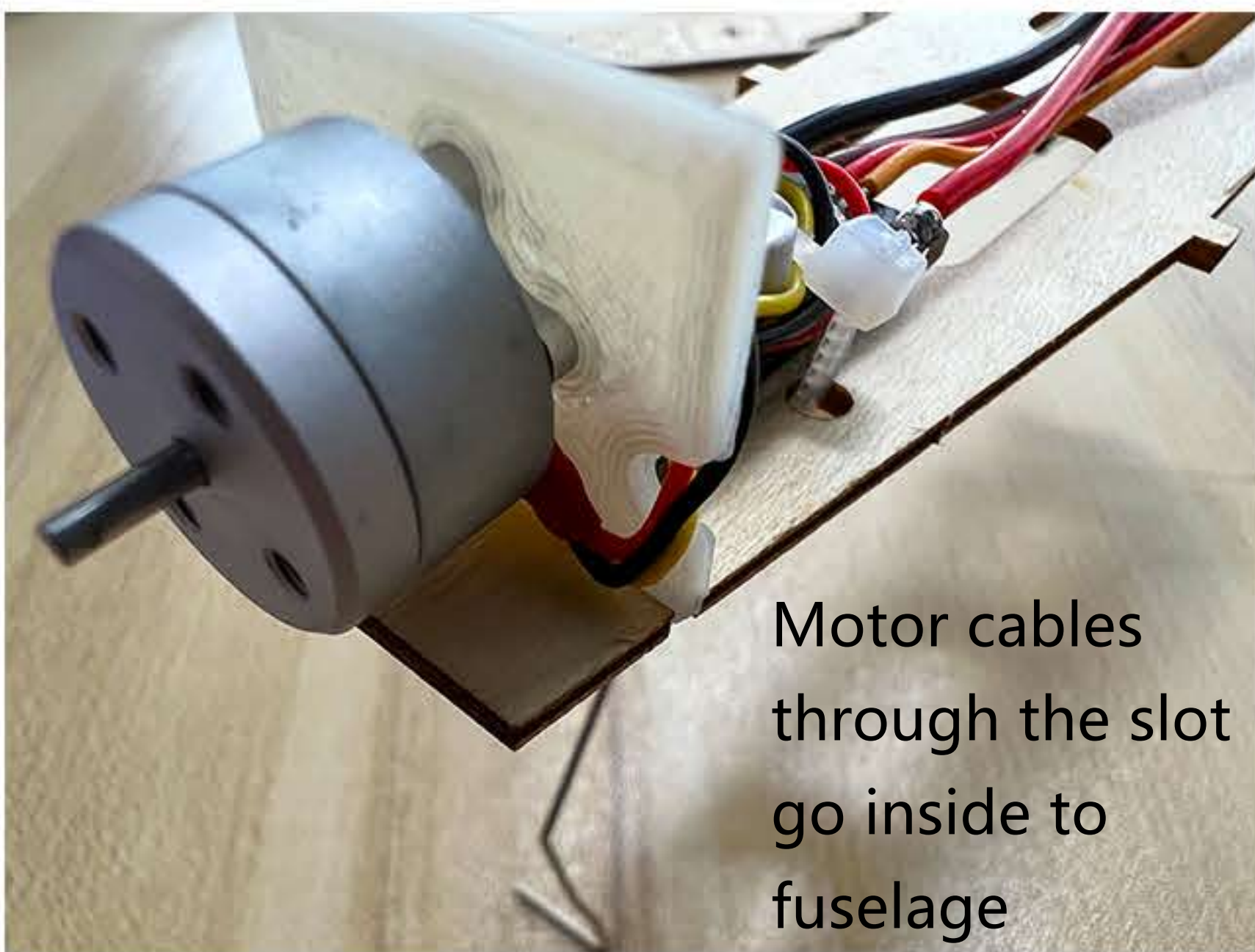
Use flat head screw to install the hatch mounting plate



Install the Motor

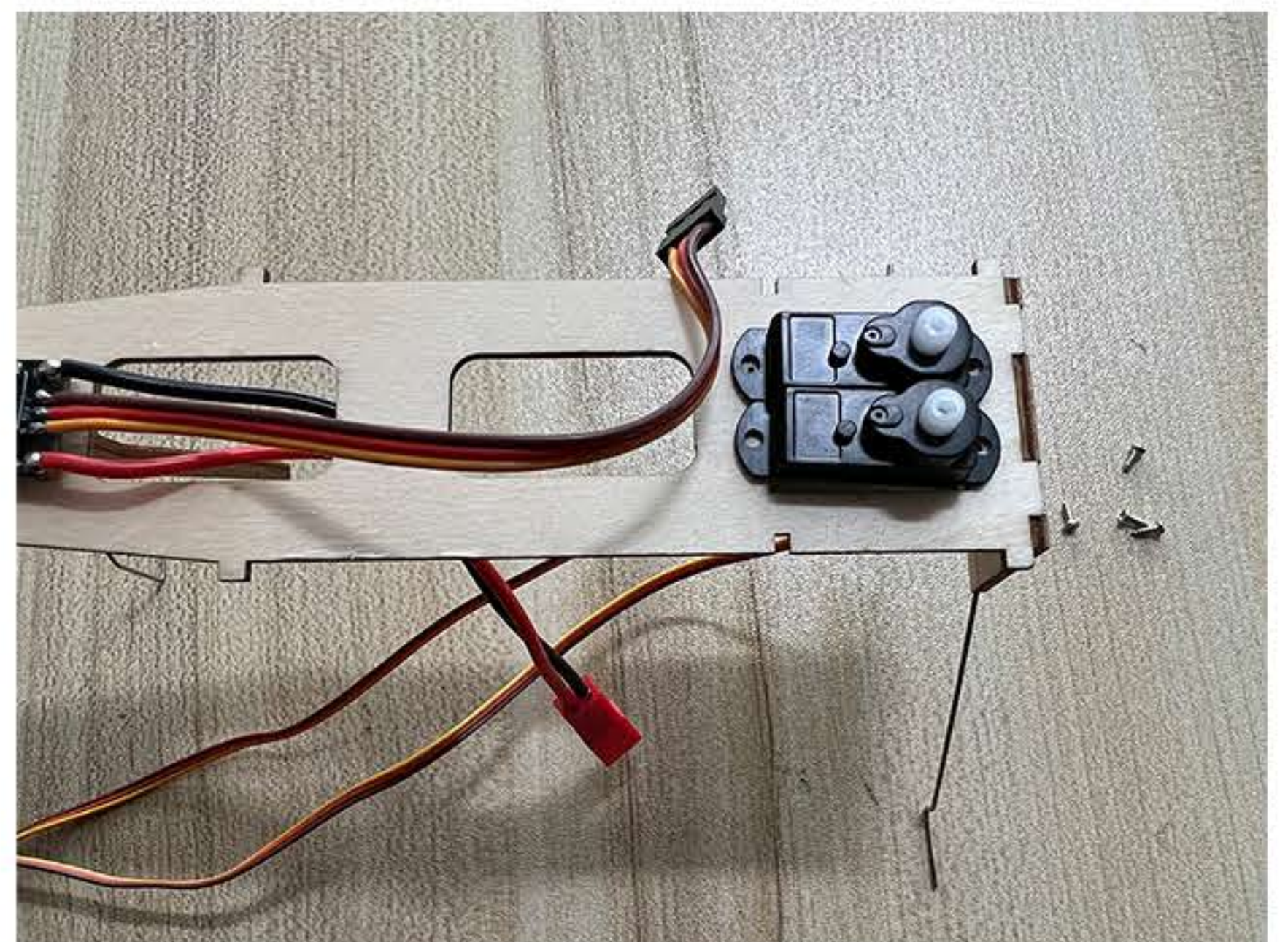
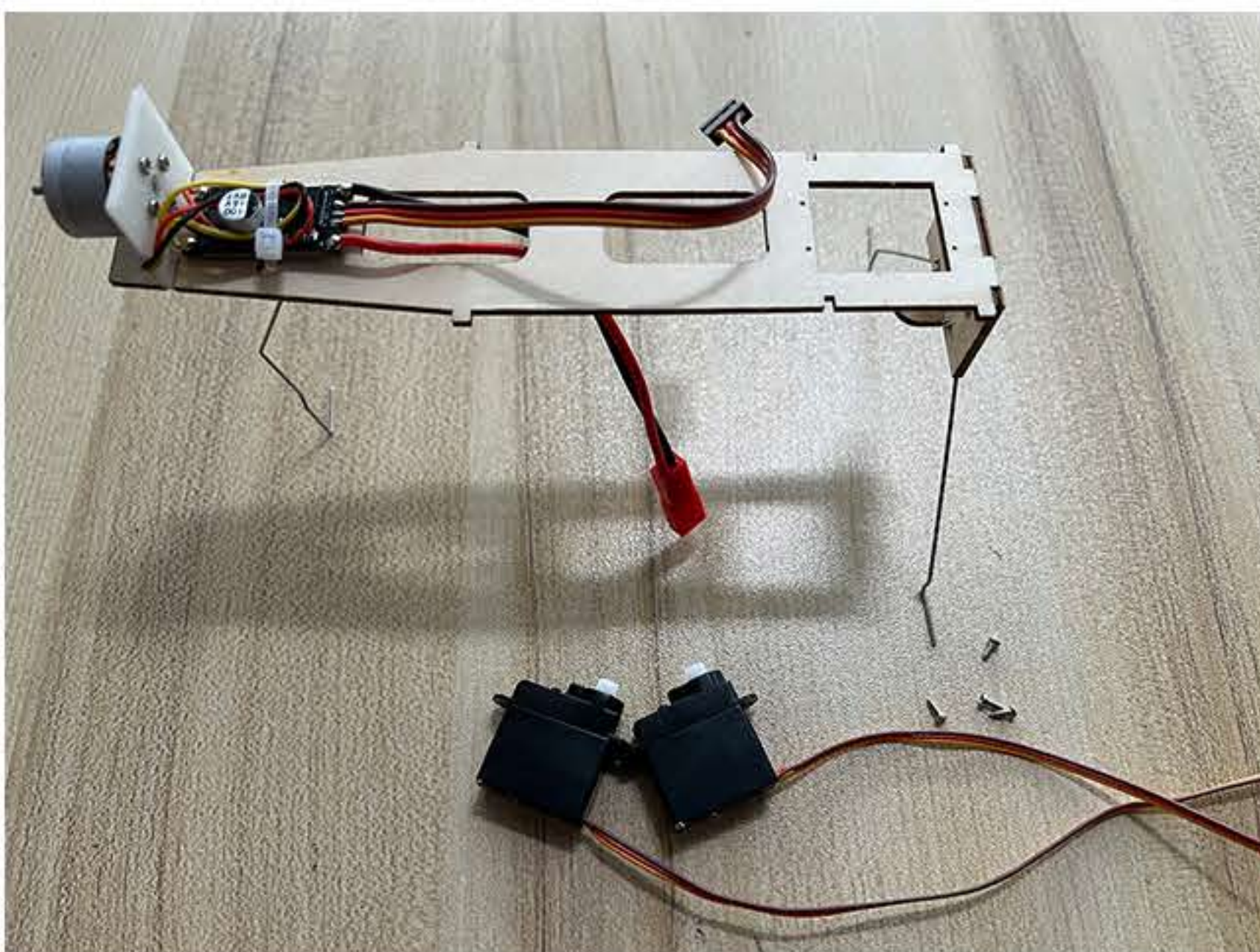
Find out the Motor, ESC, 3D print motor mounting base and 1.4*3 screws. Install as below picture shown

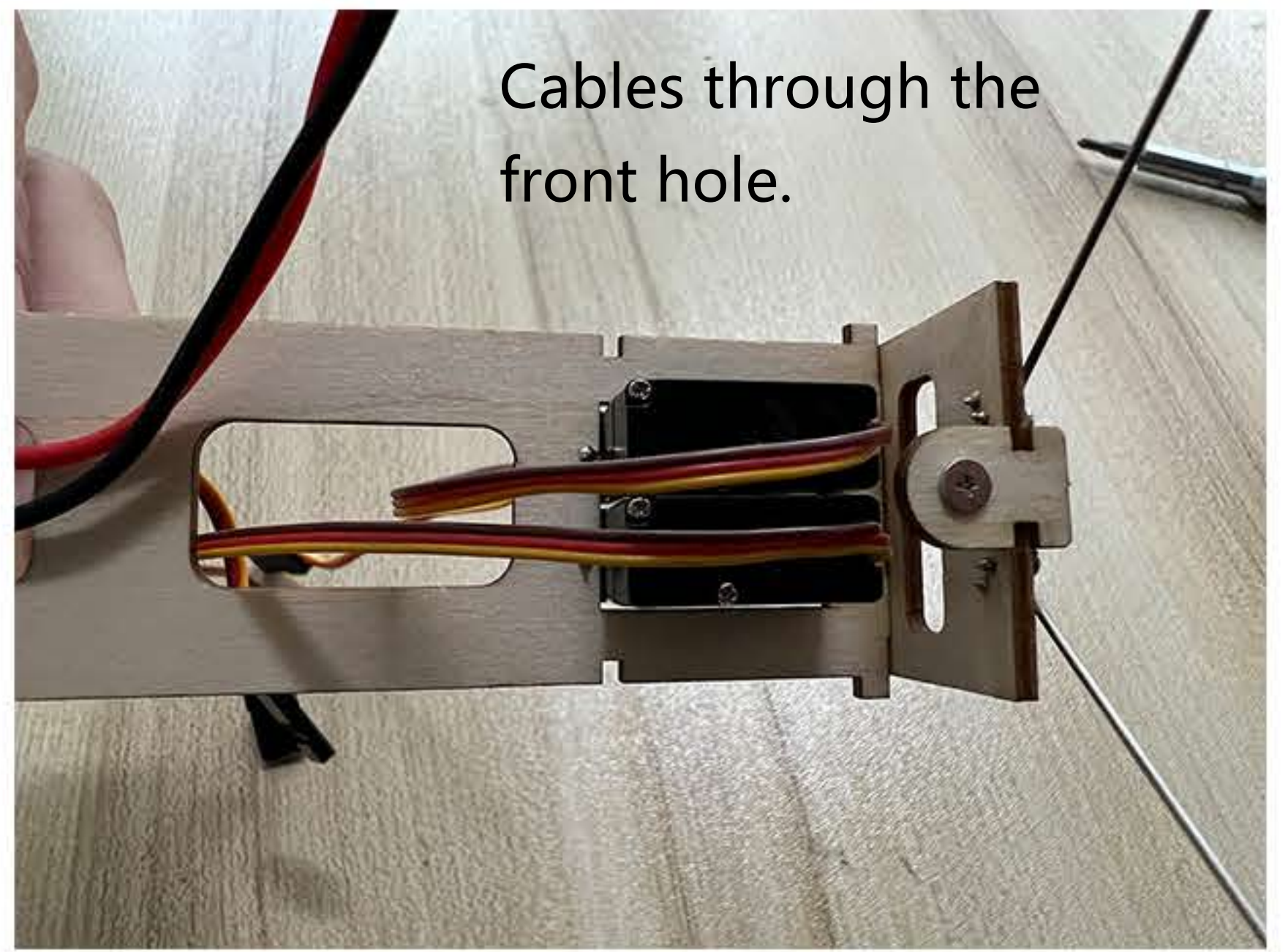




Install servos

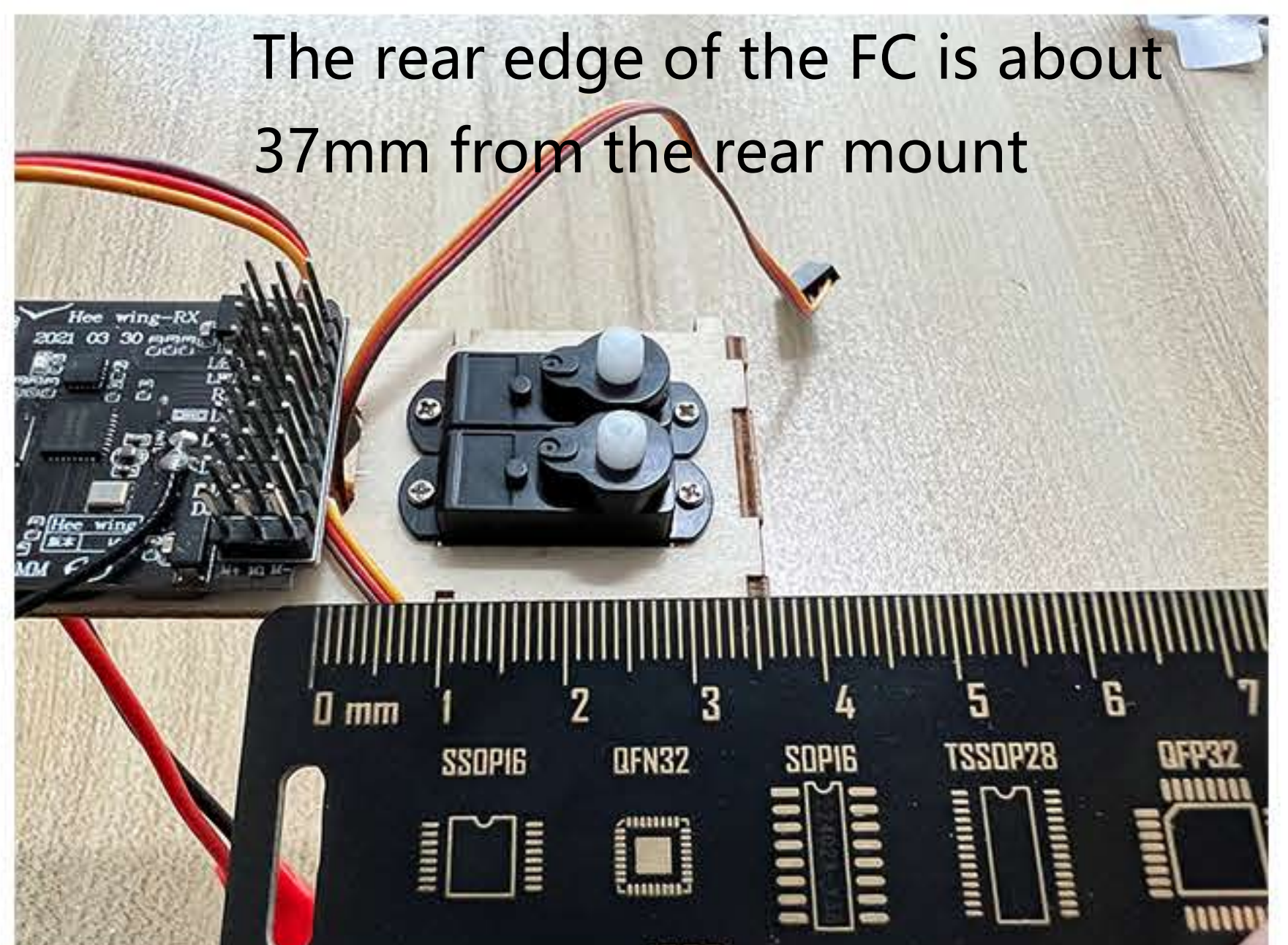
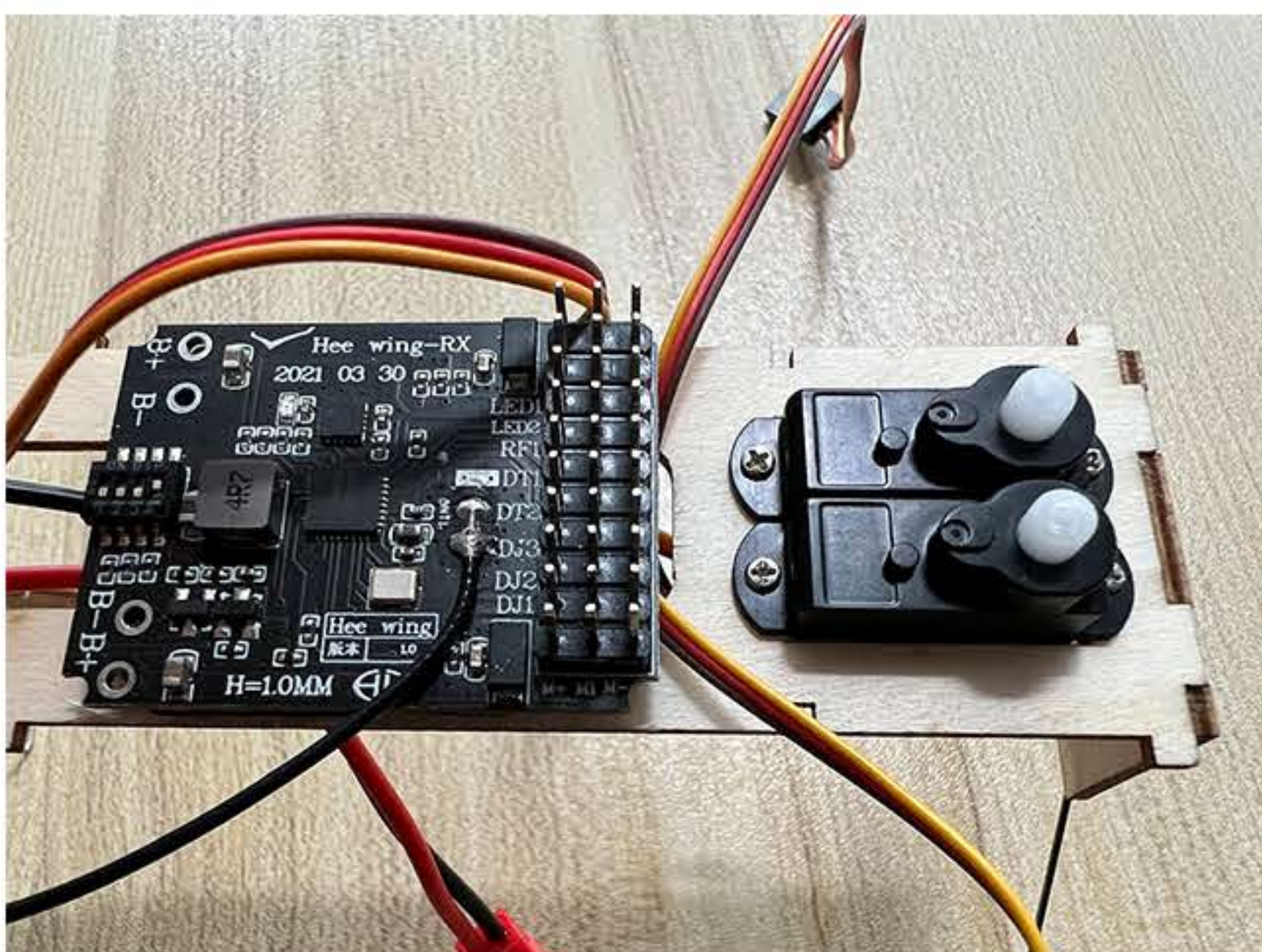
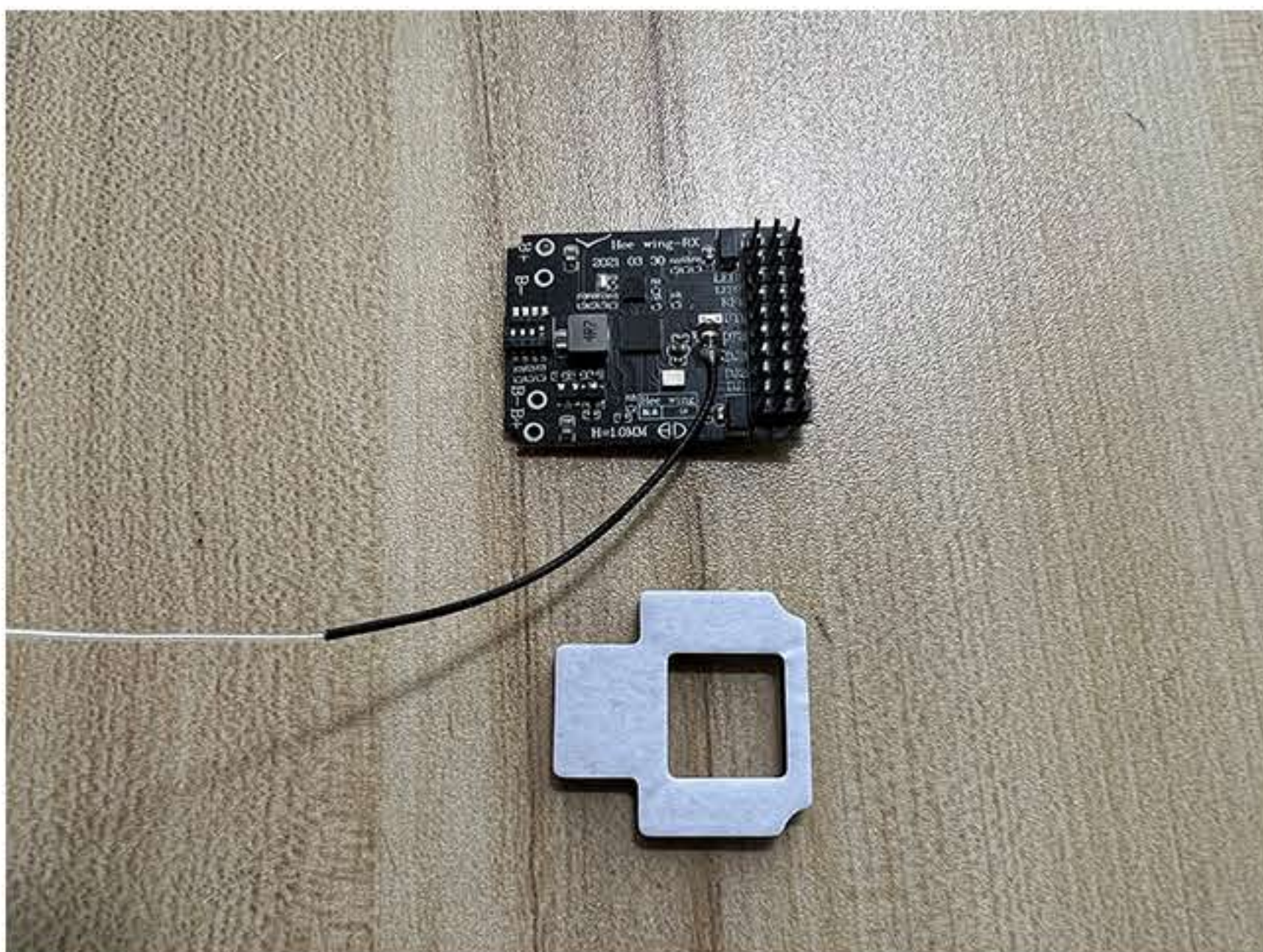
As below picture shows: Note the install direction, use 1.5*4 screws to fix.

