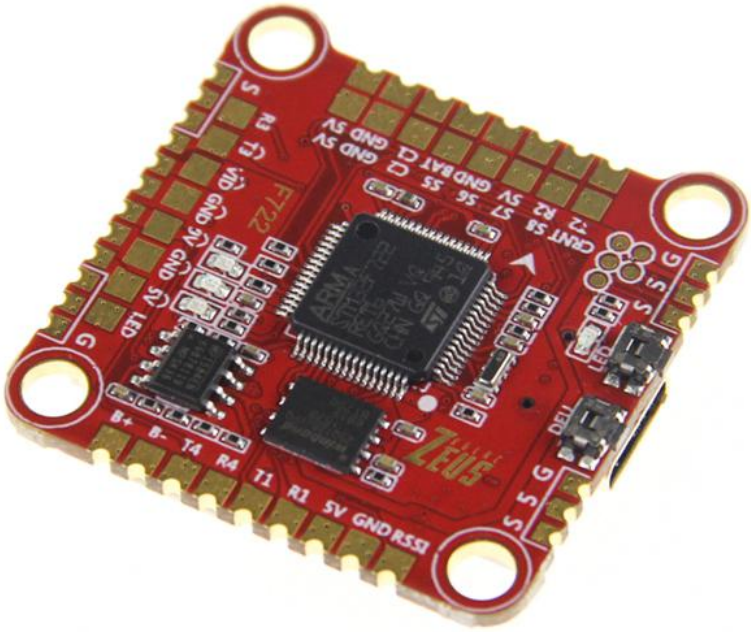
Zeus F722

Flight Controller

Manual



Contents

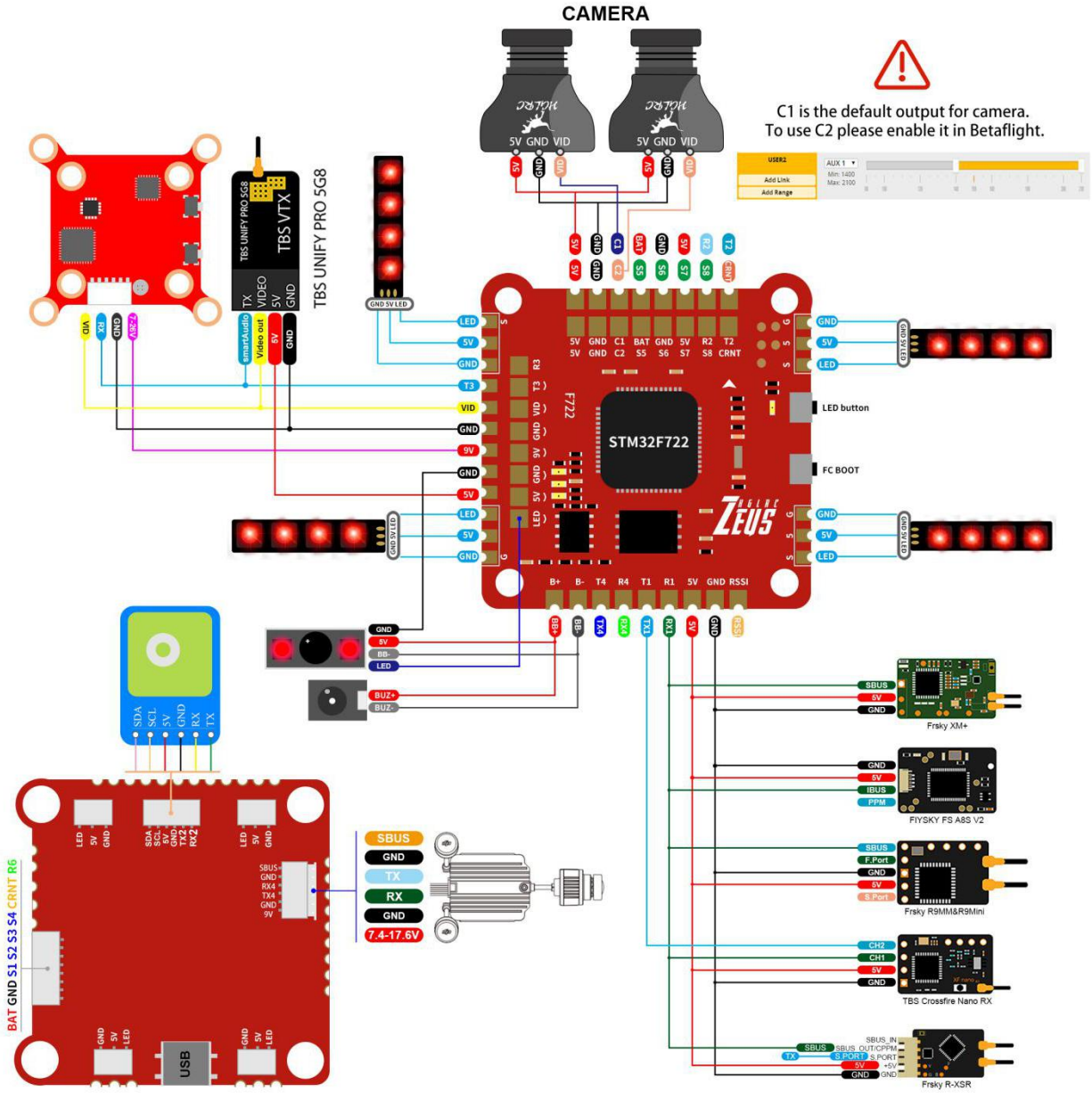
Package Included

Zeus F722 Flight Controller*1	Accessory Bag*1

1.Product Specifications

Product parameters	
Model	Zeus F722 Flight Controller
Weight	8.1g
Usage	for 100mm-450mm Frame Kit
MPU	MPU6000
CPU	STM32F722 RET6
Black Box	16M
Support receiver	SBUS .IBUS.DSMX/R9MM
Input Voltage	3-6S Lipo
BEC Output	5V/3A, 9V/2A
LED Output	5V/3A
Size	37.3x37.3mm board, 30.5mm mounting holes

2.Interface Description



3.Check the flight control drive