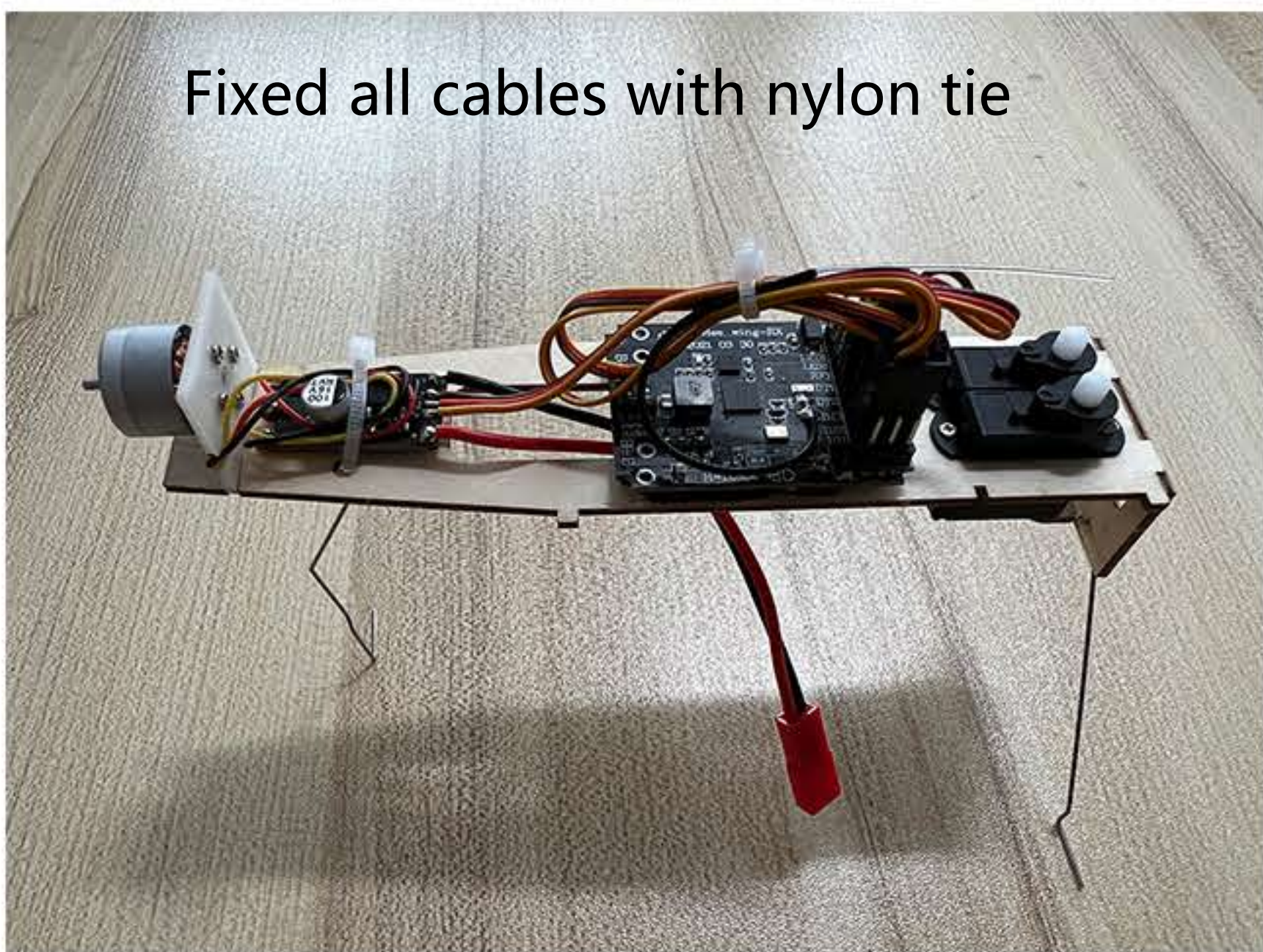
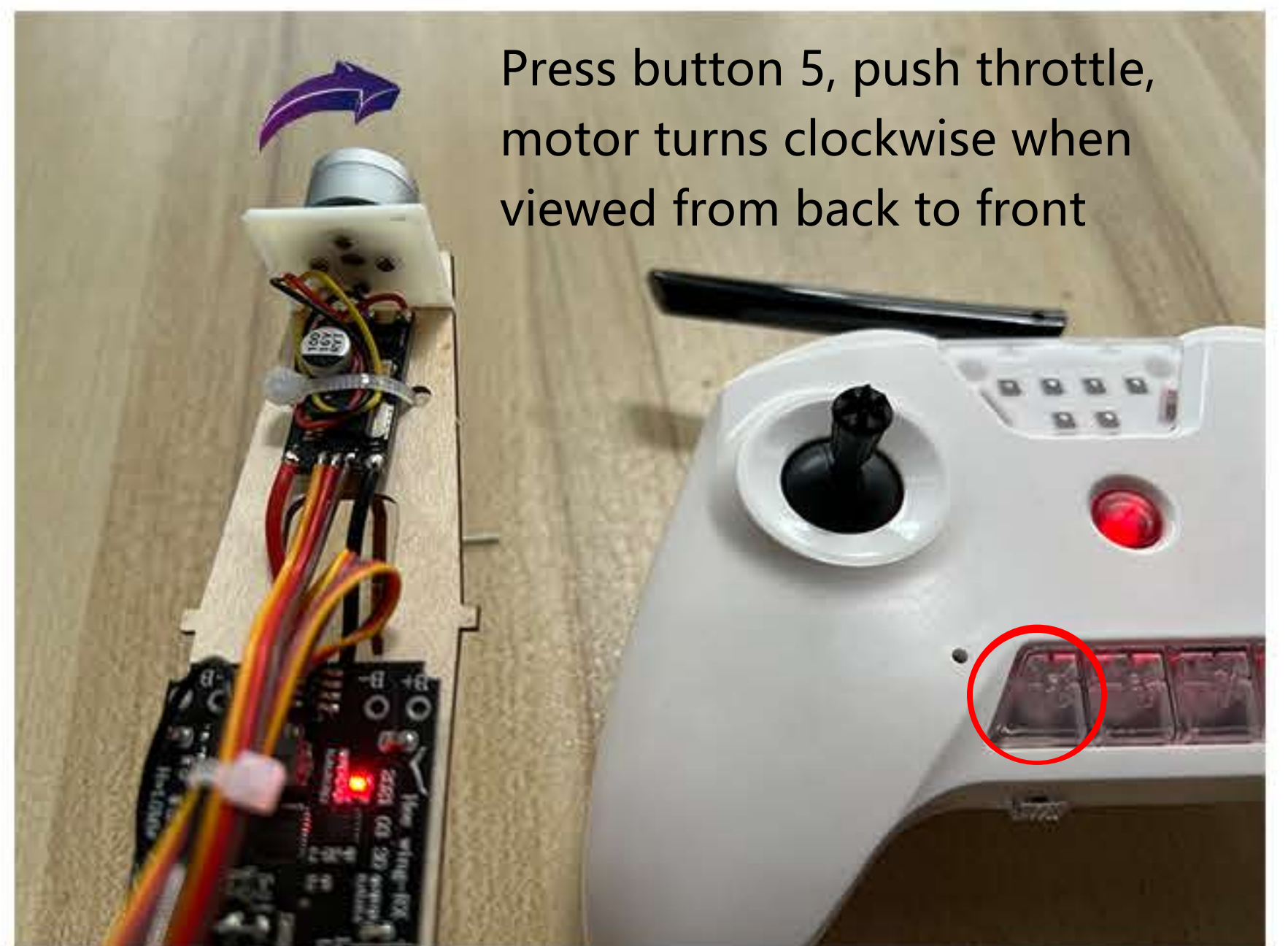
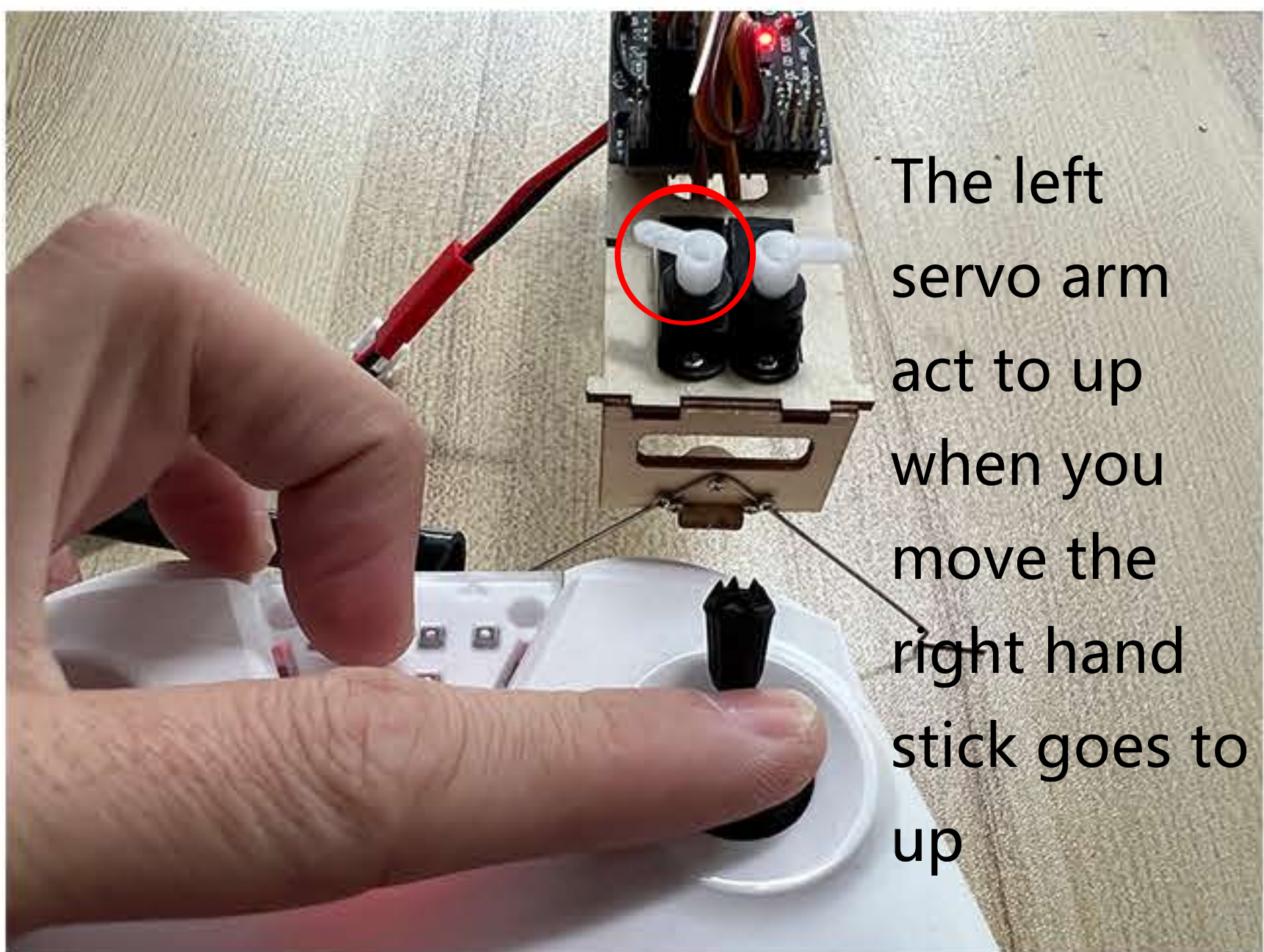
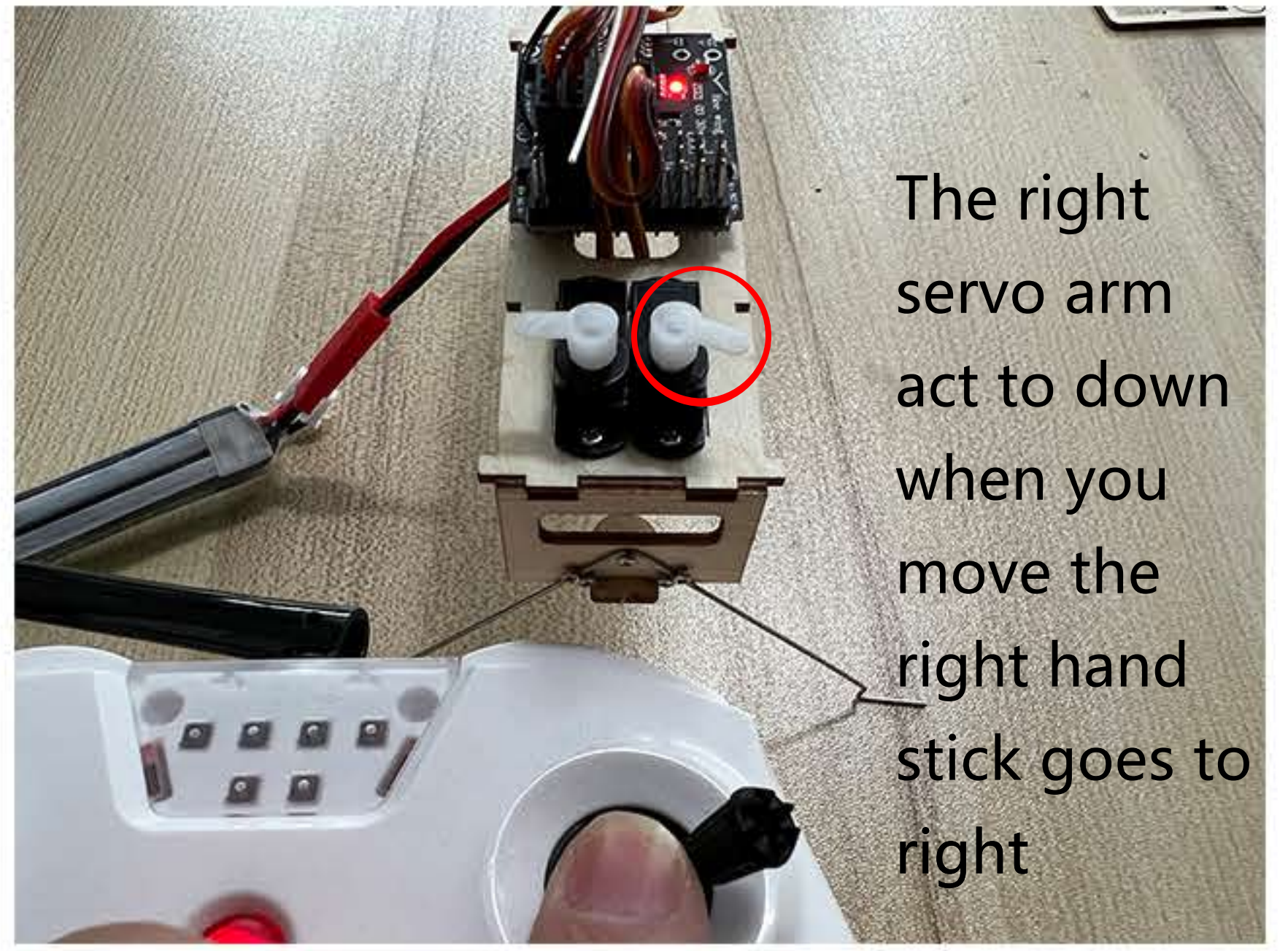
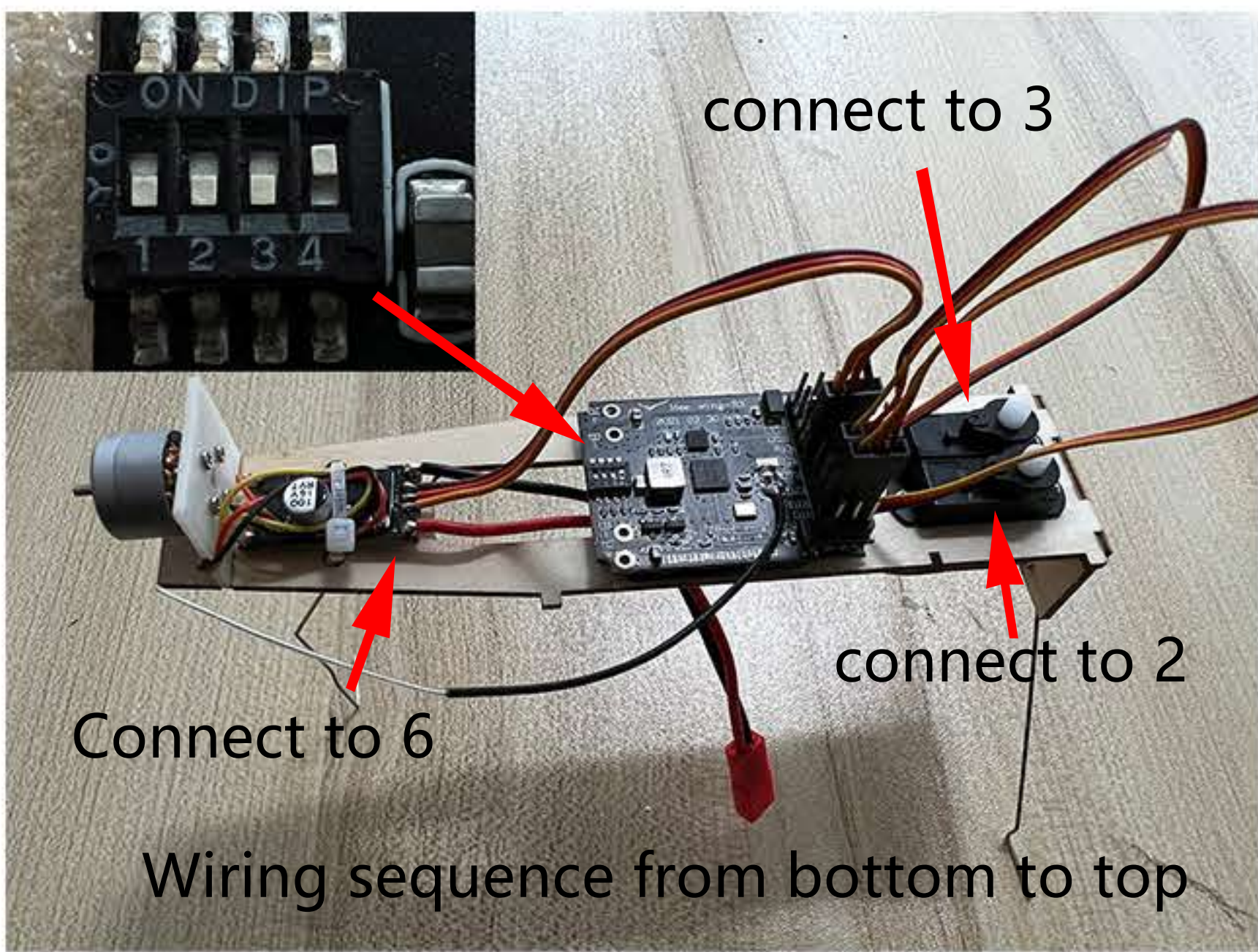




Install RX1.0

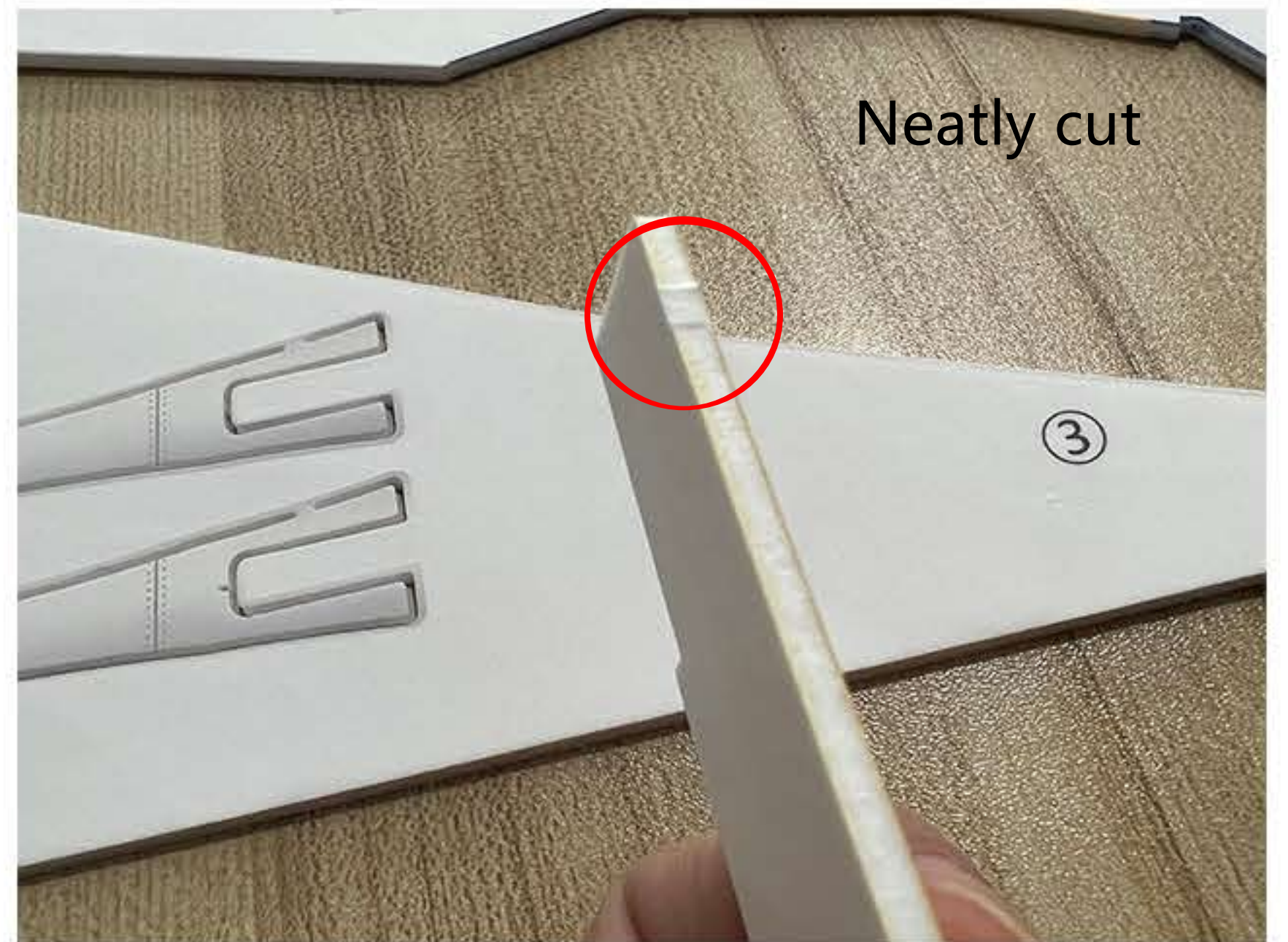
Glue the flight controller with thick double-sided tape and find a suitable place to paste it on the motor board. Connect the cables and test each part is working properly.



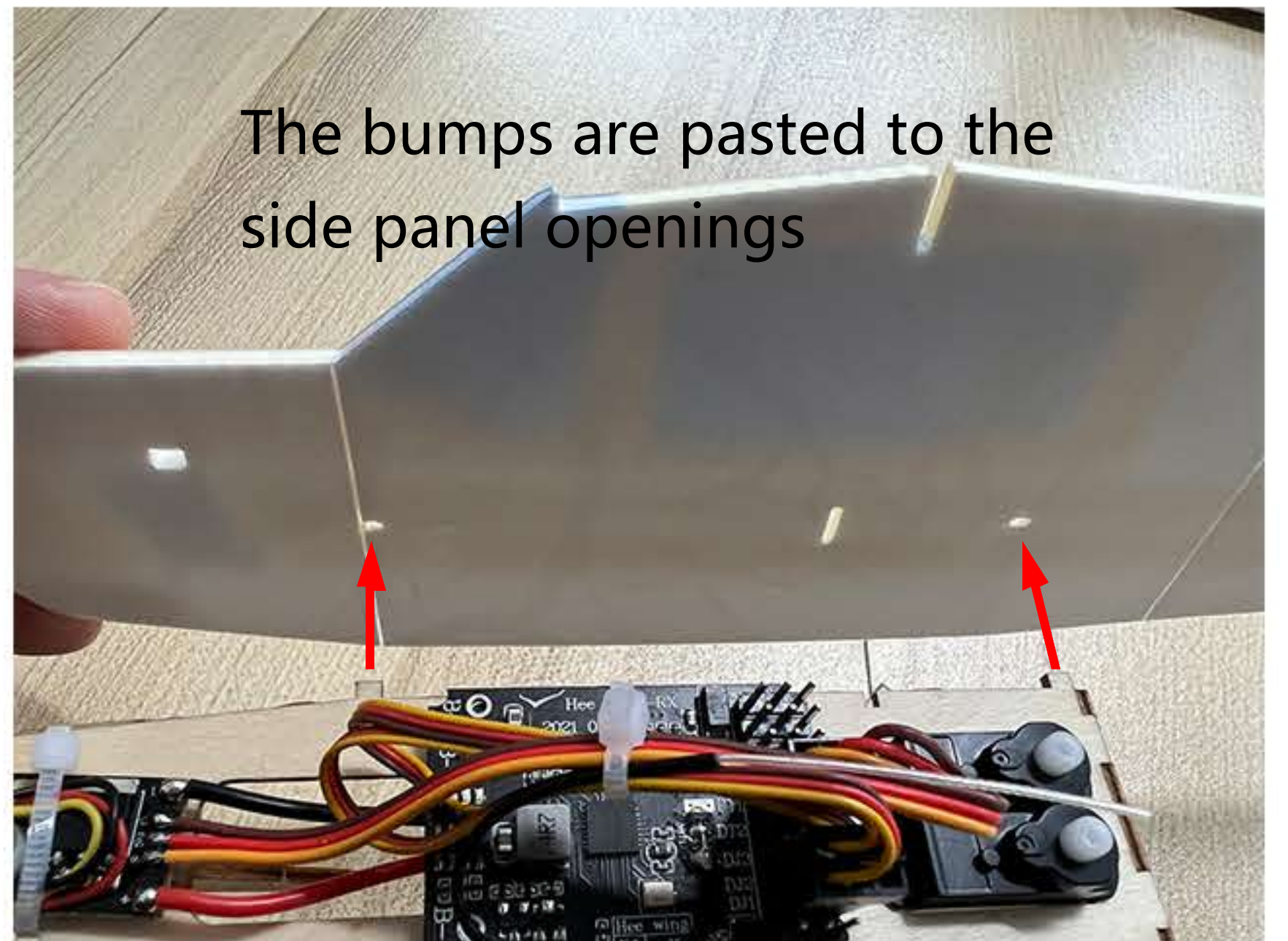
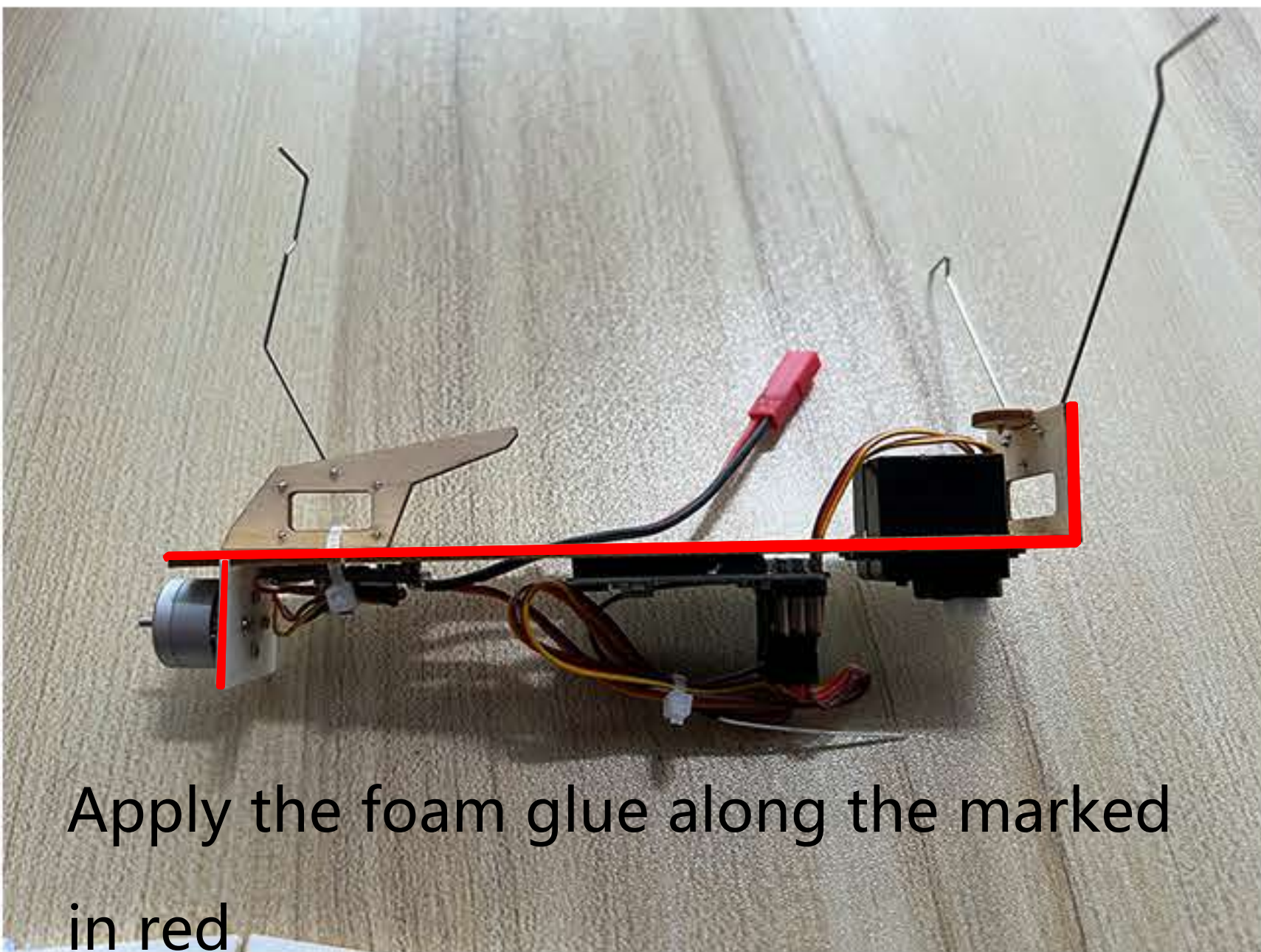


Fuselage assembly

Find out the No.3 right frame board, neatly cut for a better smooth application. (All the following plates are cut neatly.)

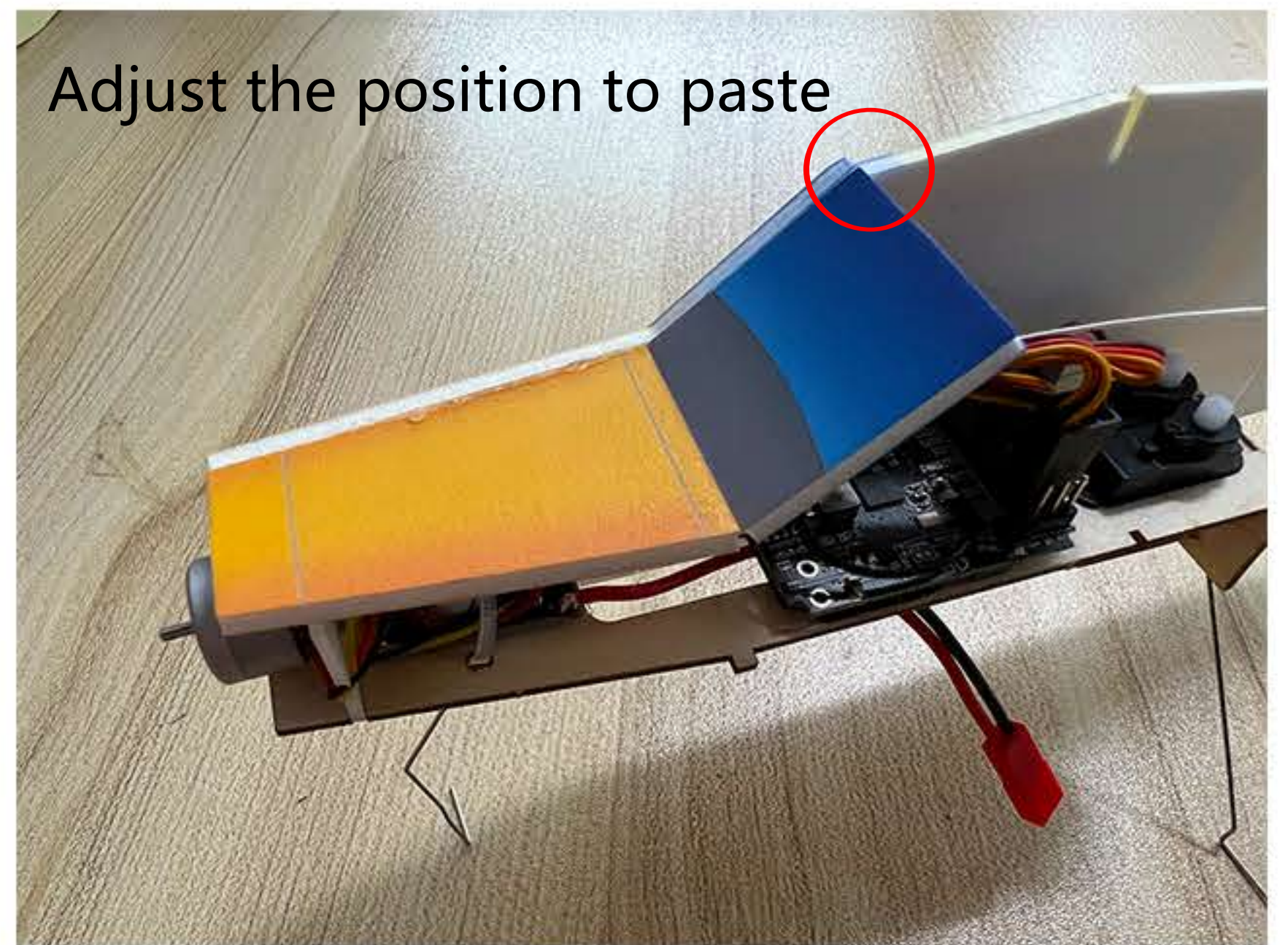
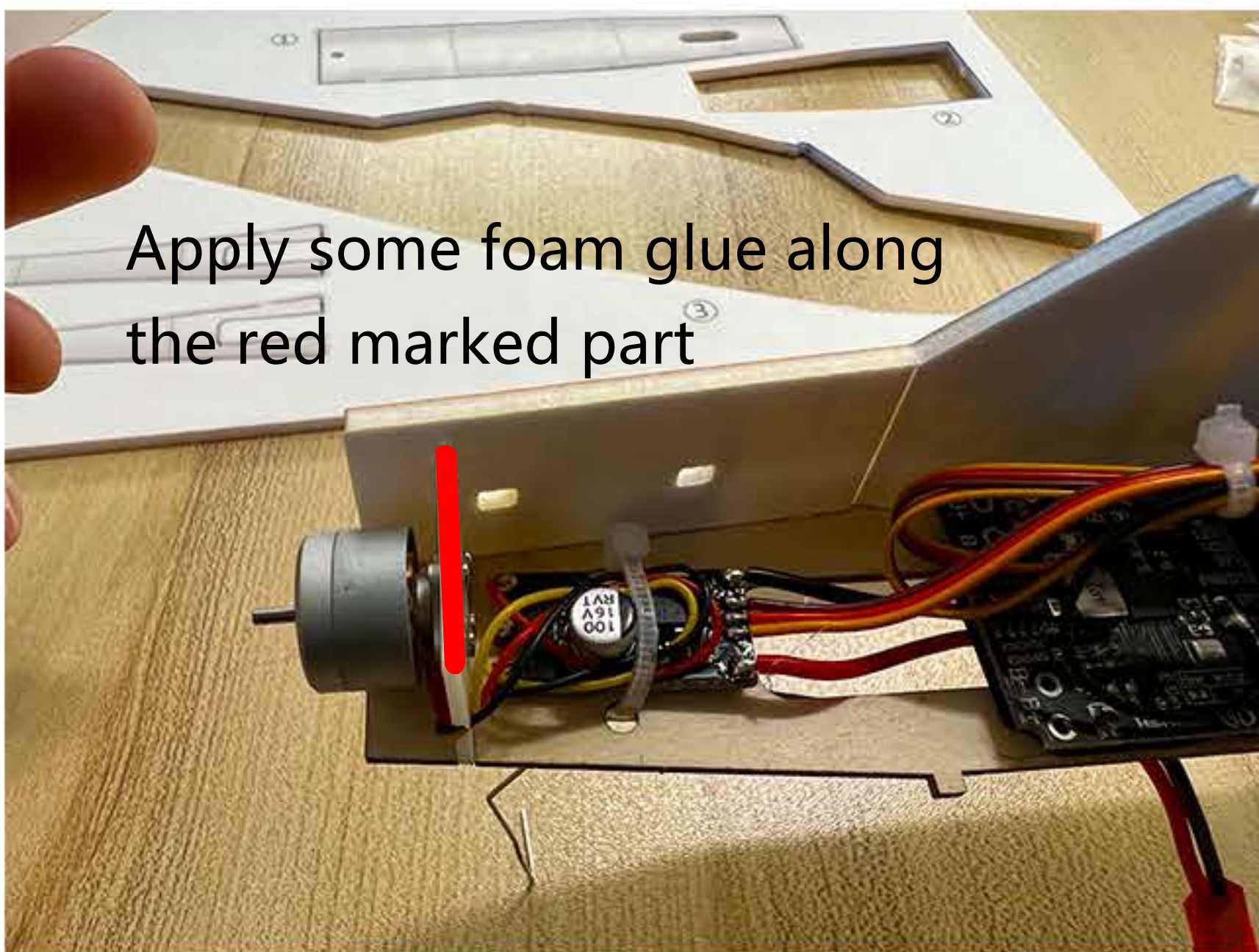
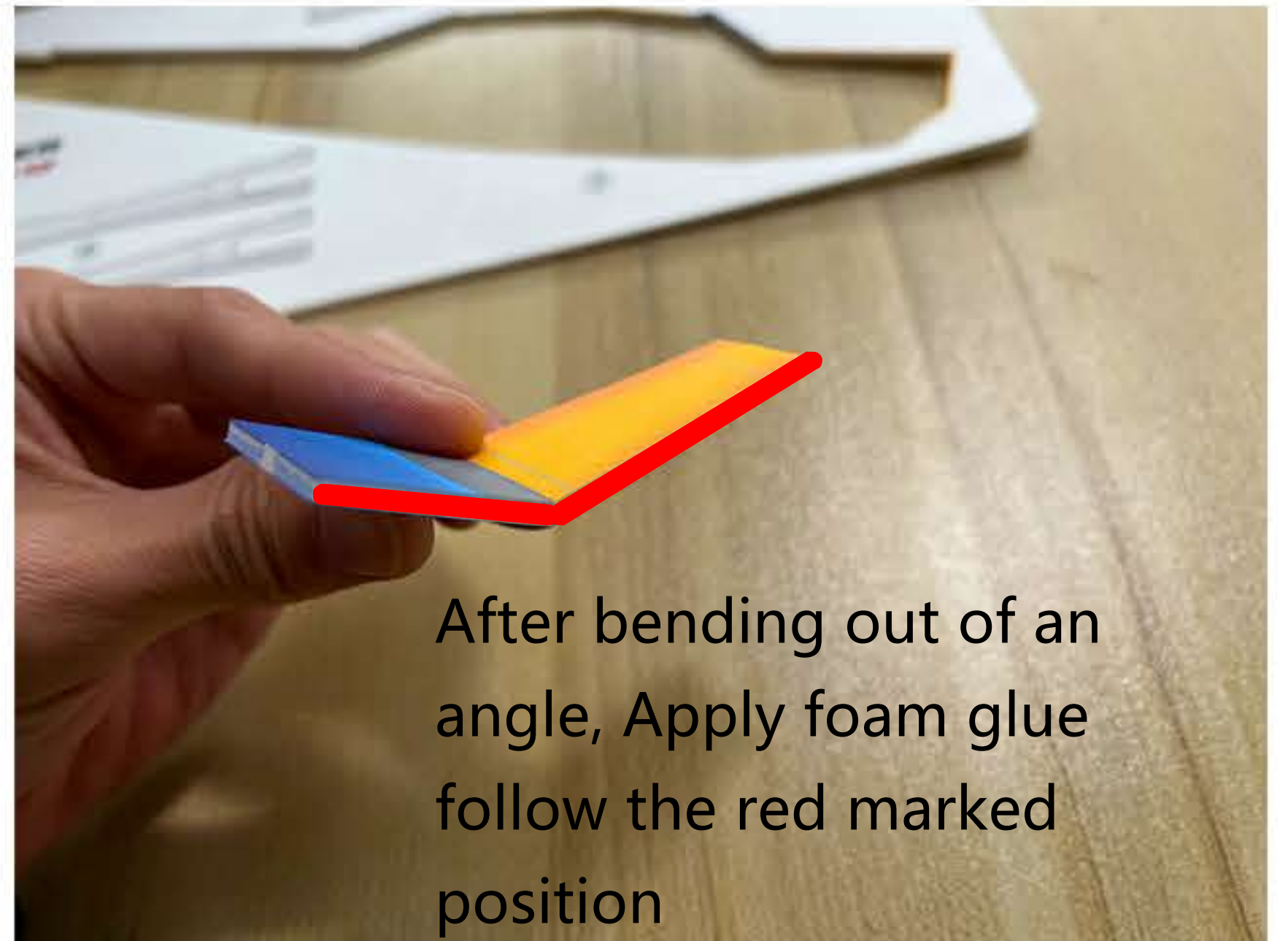


Apply foam glue to the right side of electronic mounting plate, adjust the position and paste it on the right frame.



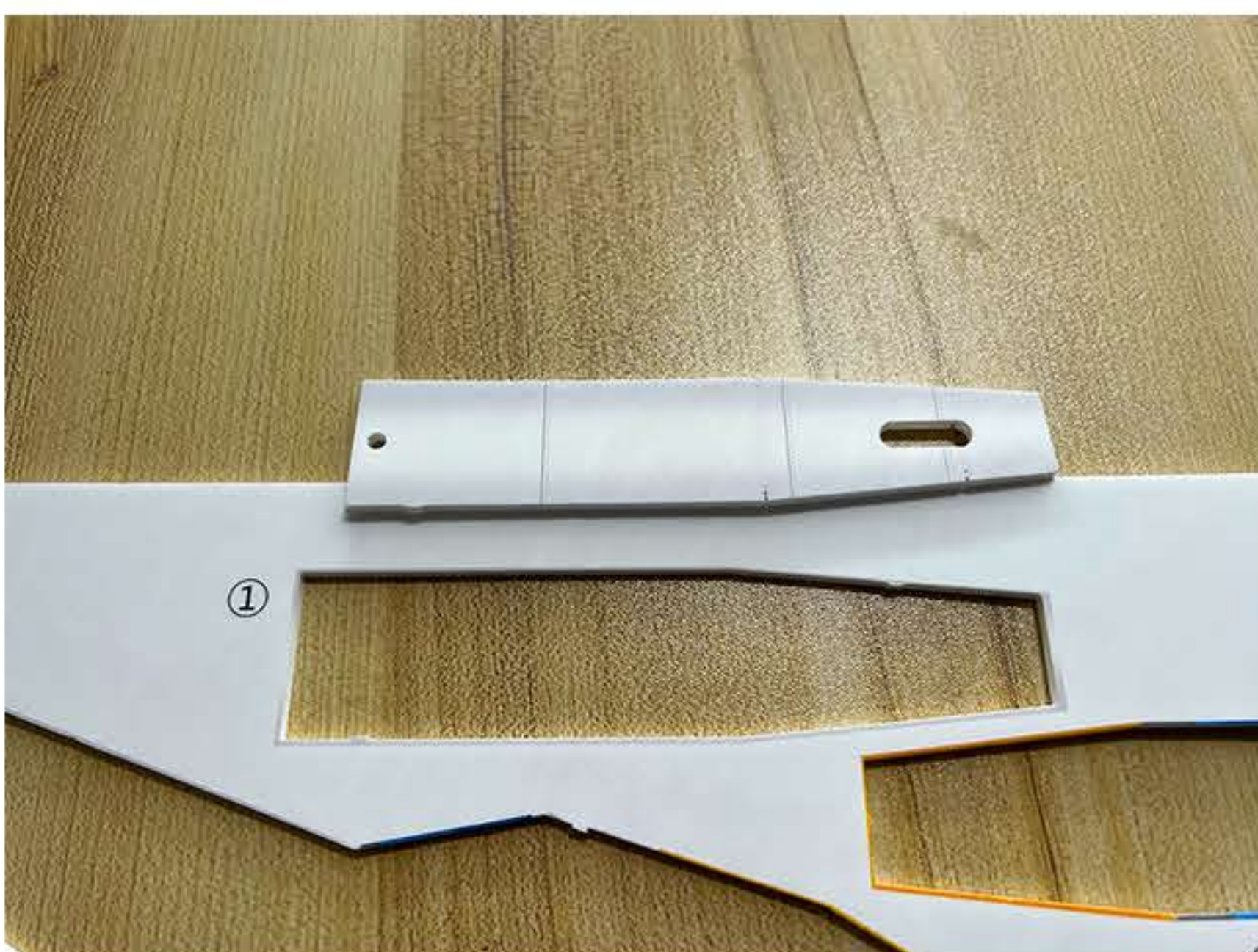
Paste the fuselage upper plate

Take out the plate 2, cut the incision, and fold it by hand along the back line at an angle for a better fit when pasting, apply foam glue to the pasting position and adjust the position to paste

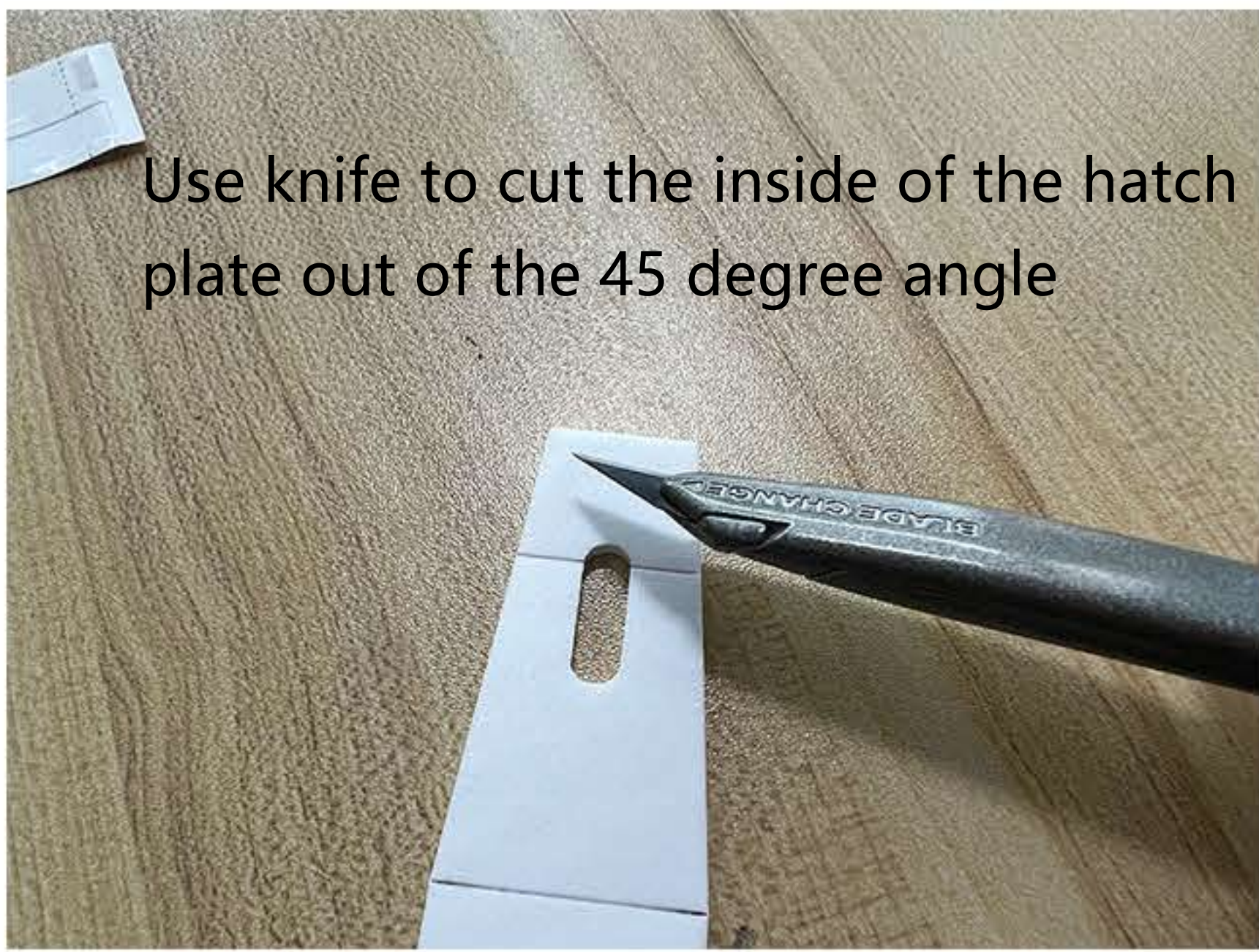


Hatch assembly

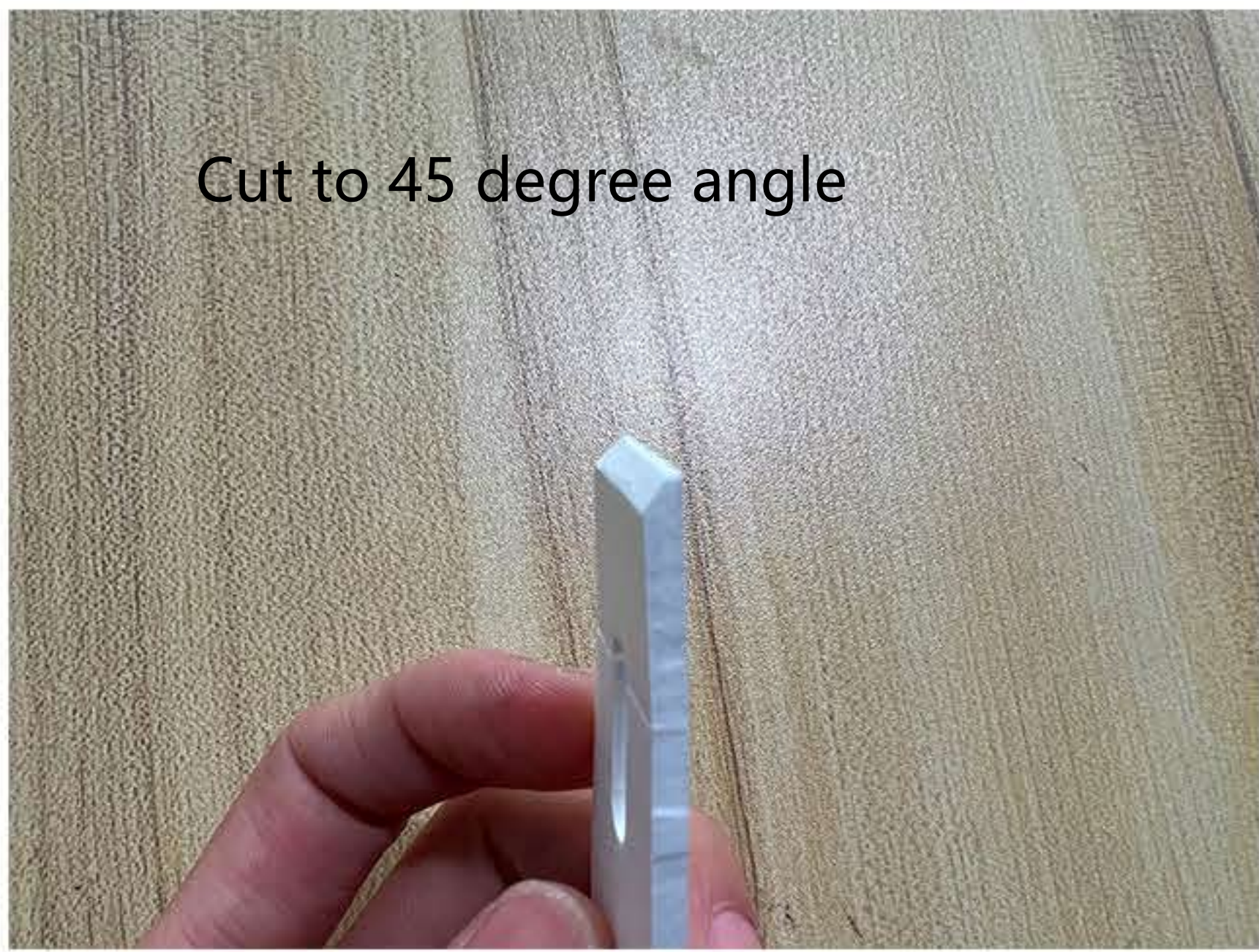
Take out the No.1 board, assemble the magnet, stick on the hatch sticker(handle), install to the electronic mounting plate