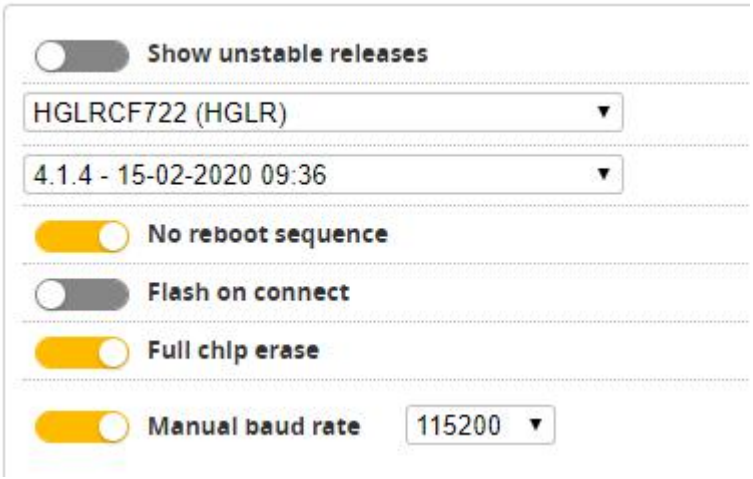
1. Long Press BOOT buttons.connect USB.The system automatically install the driver

2.Driver cannot be installed, please download ImpulseRC_Driver_Fixer

3.Double-click on the run(Plug in the flight controller to automatically install the driver)

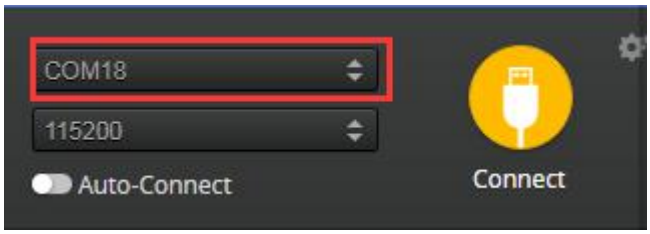
4.open betaflight configurator , enter DFU mode

5.Click Firmware Flasher Select firmware version



6.Click Load Firmware [Online] Load firmware. Flash Firmware Waiting for completion Erasing ... It will be prompted upon completion. Programming: SUCCESSFUL