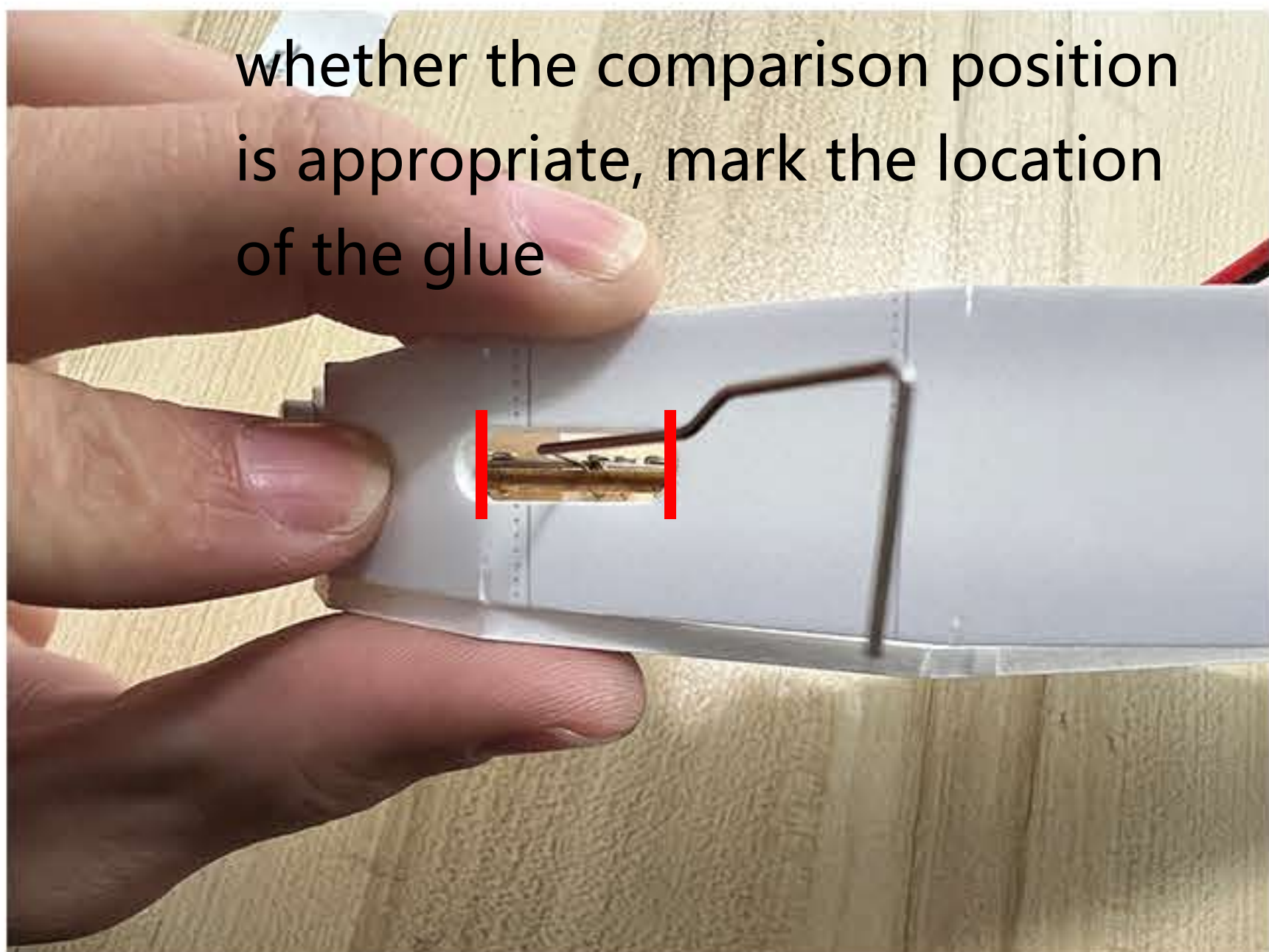




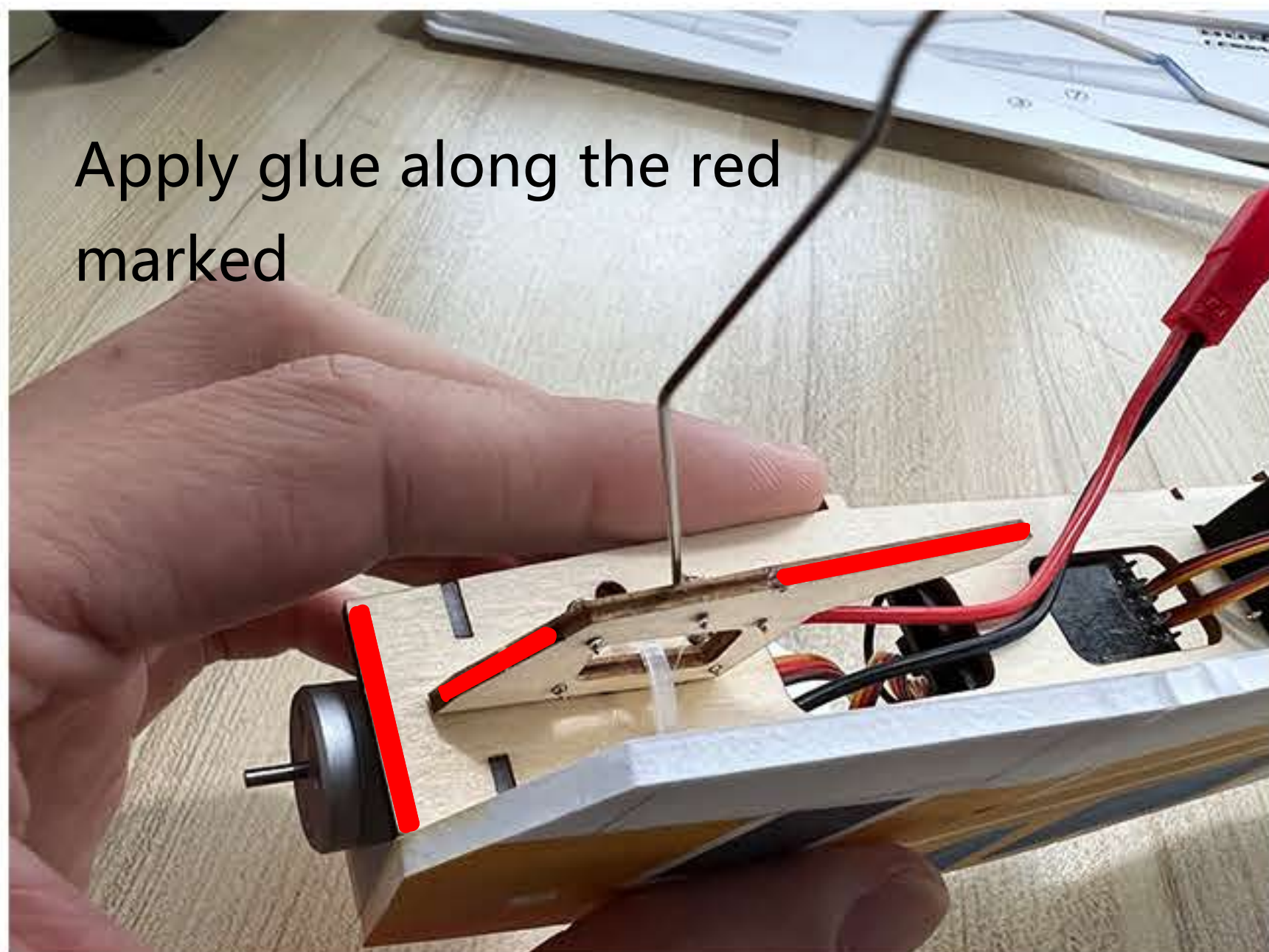
Use knife to cut the inside of the hatch plate out of the 45 degree angle



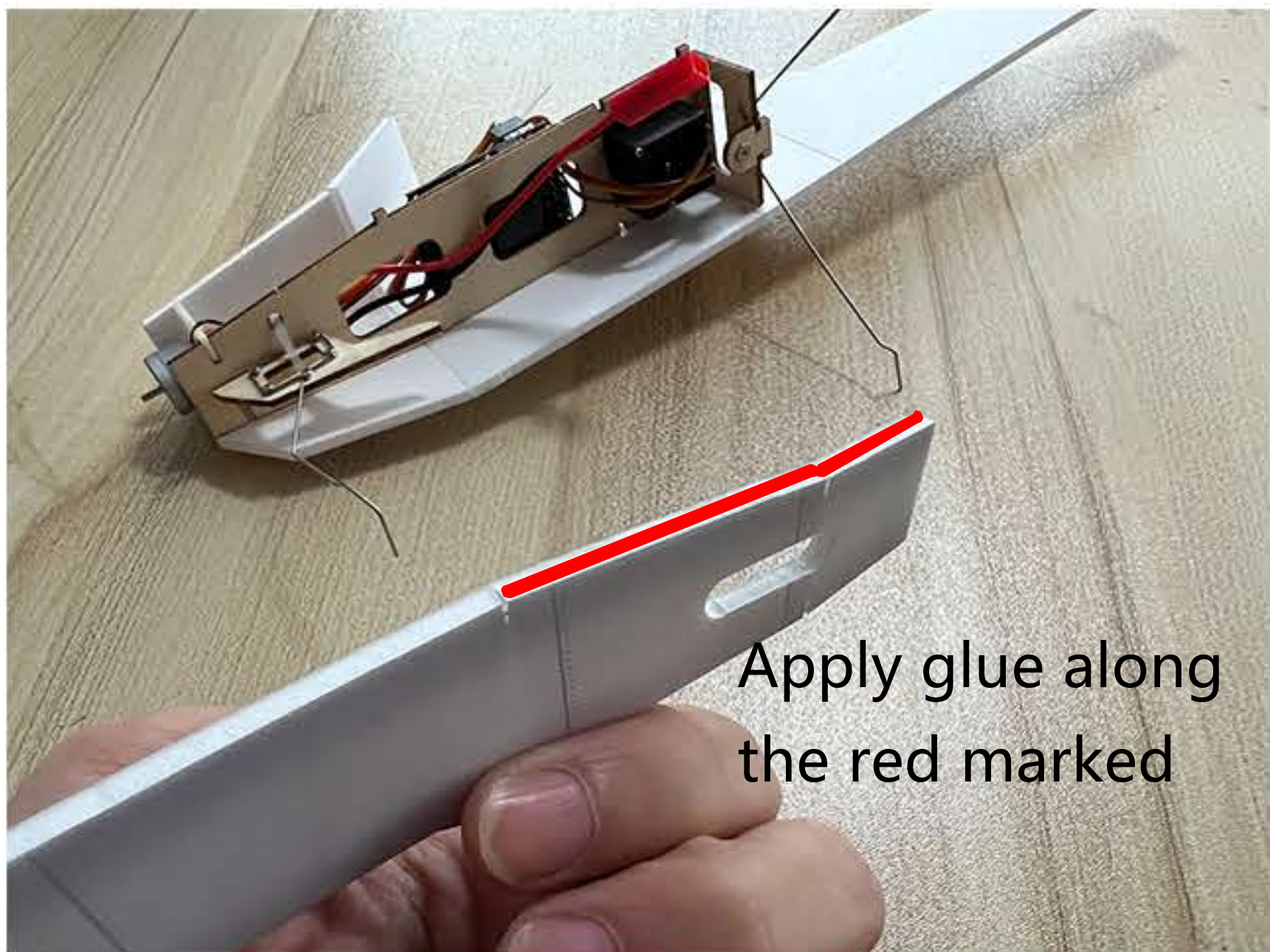
Cut to 45 degree angle



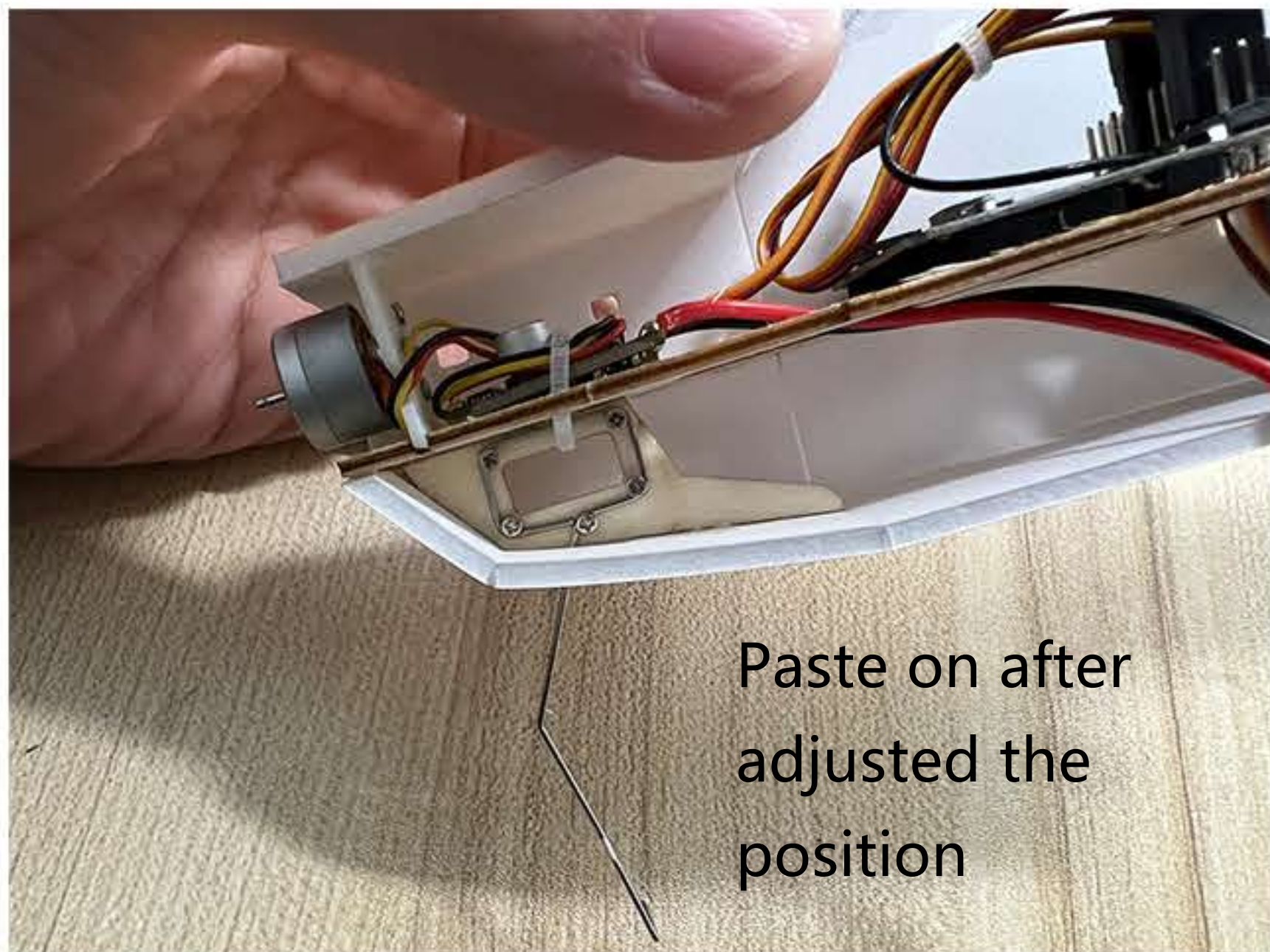
whether the comparison position is appropriate, mark the location of the glue



Apply glue along the red marked



Apply glue along the red marked



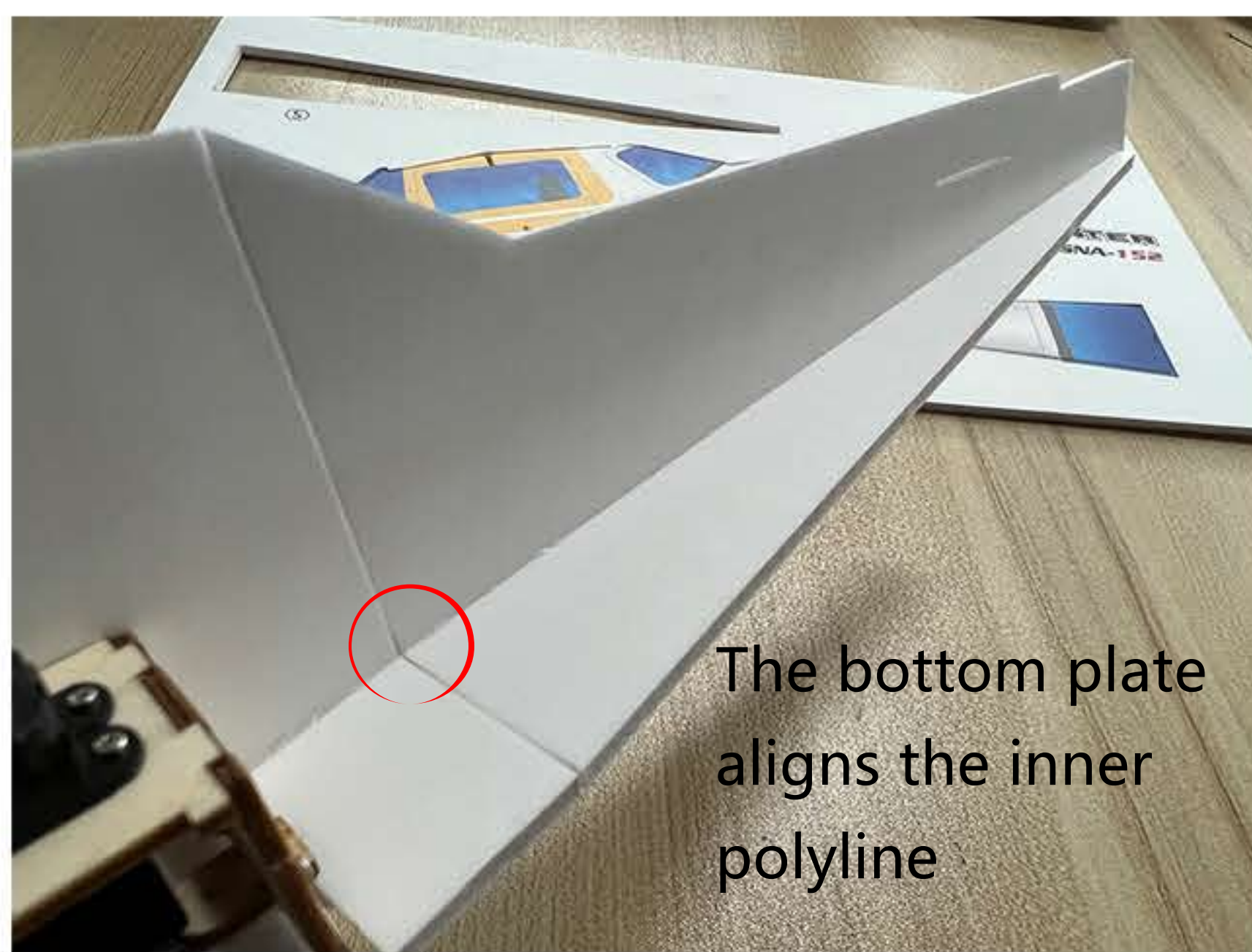
Paste on after adjusted the position

Tail upper plate and bottom plate assembly

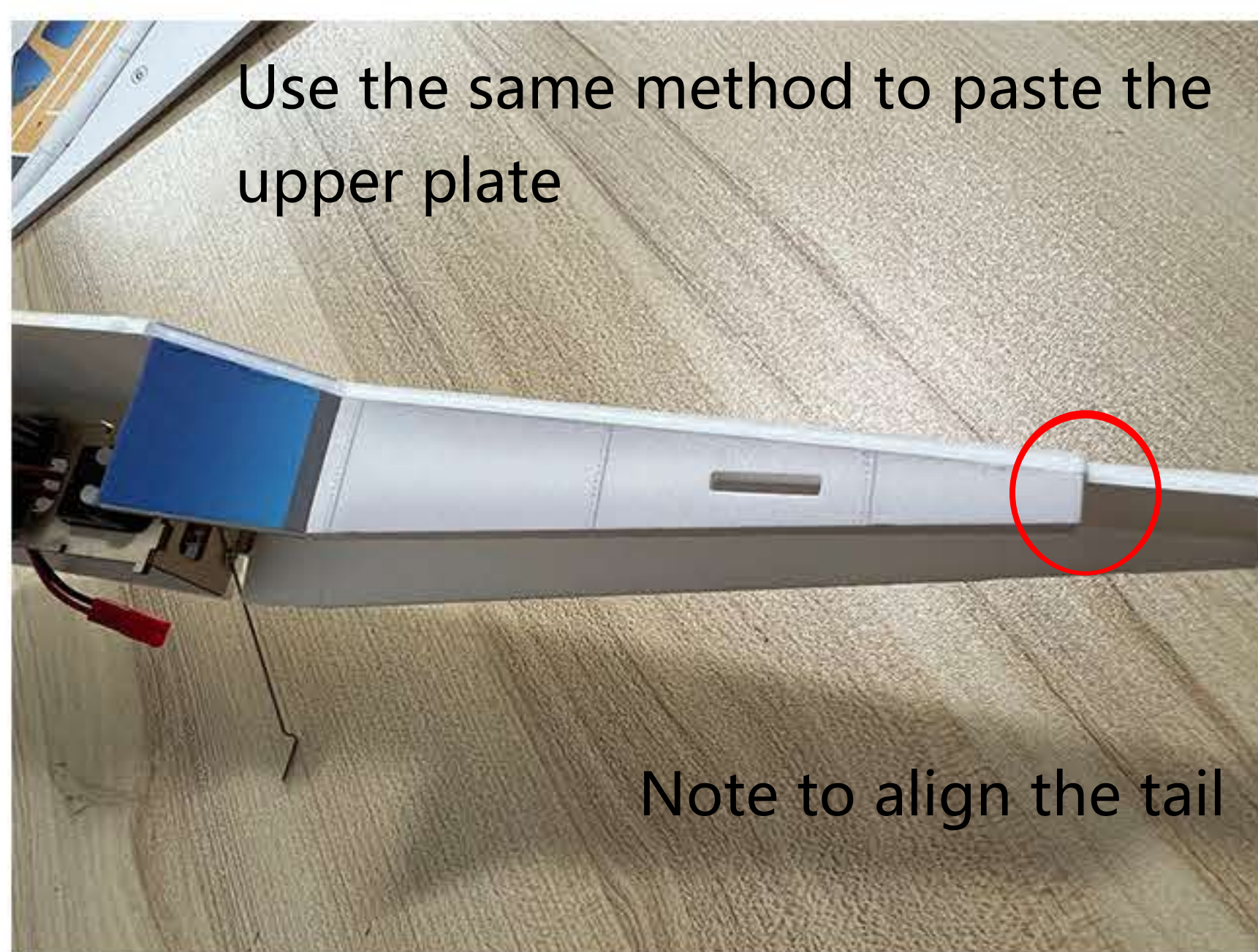
Take out No.5 and No.7 board, apply foam glue to the pasting position and adjust the position to paste



Apply glue along the red marked



The bottom plate aligns the inner polyline

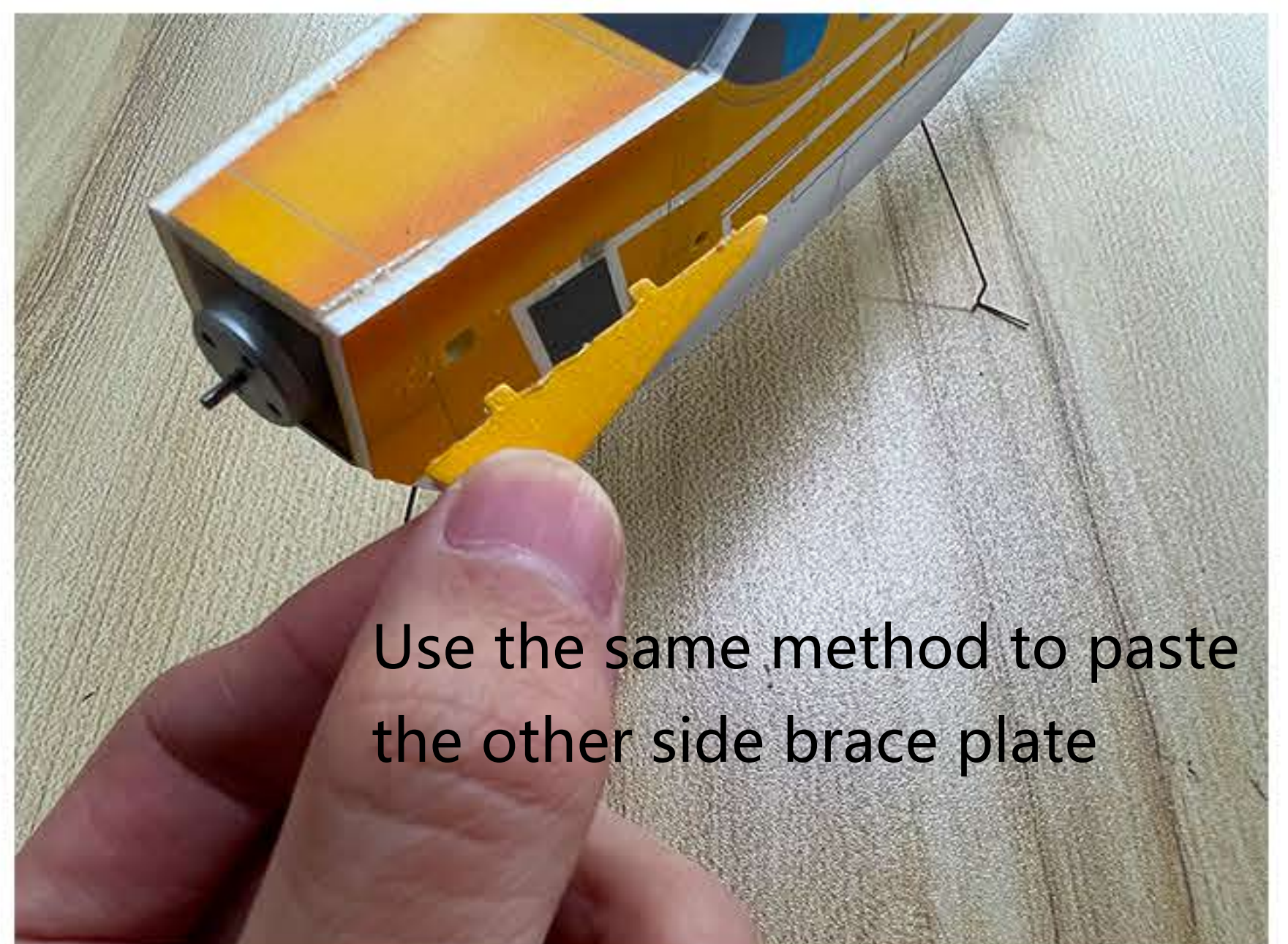
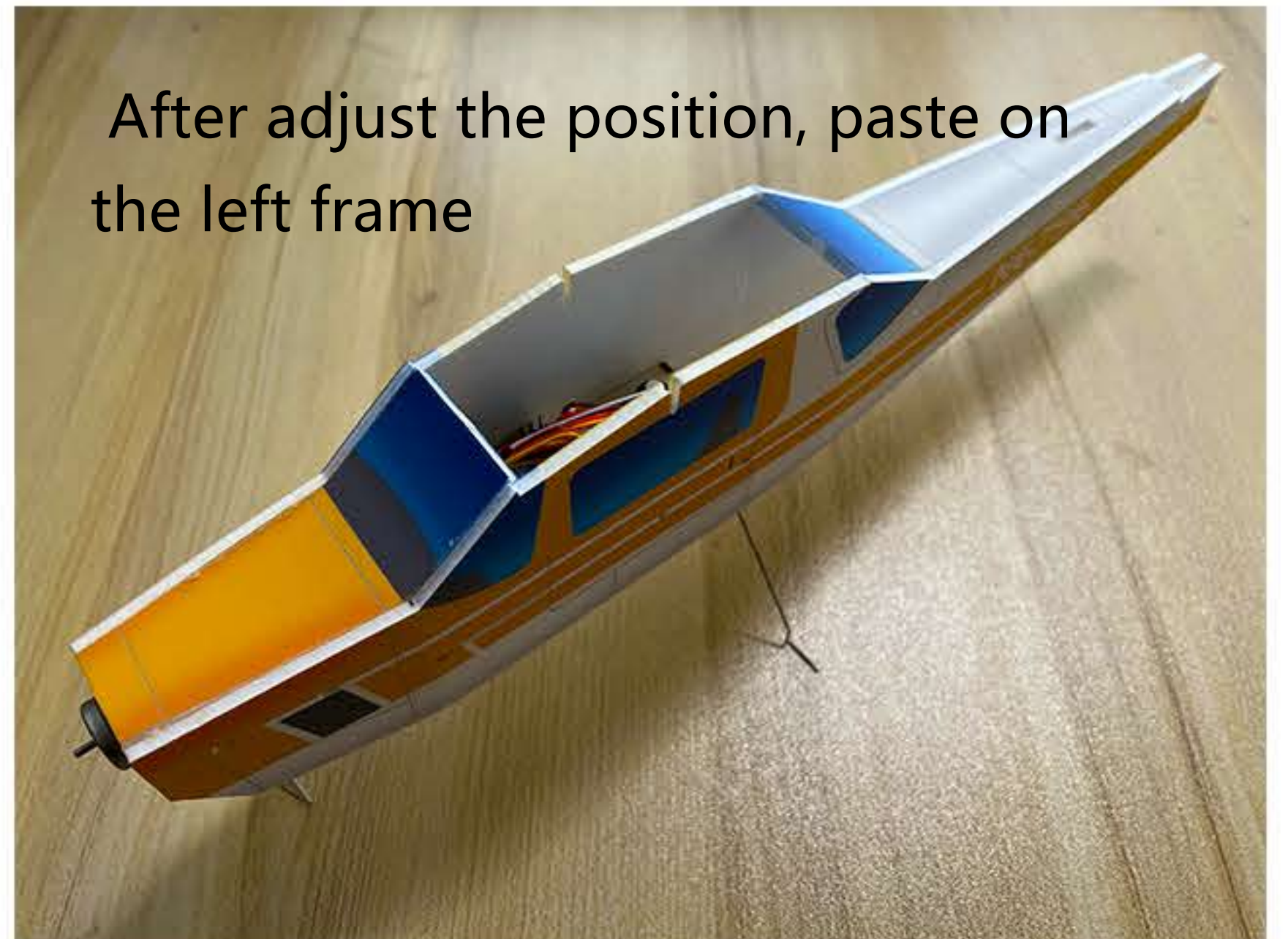
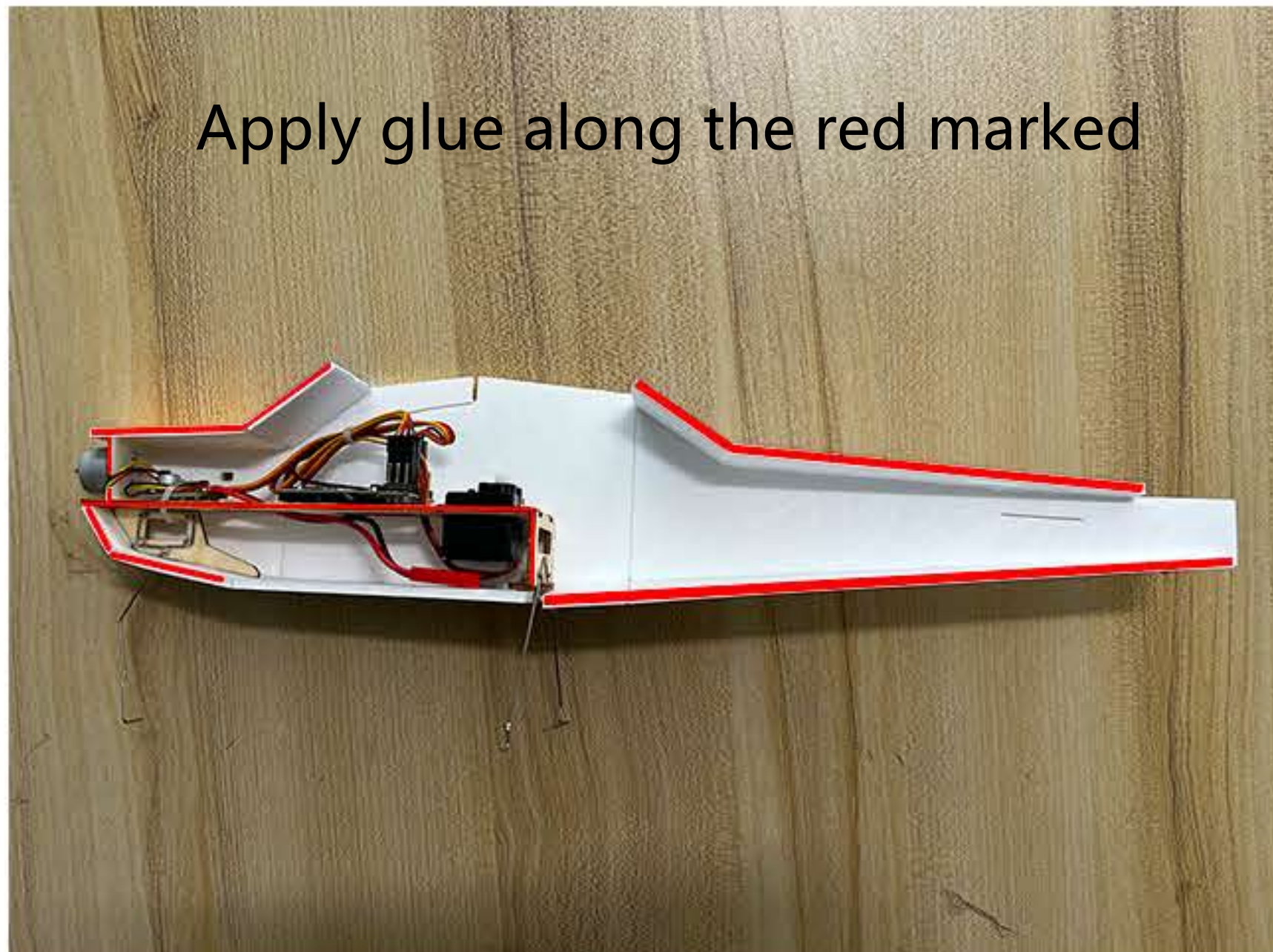


Use the same method to paste the upper plate

Note to align the tail

Left frame and frame brace plates assembly

Take out No.6 and No.11 board, apply glue to the paste position

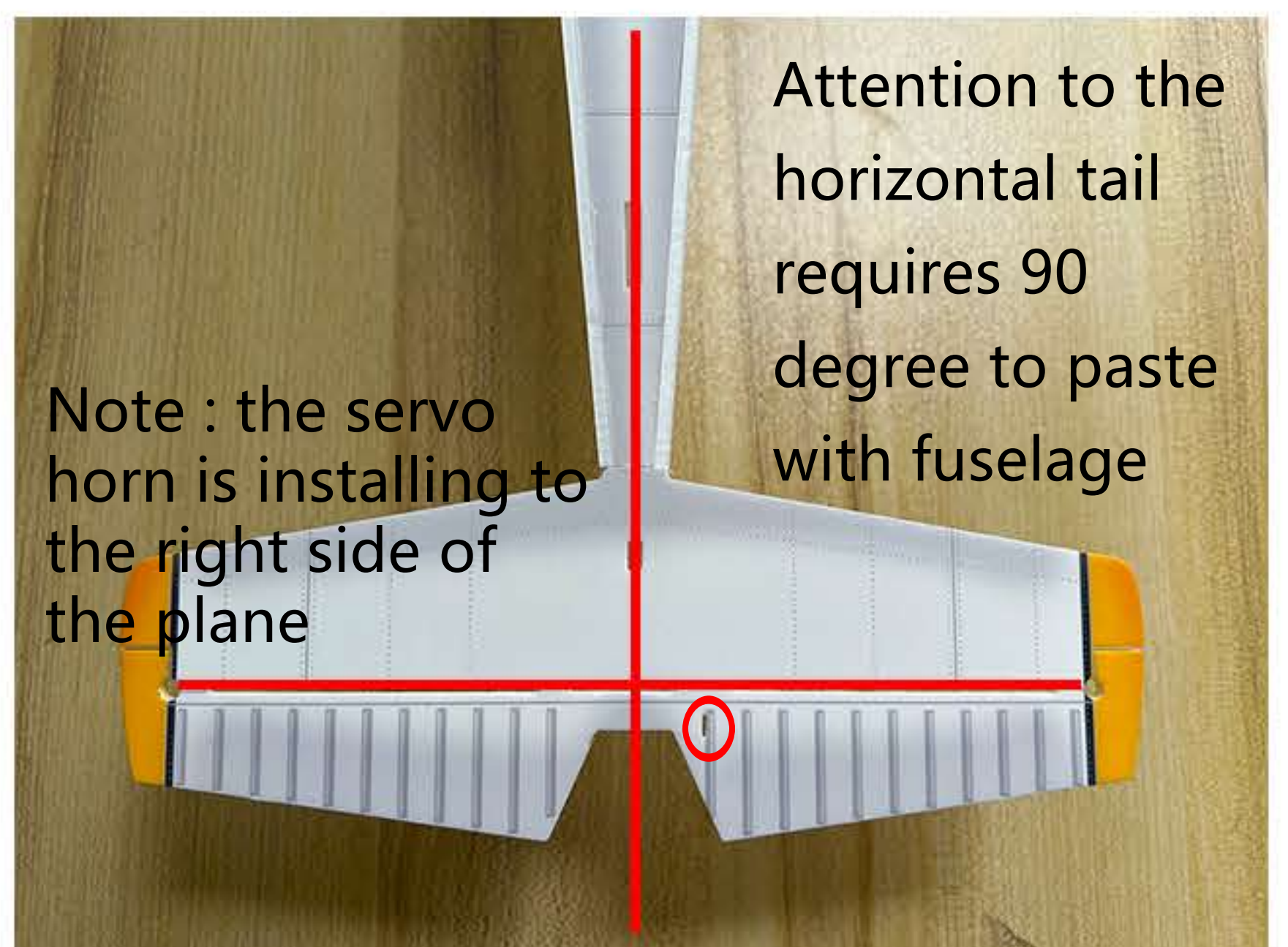
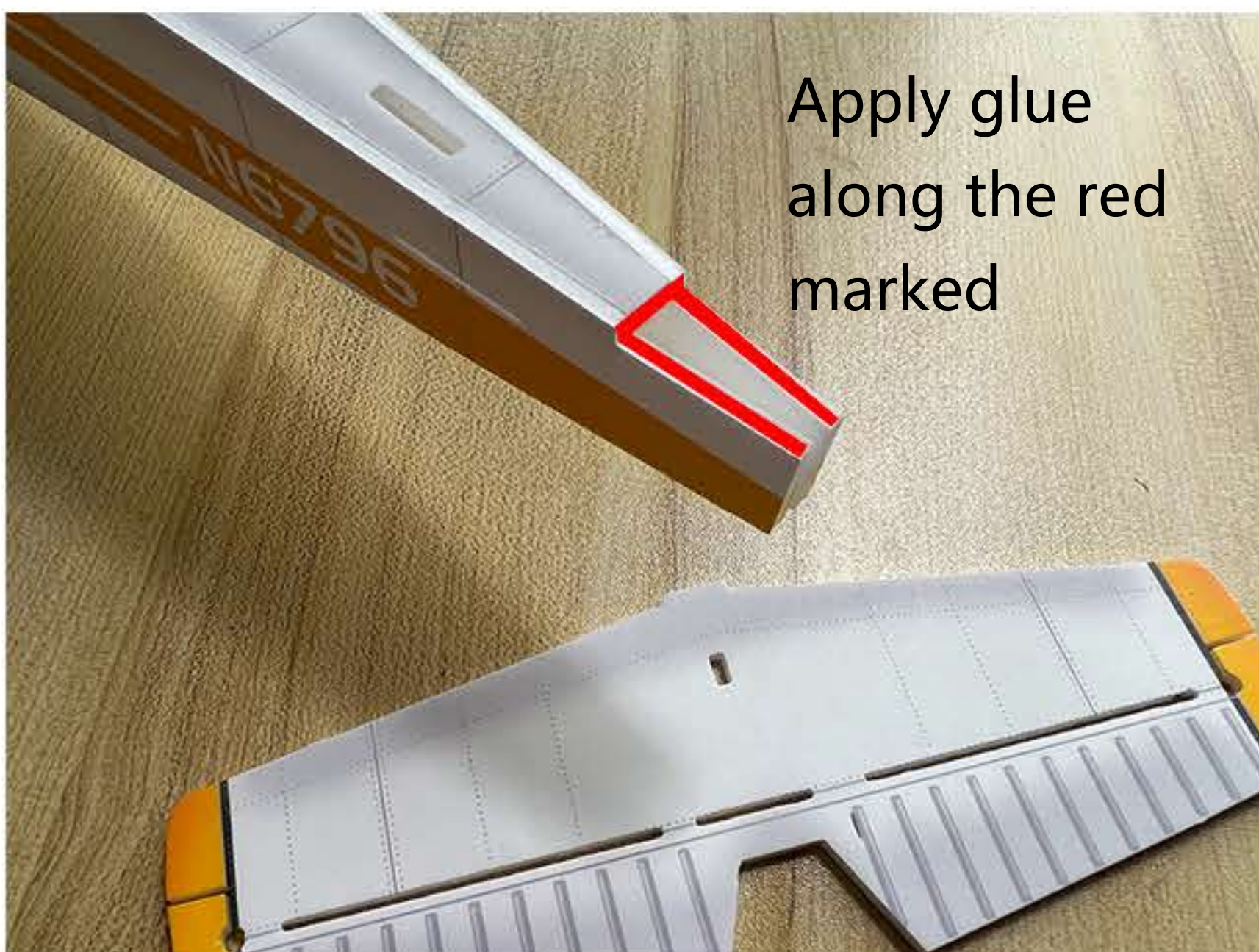
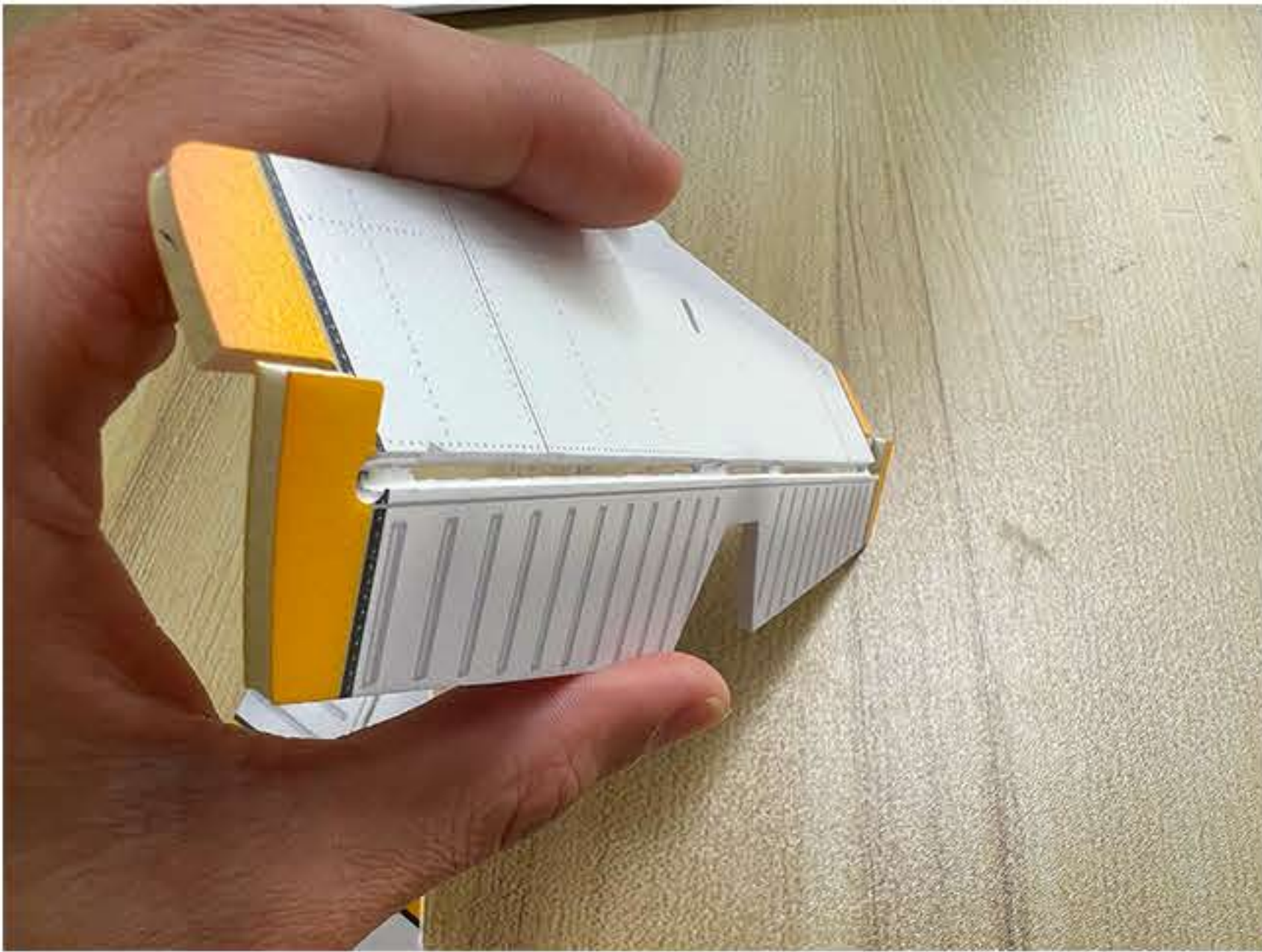


Horizontal tail and vertical tail assembly

Take out No.12 and No.8 board, cut the incision. The hinges of the rudder surface have been pre-processed, and may be hard. You can swing the surface left and right with your hands to soften it when necessary.

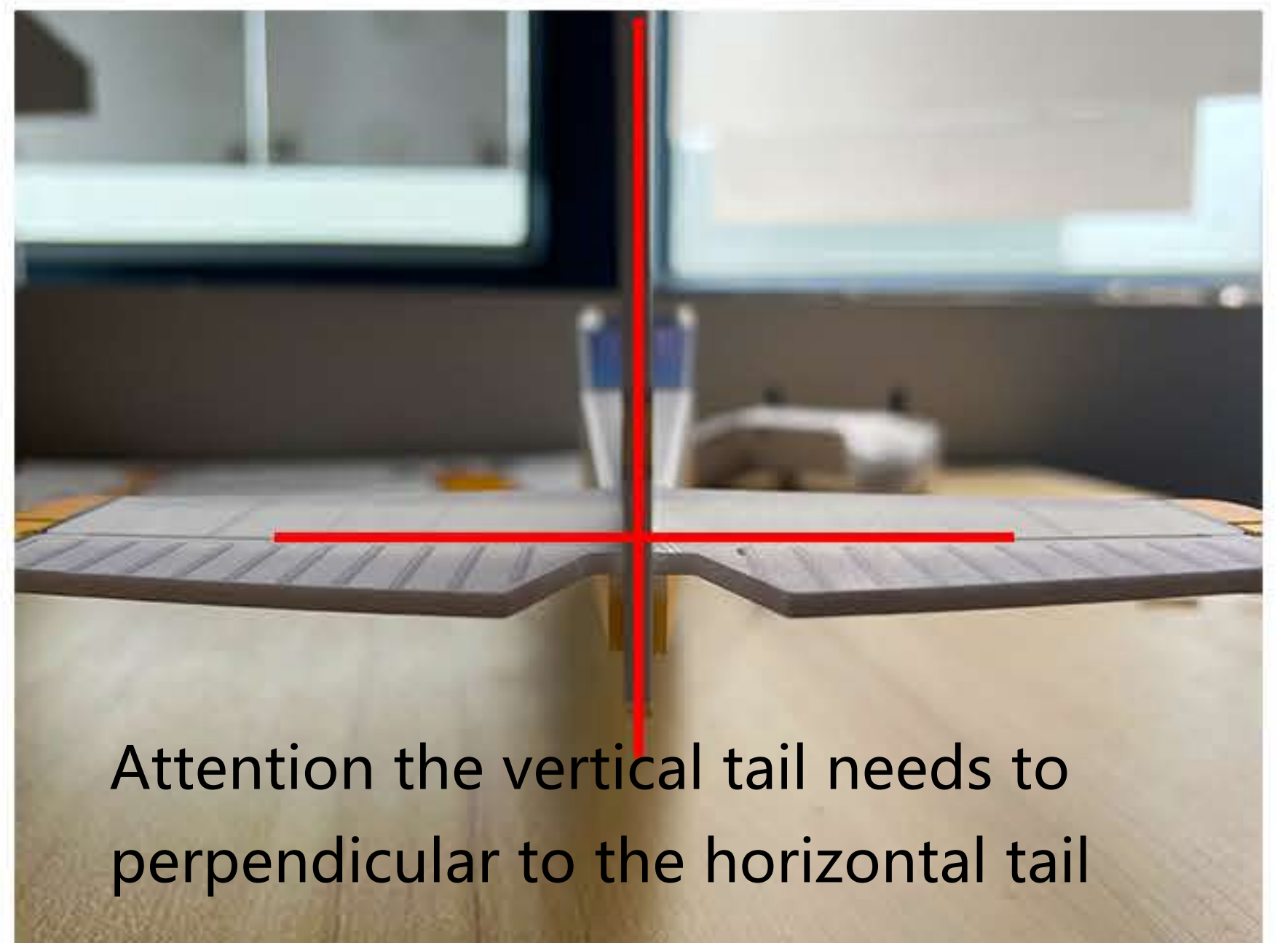
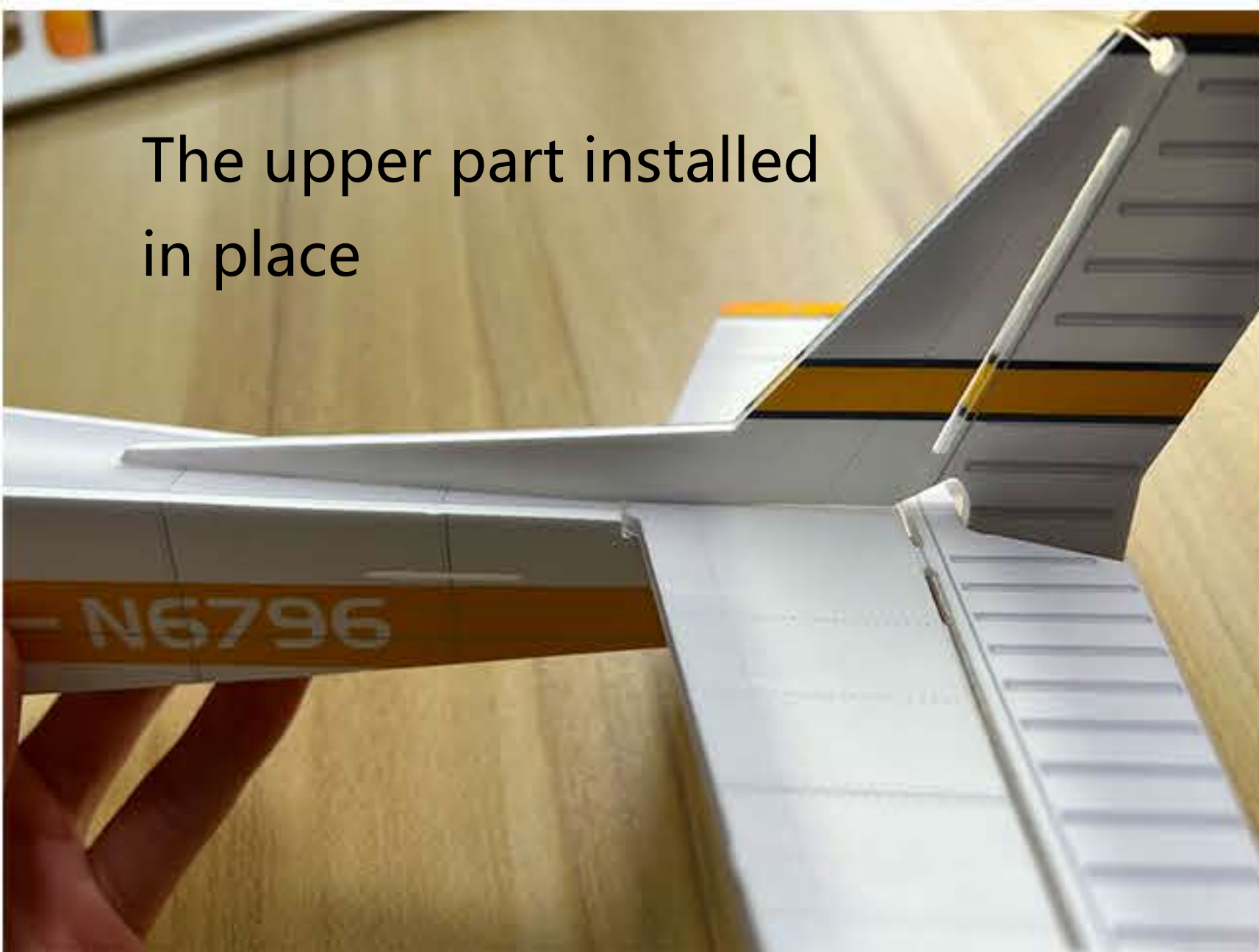


Swing the surface left and right with your hands to soften it when necessary.



Apply glue to the vertical tail





Servo horn assembly

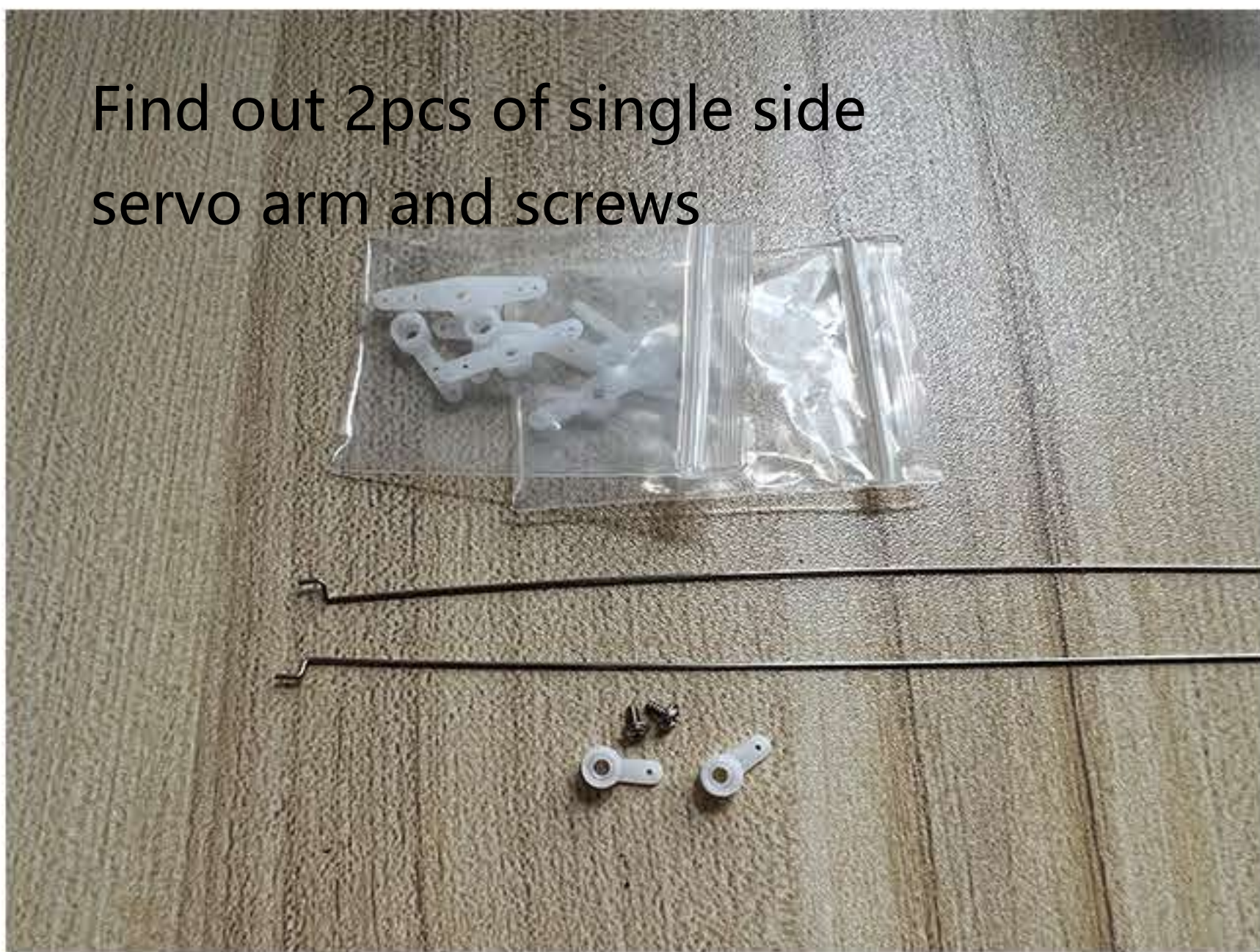
Take out the servo horn, apply some glue to it





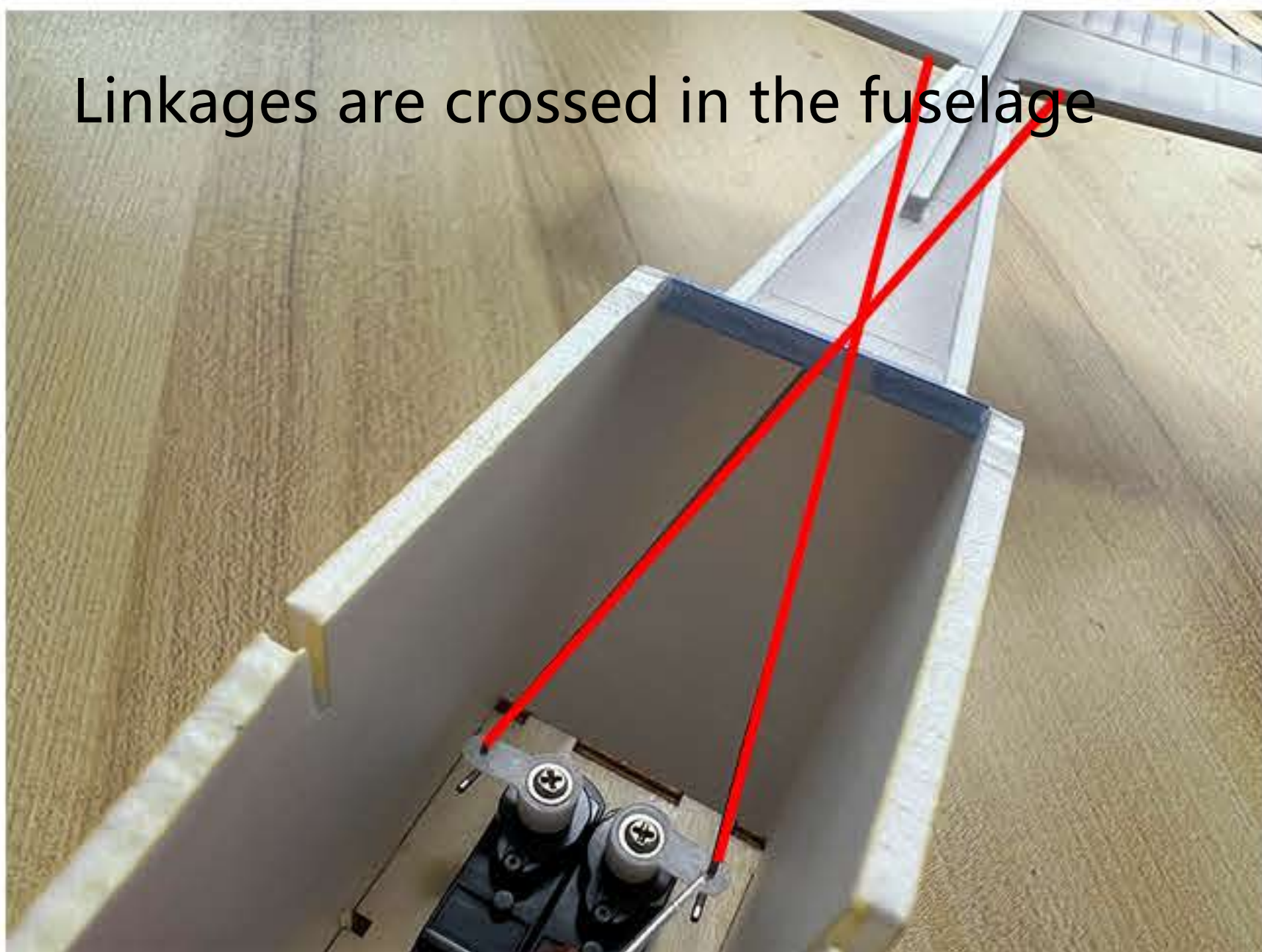
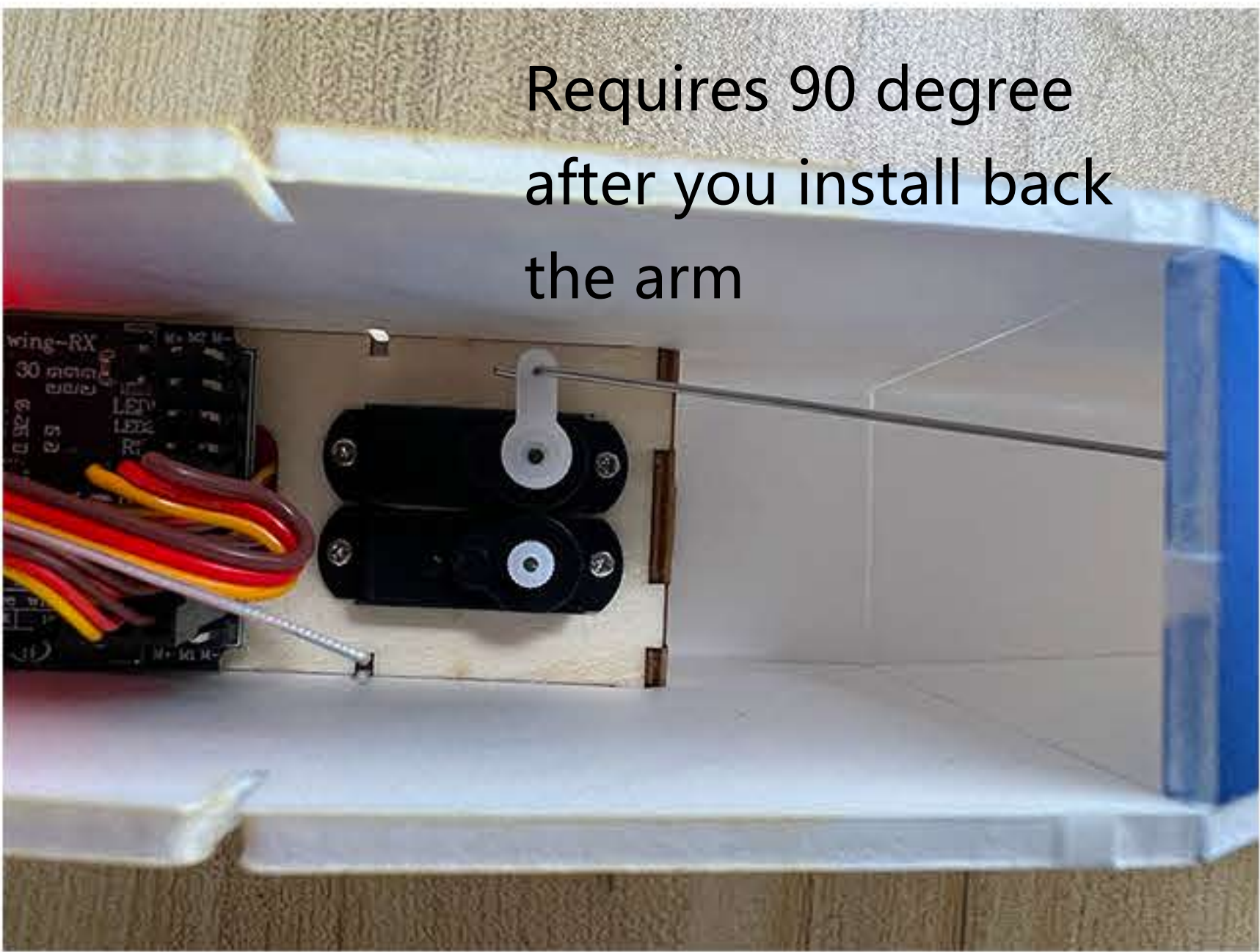
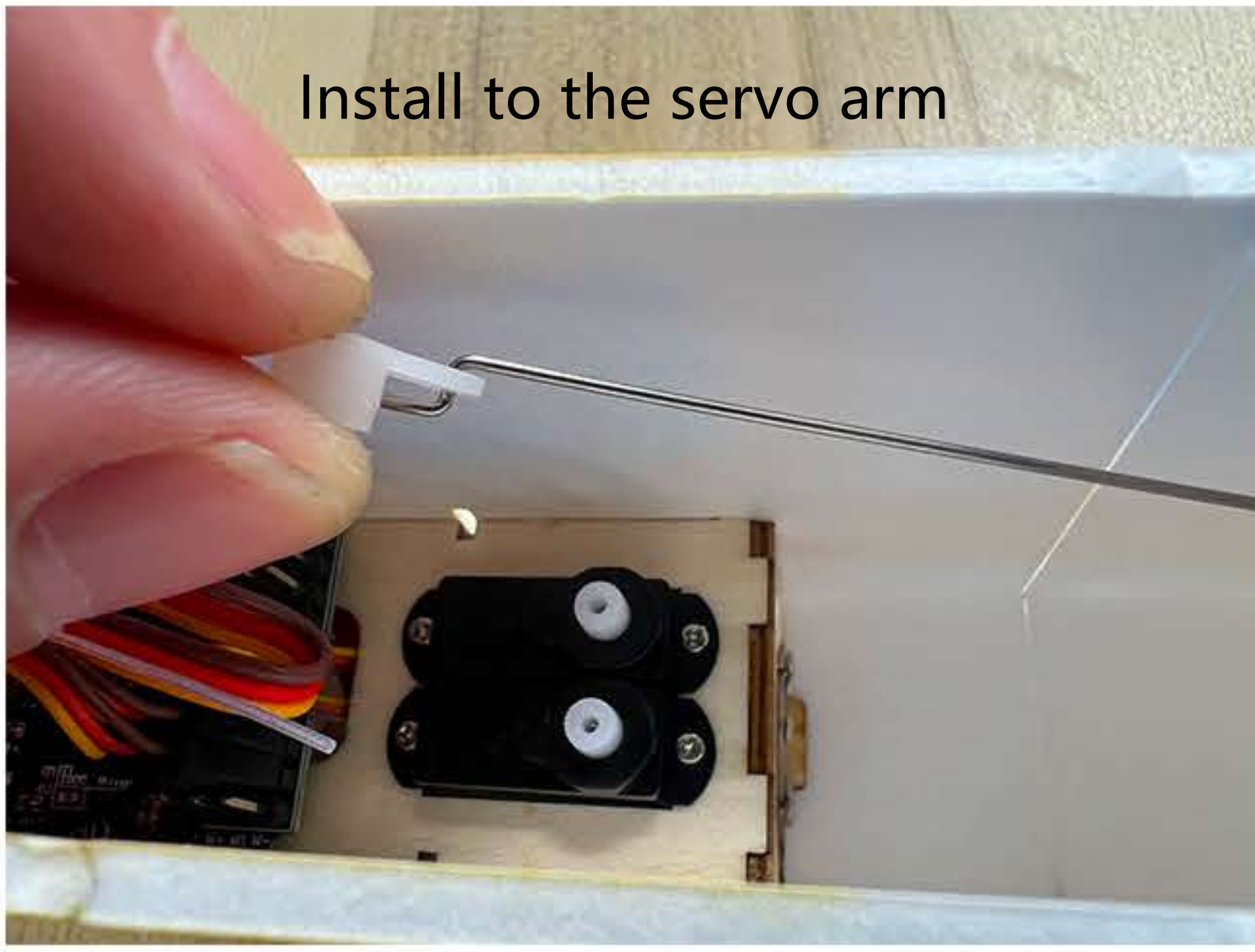
Linkage installation

The linkage is long, and it may be bent and deformed during packaging. It can be straightened by hand

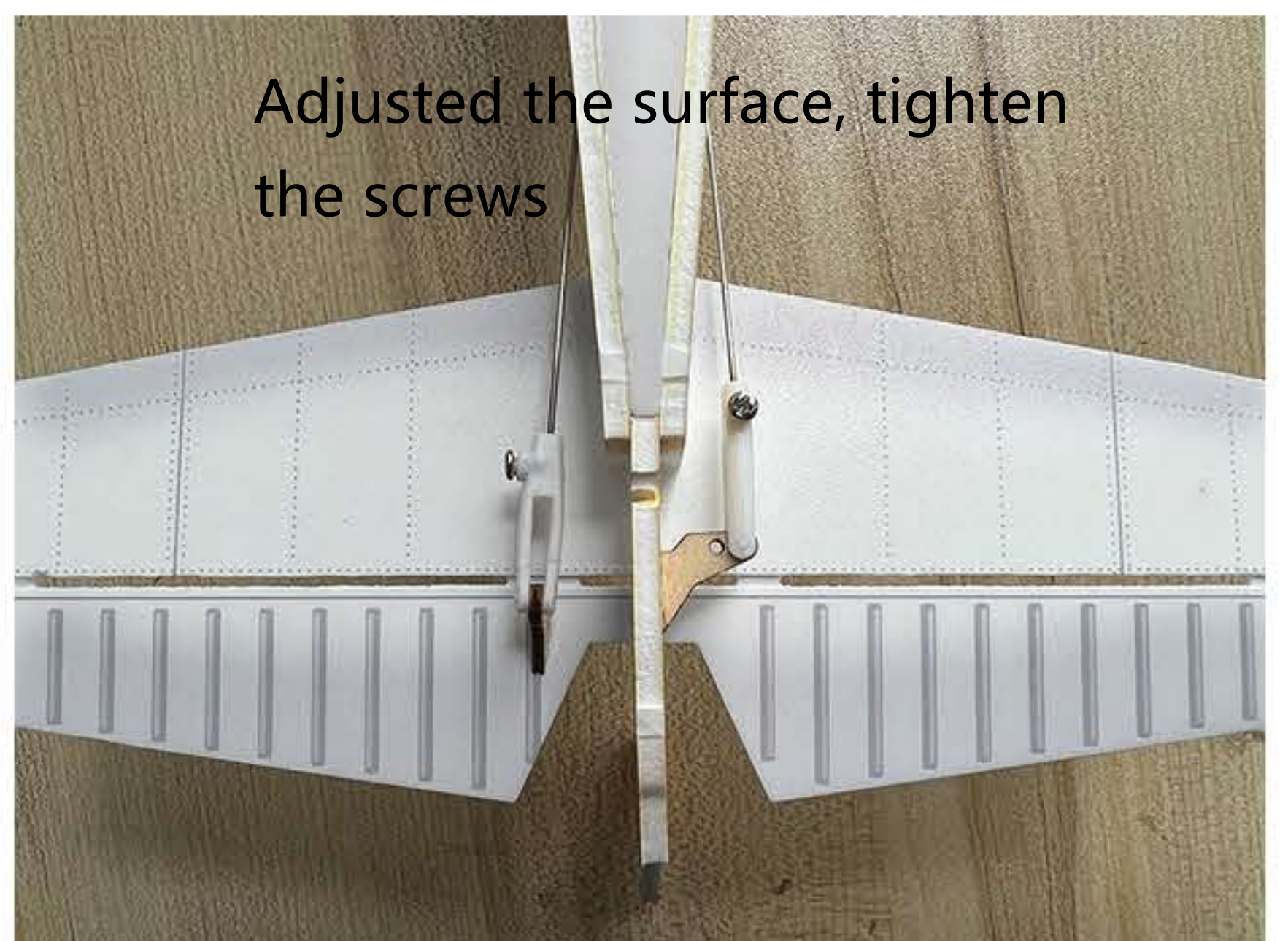


Power on the aircraft, servo arm will returns to the neutral point





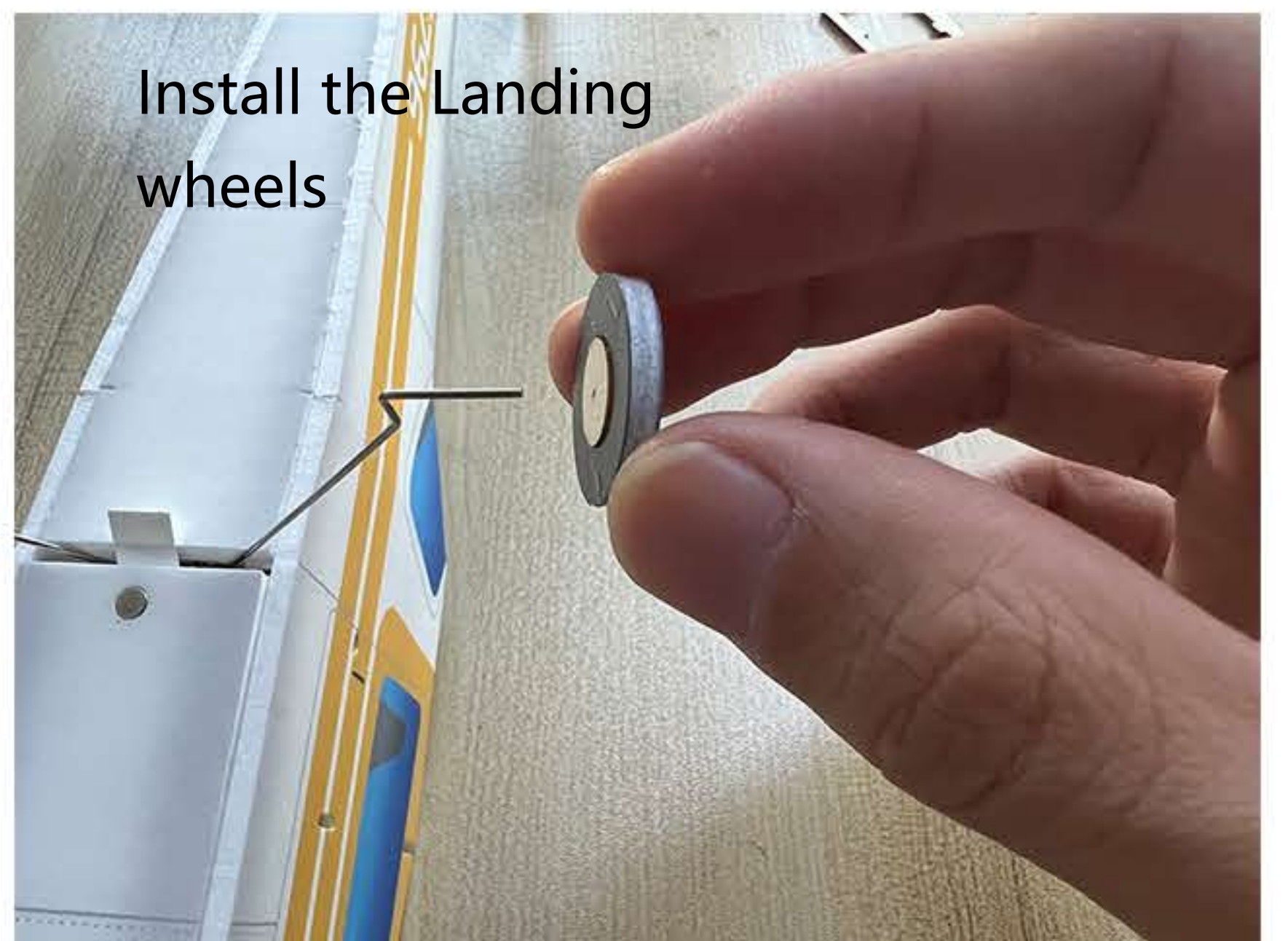
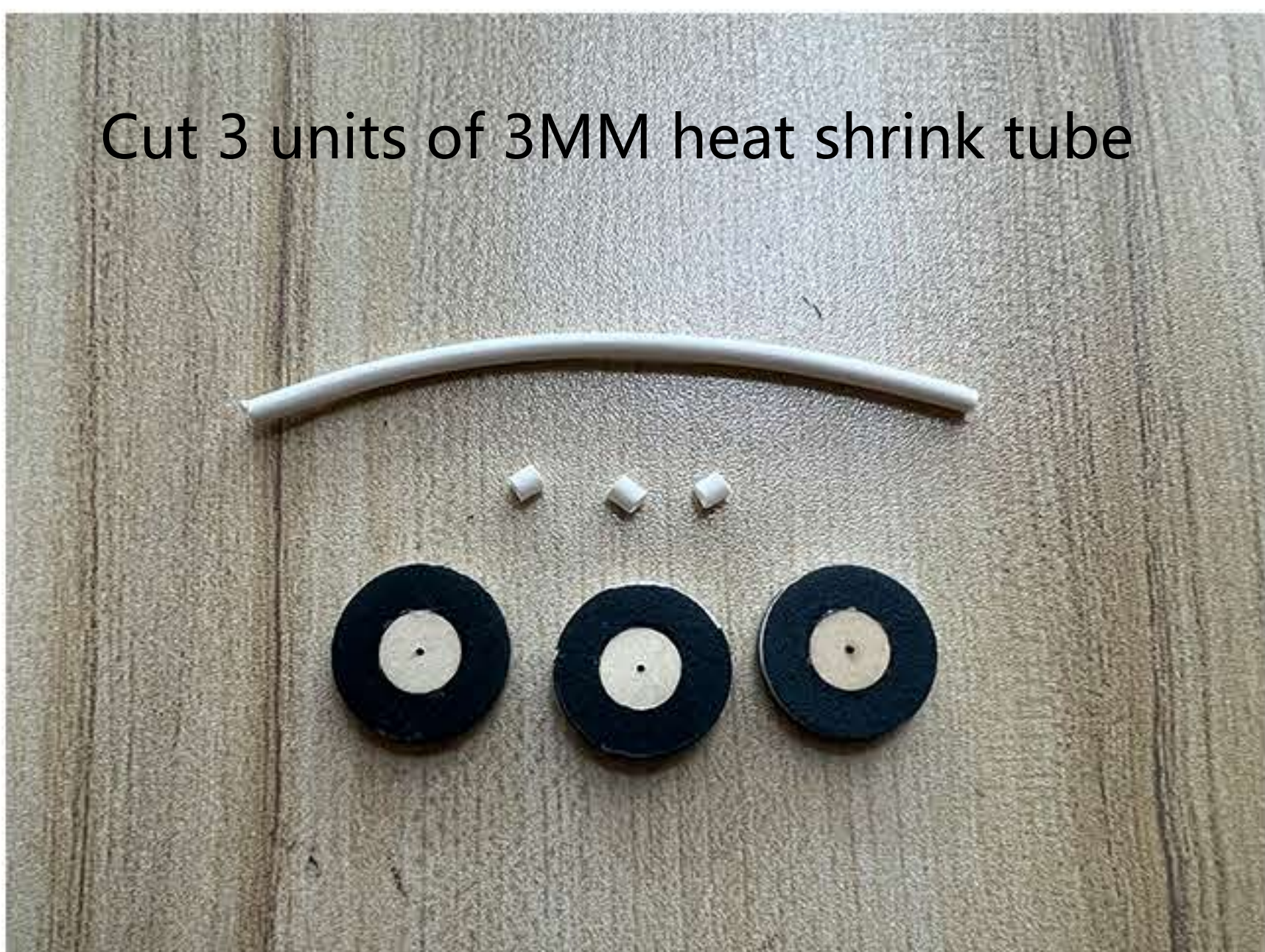
Chuck assembly



Landing wheels assembly

Take out the No.9 board and wheel axle



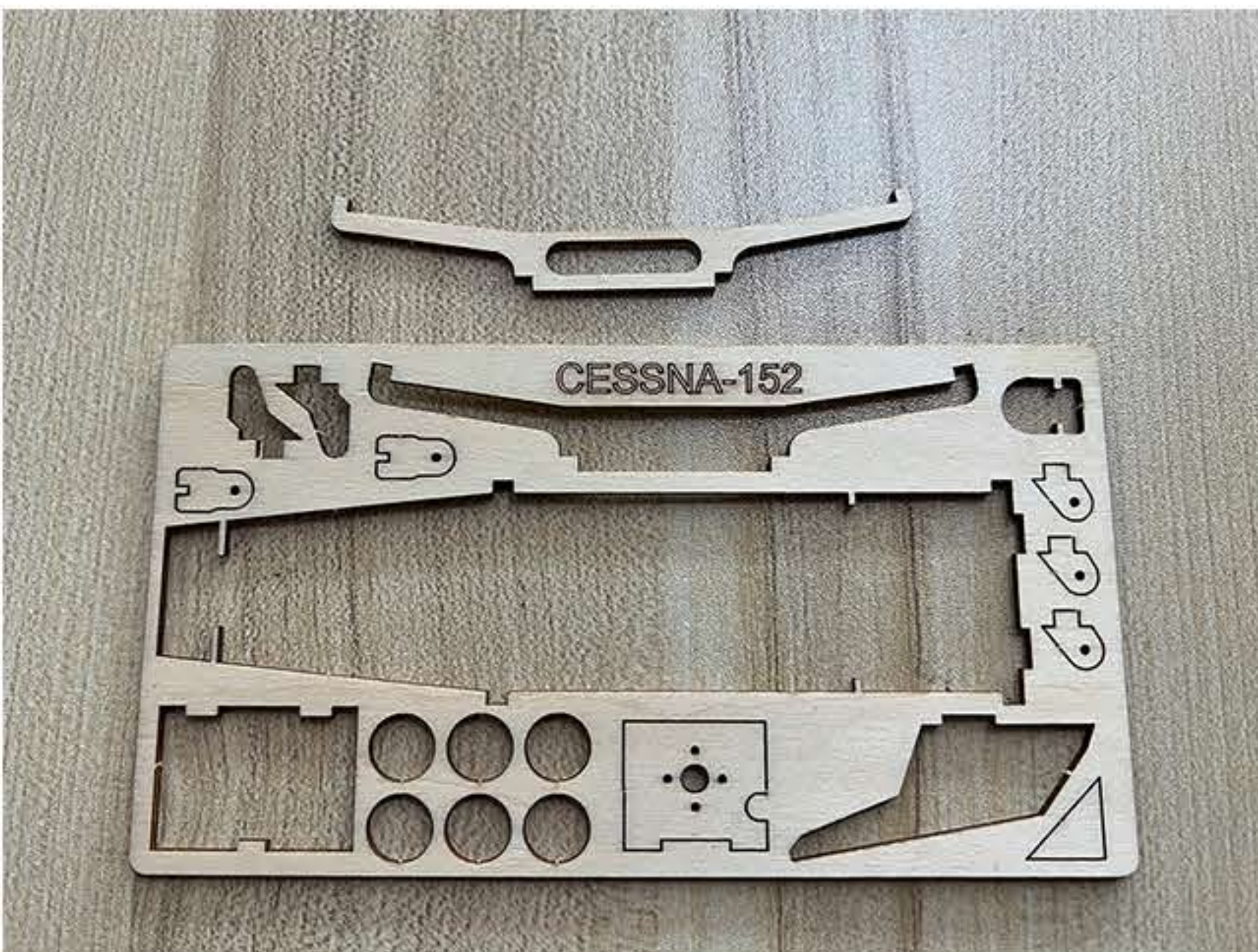


Put on the heat shrinkable tube, do not use fire shrink heat shrink tube, you can use an electric soldering iron or hot metal sheet to iron. Install all three wheels in the same way

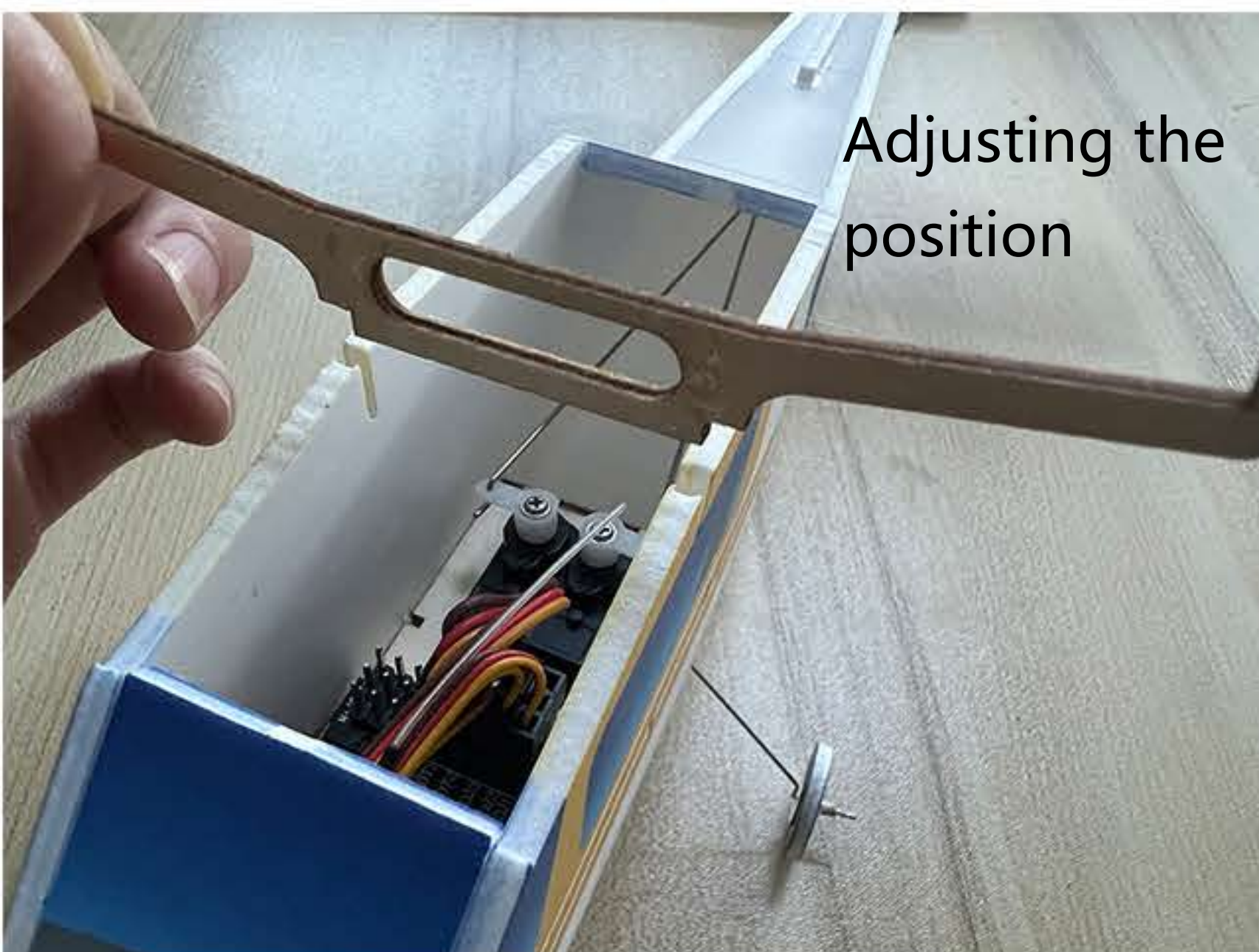


Wings assembly

Take out the wing mounting plate



Apply glue along the red marked

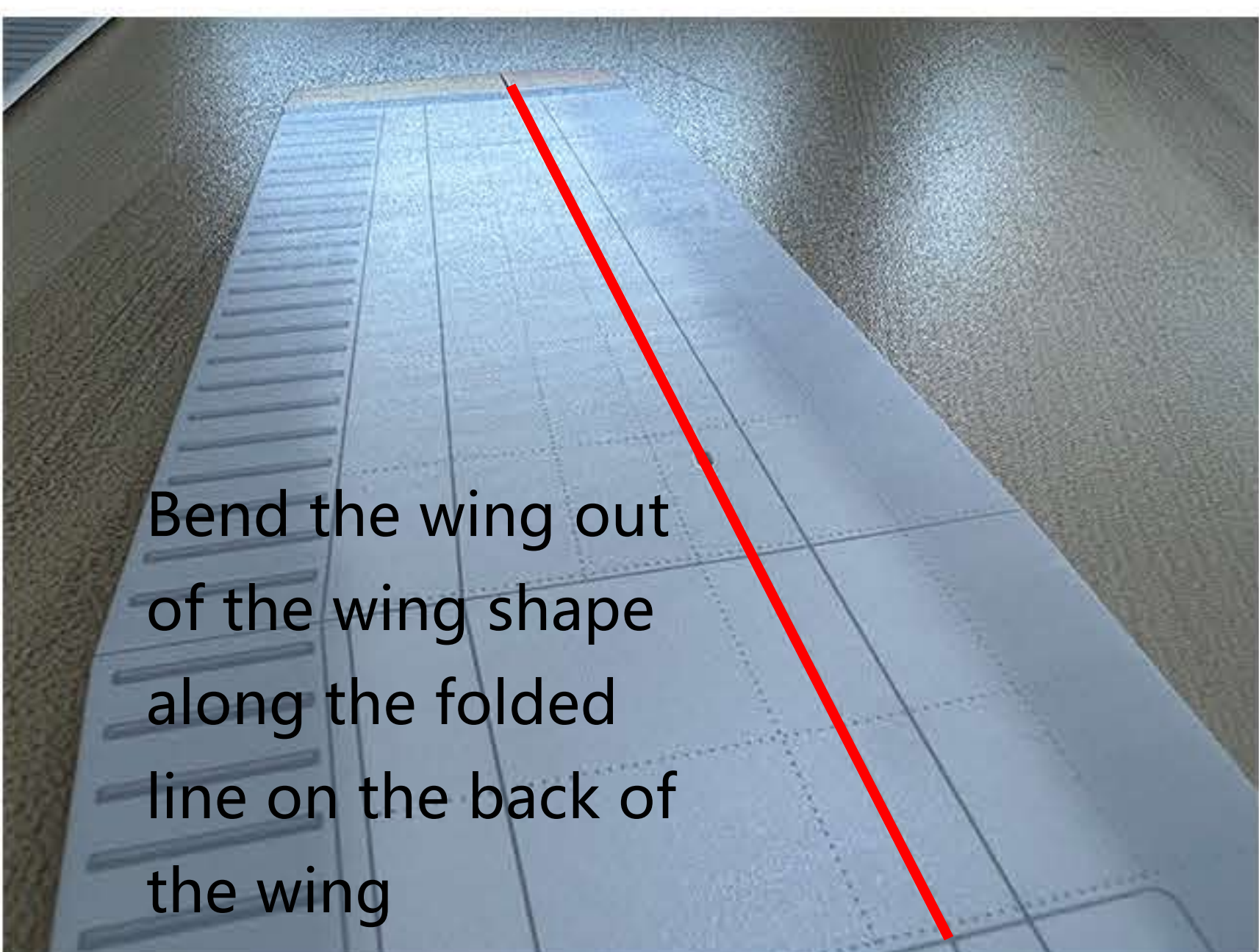
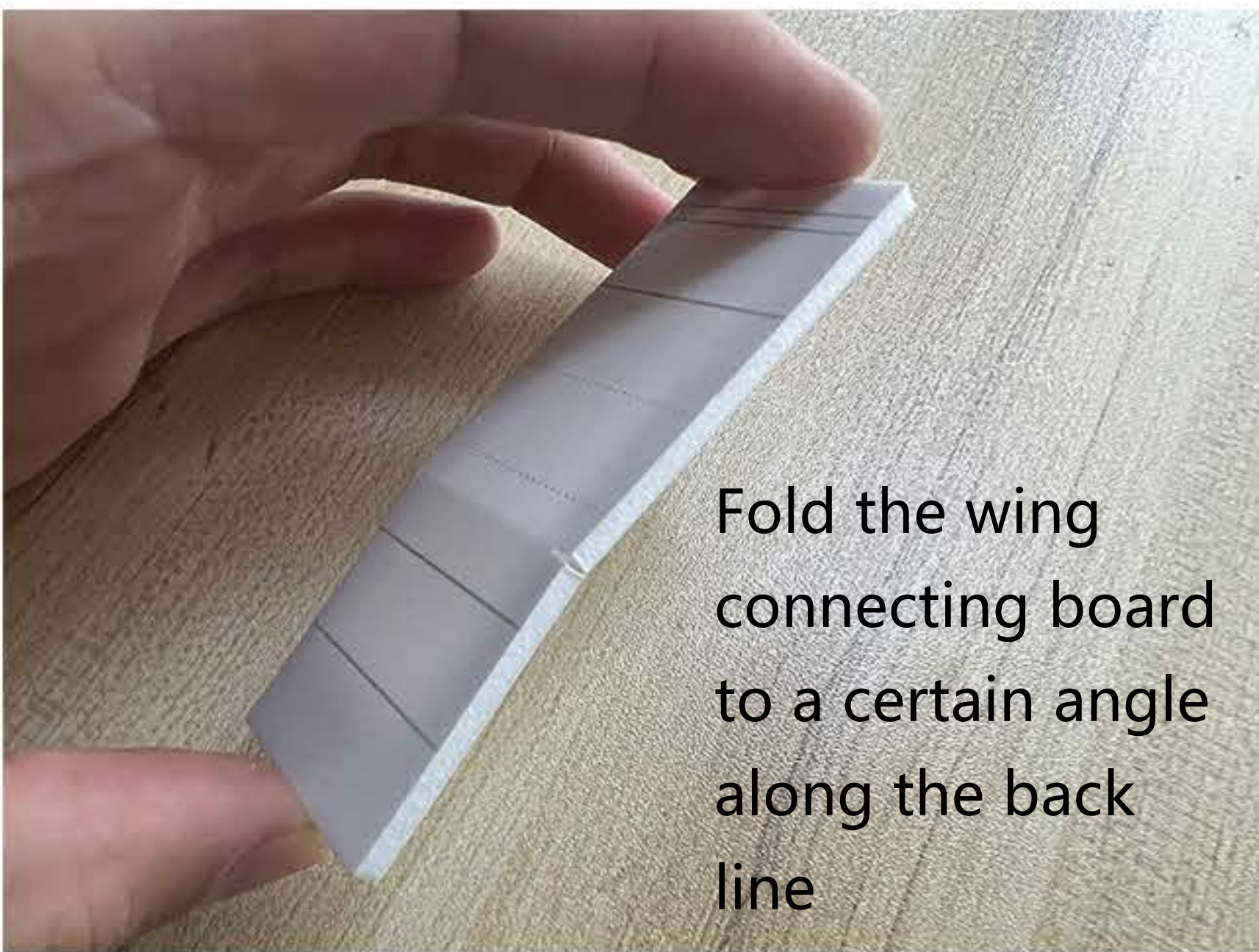
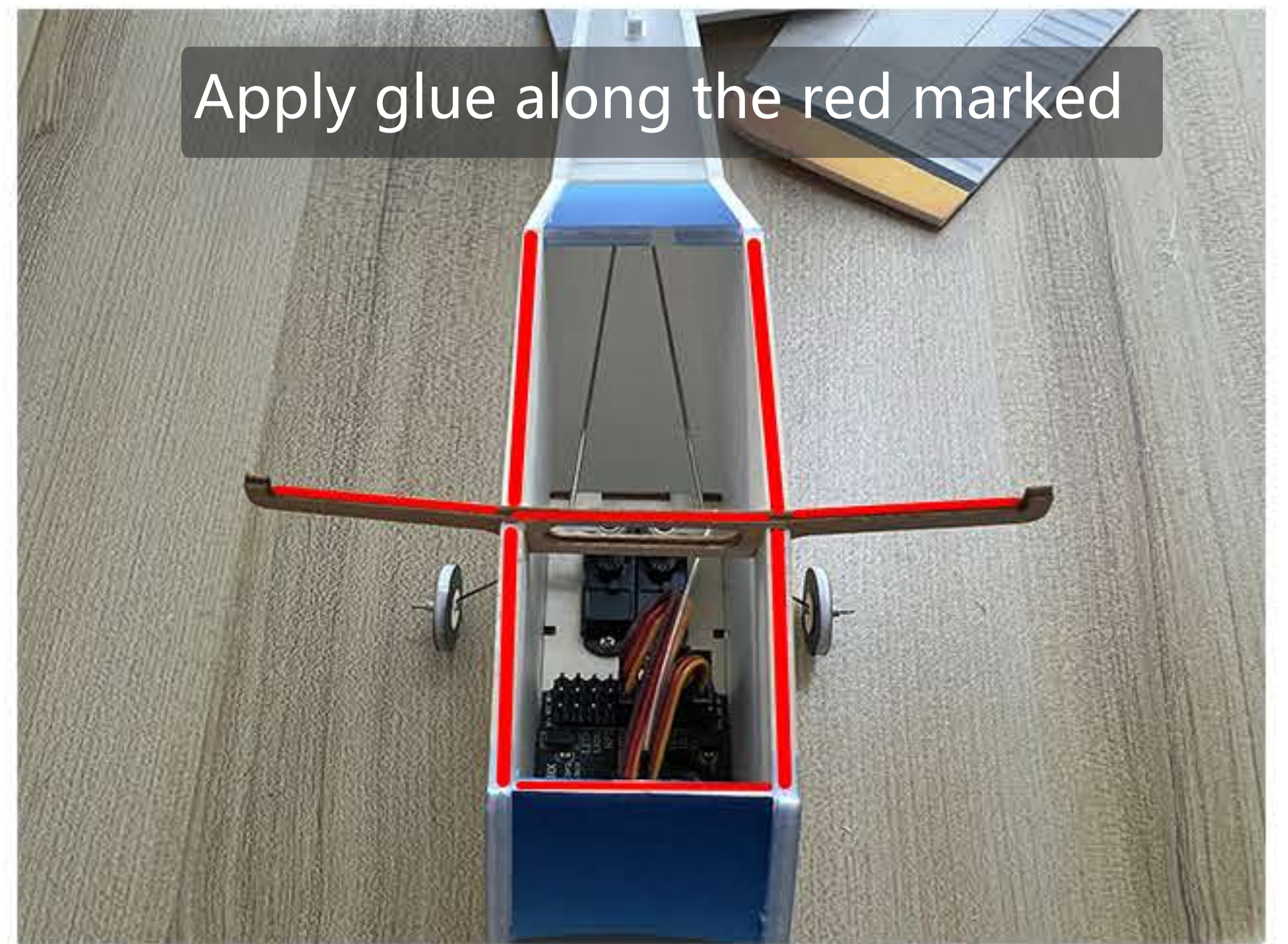


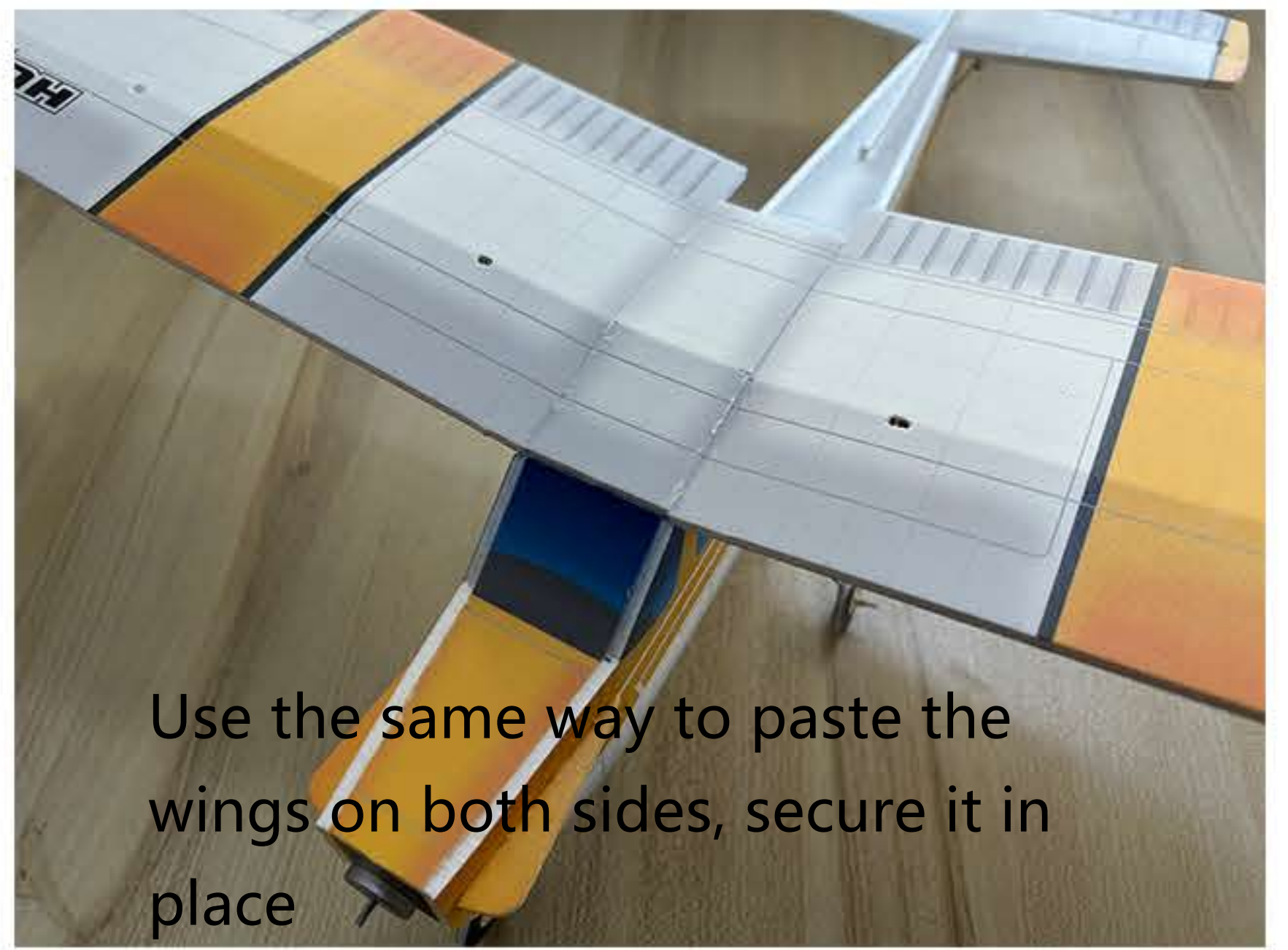
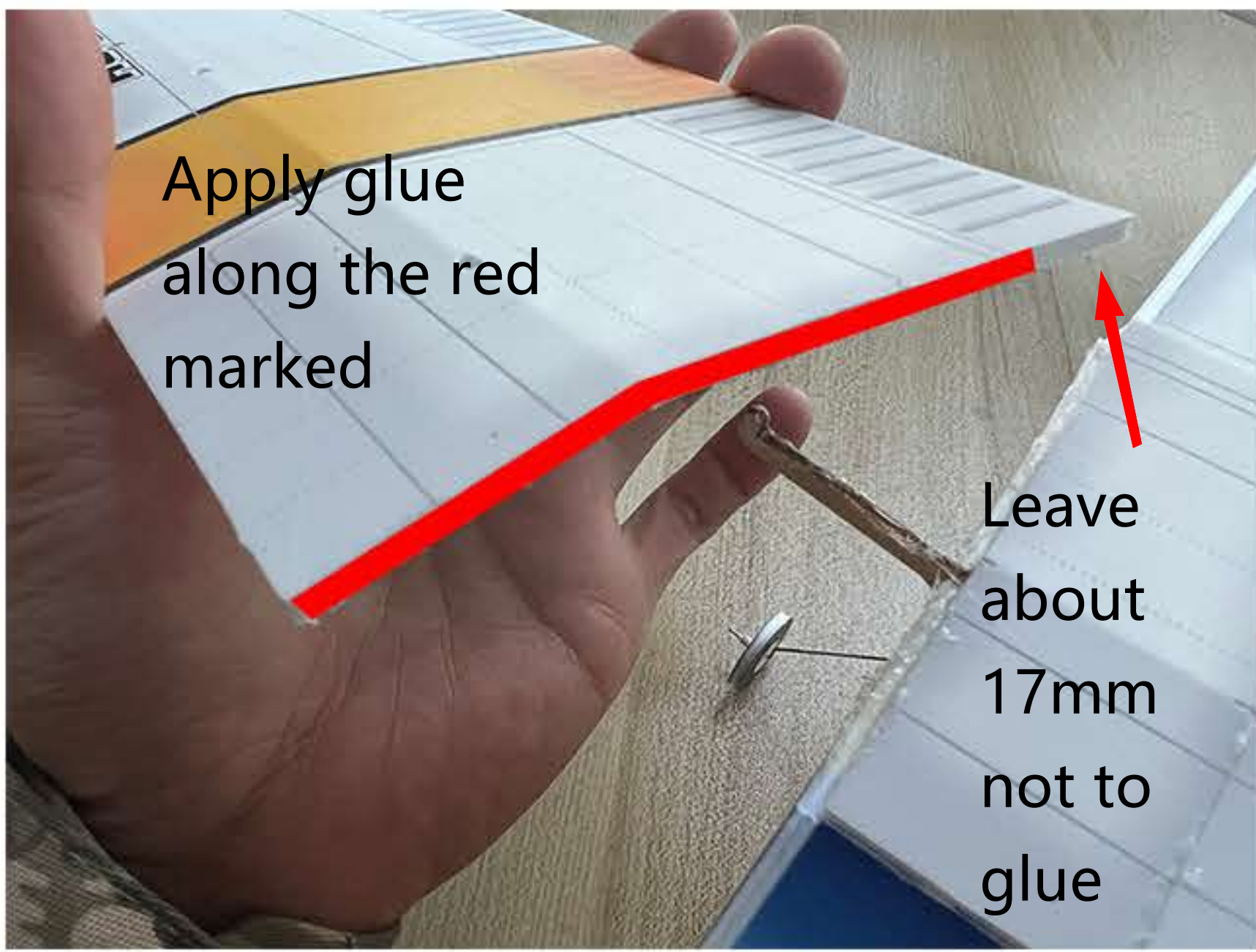
Adjusting the position



Secure it in place

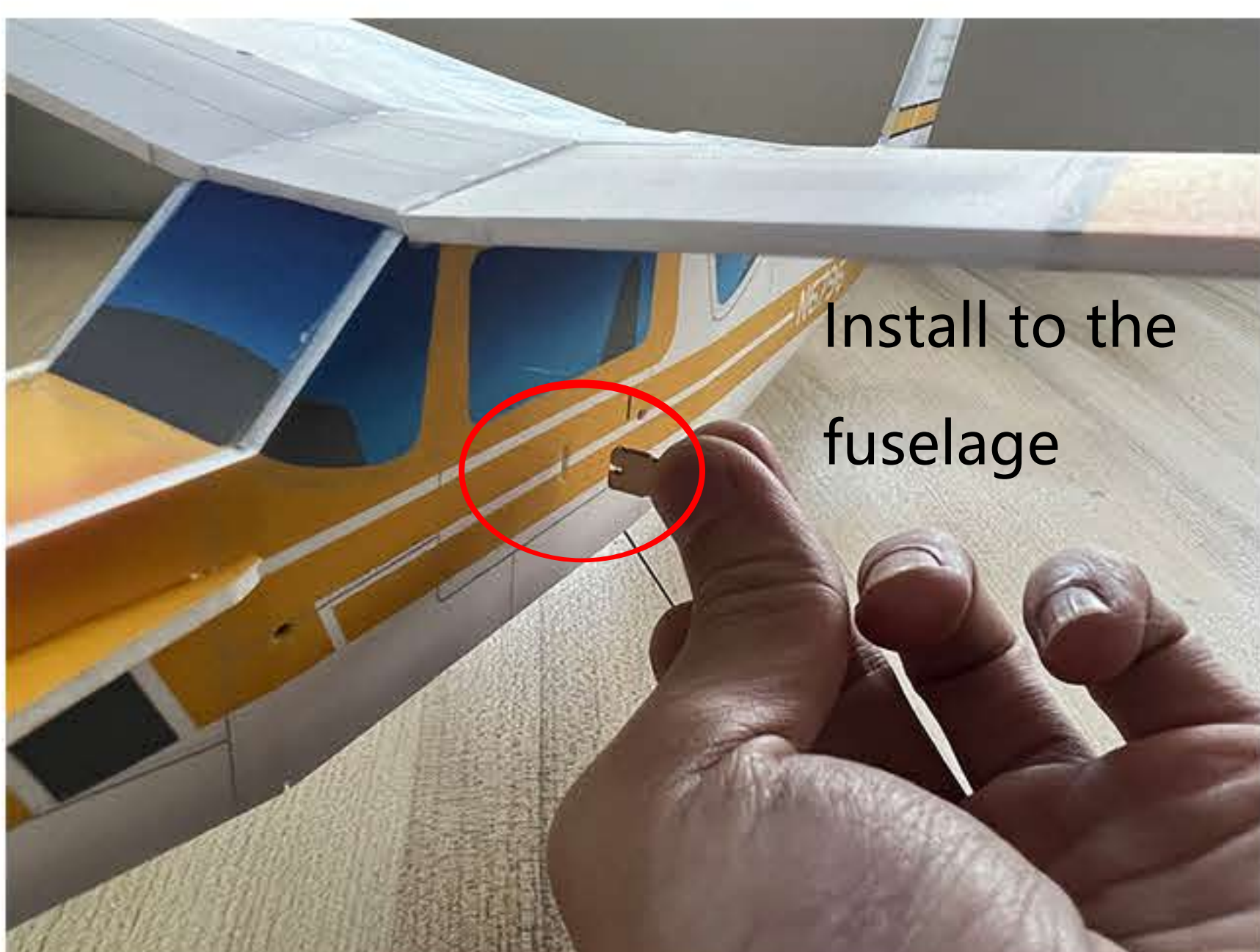
Take out No.10、 13、 14 board.

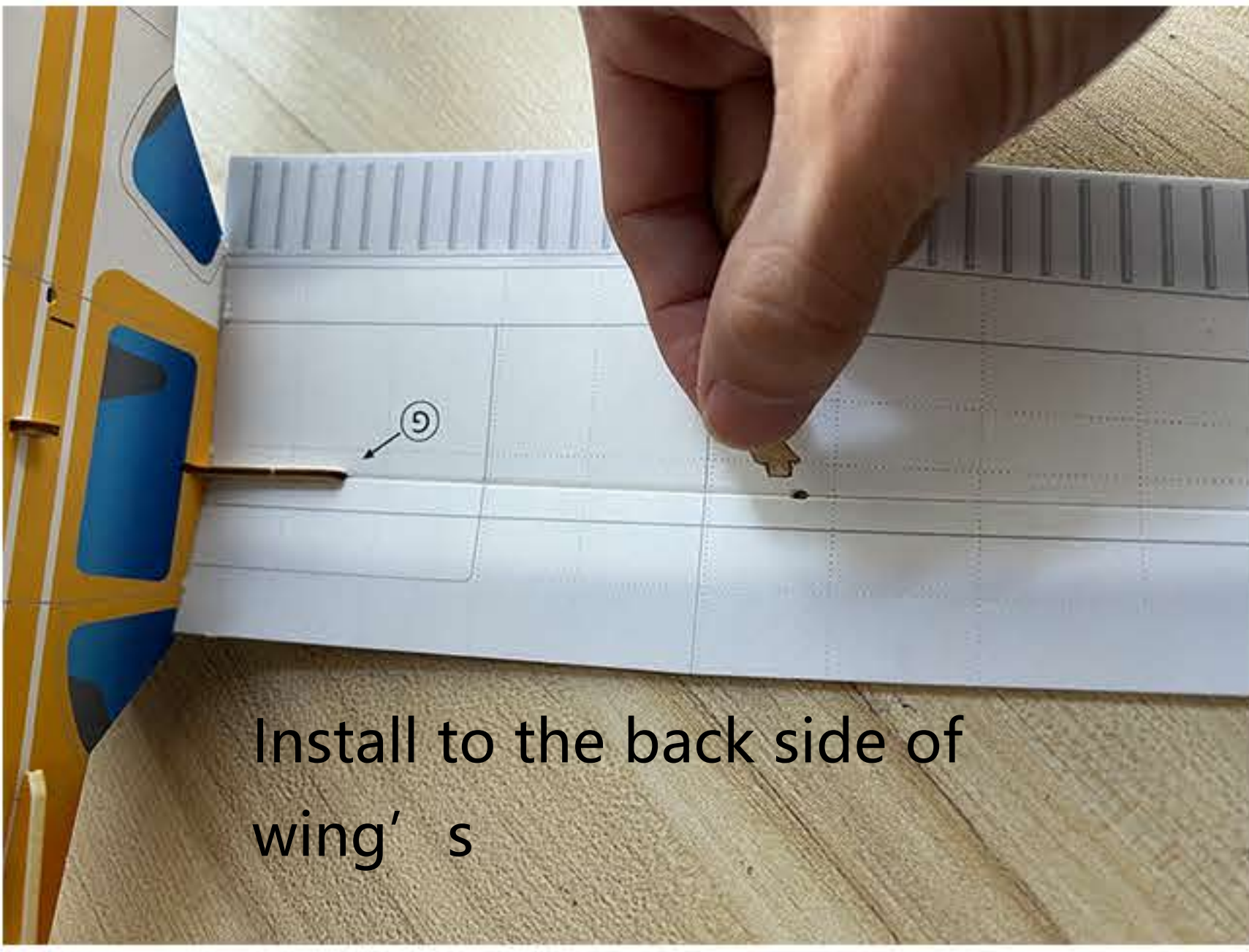




Wing brace mount assembly

Take out the wing brace mount: wing side and fuselage side





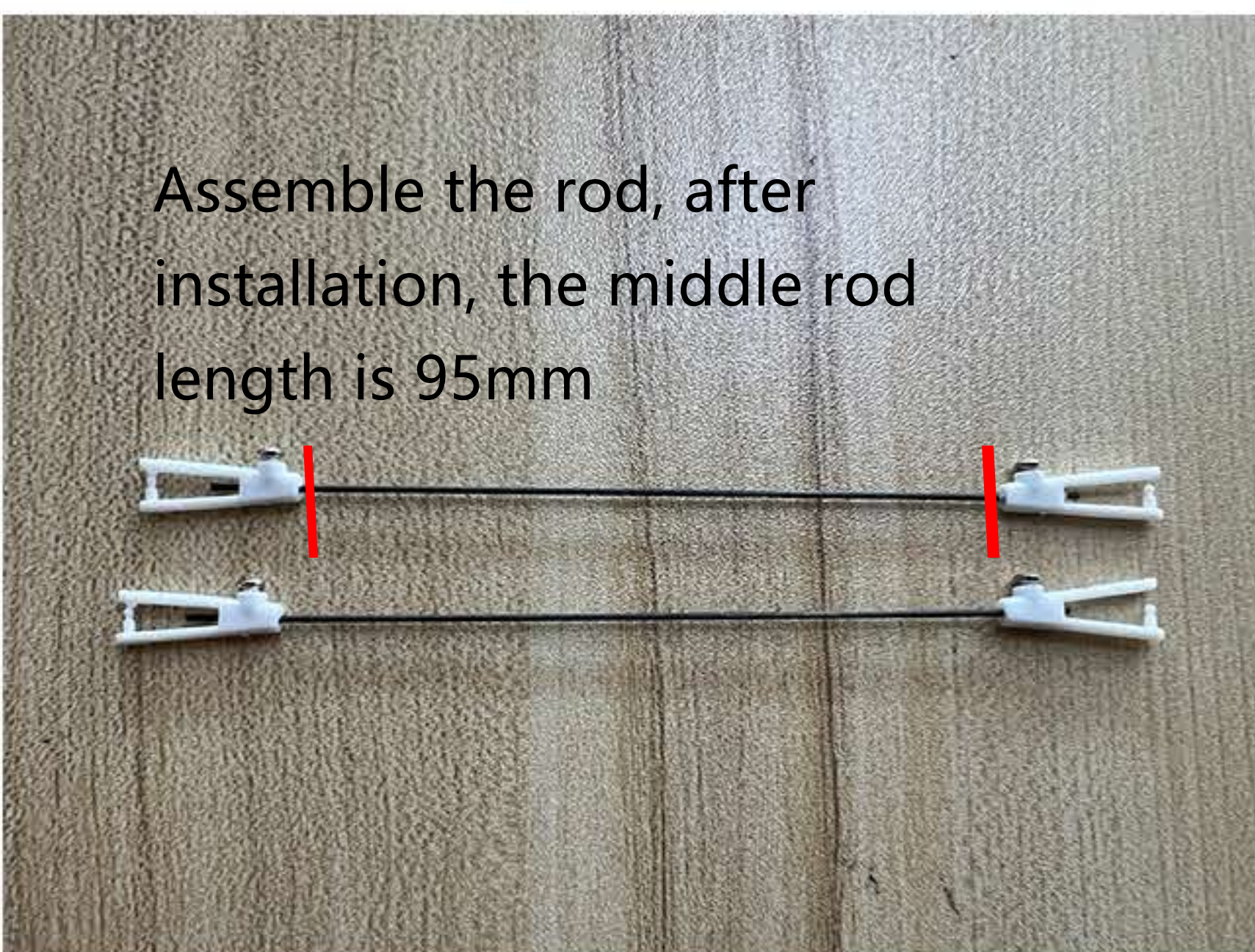
Install to the back side of wing's



Attention to the install direction



Screw chucks(not too tighten)



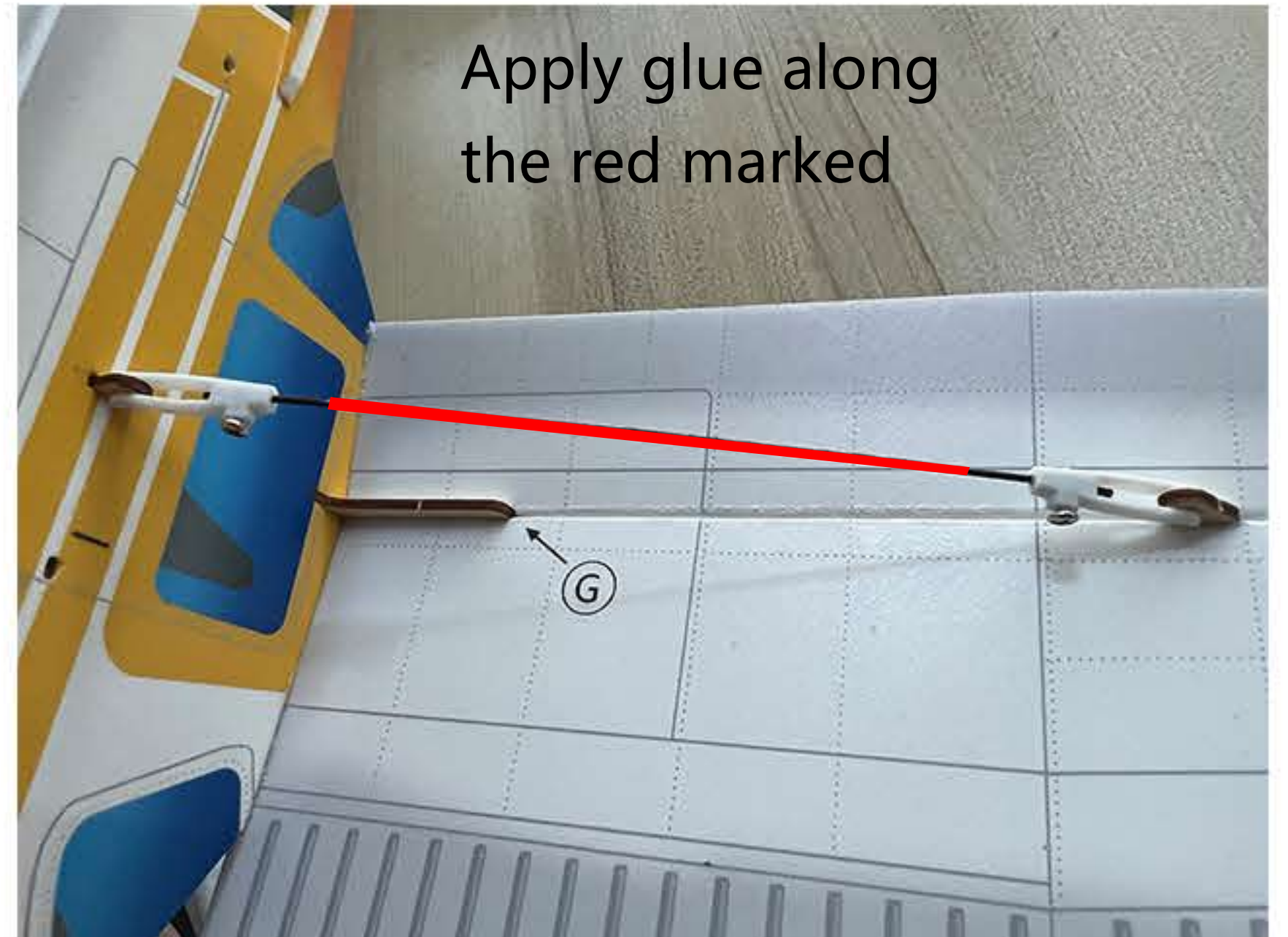
Assemble the rod, after installation, the middle rod length is 95mm



Install to the fuselage and wing side

Take out No.4 board.

Apply glue to the brace rod and paste on the brace plate



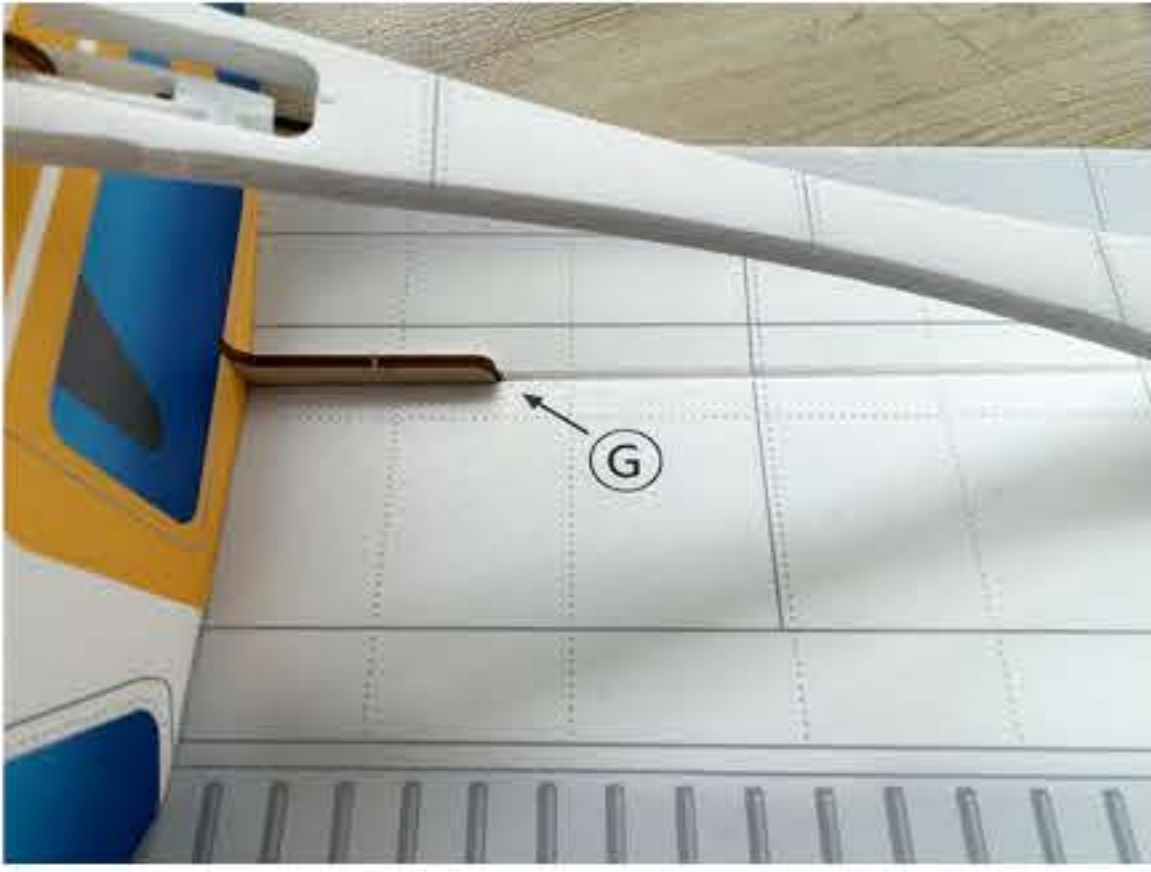
Install the propeller



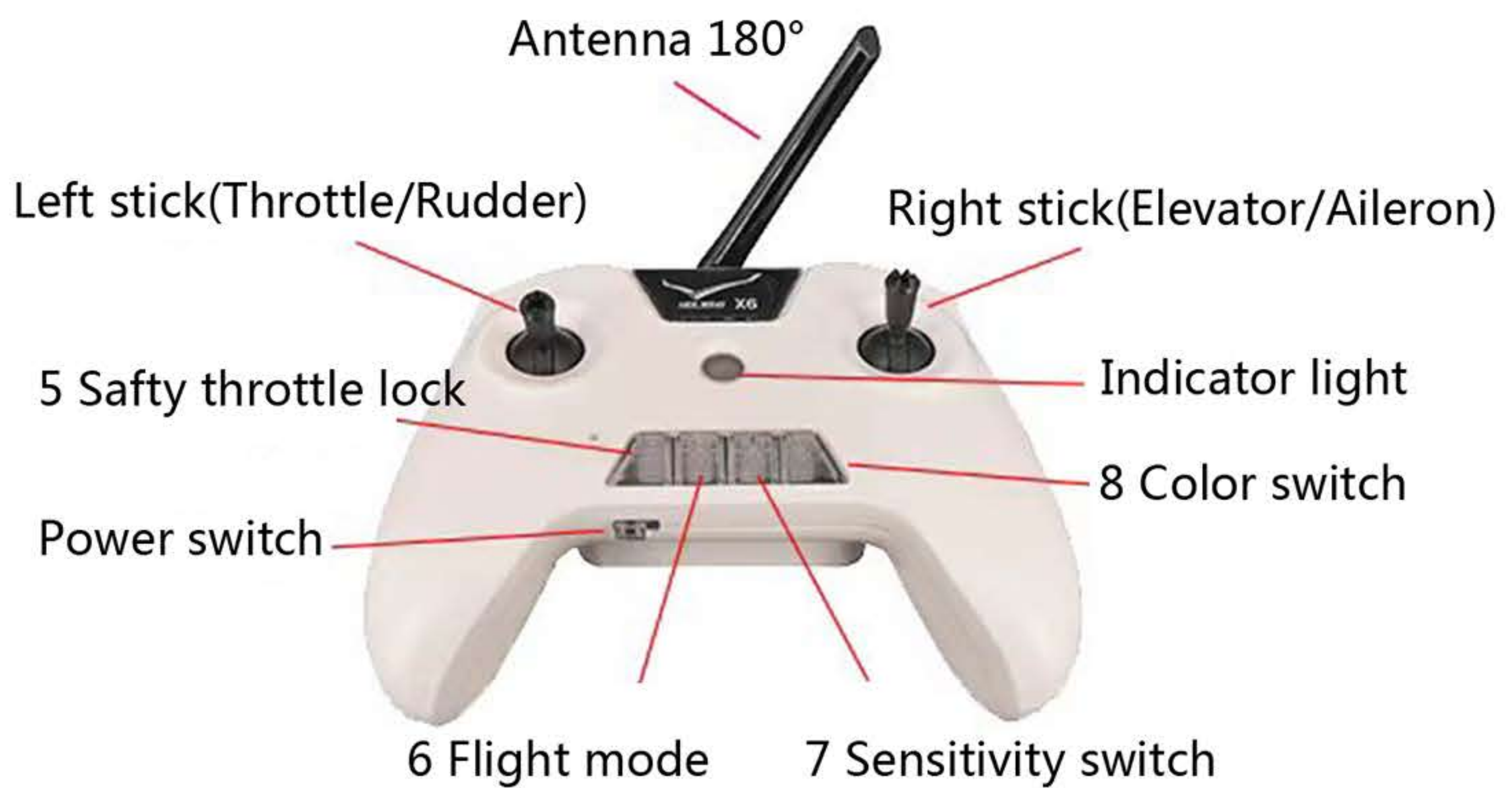
三、 Trial flight

1. Always respect the rules provided by your local remote control aircraft organization. Choose an appropriate flying site consisting of a large open space to ensure the safety of yourself, others and your model.
2. Power on the aircraft, test all channels and functions, make sure all running properly.
3. If you are using throw away to take off, please must attention to the propeller, avoid any unnecessary injuries.

CG is in the position of wing mount as below shows:



X6 Radio User Guide



5 Safety throttle lock button: Press once to unlock, press once to lock

6 Flight mode: Self stabilizing/ manual(default is self-stabilizing mode) Supports to cyclic switching

7 Sensitivity switch: High sensitivity/Low sensitivity(default is low) Supports to cyclic switching

8 Color switch: Default is red color. (When using RX1.0 flight controller, it supports to control the variable light color' s output)