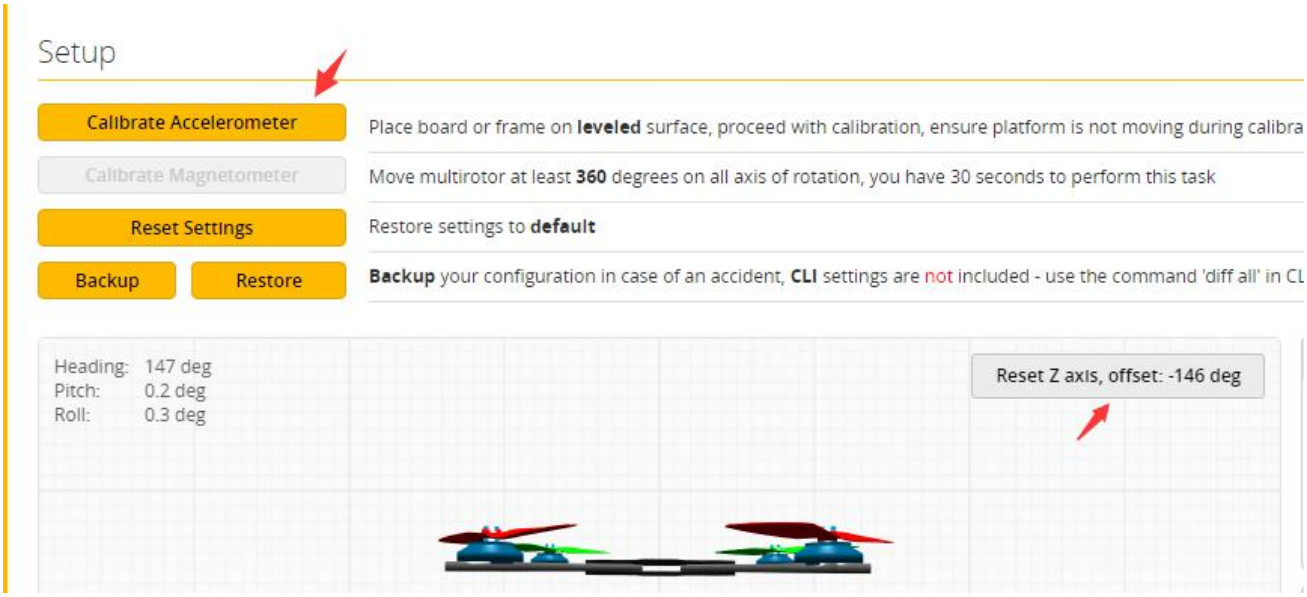
7. open betaflight configurator .Controller plugged into the computer. Betaflight Automatically assigned port, click “Connect” Enter setup interface（Different computer COM）



4.Calibration accelerometer

1. Put the aircraft horizontal and click “Reset Z axis”

Click again 



5.UART serial port use

1.UART1 uses the receiver

2.UART2 uses GPS

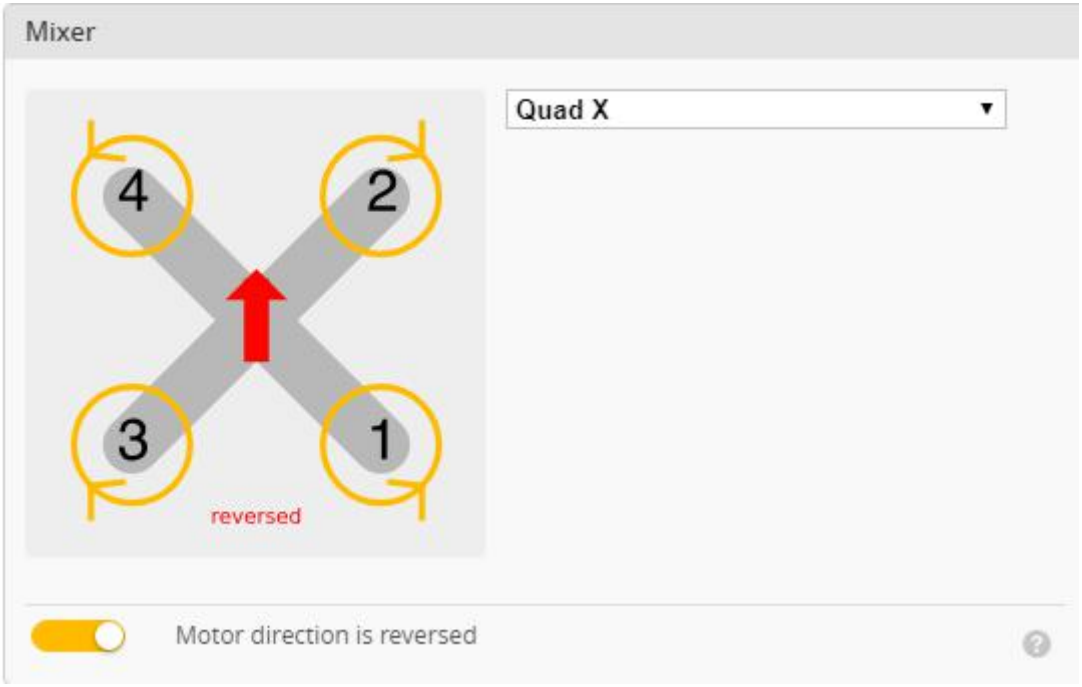
3.UART3 uses VTX image transmission

4.UART4 uses DJI

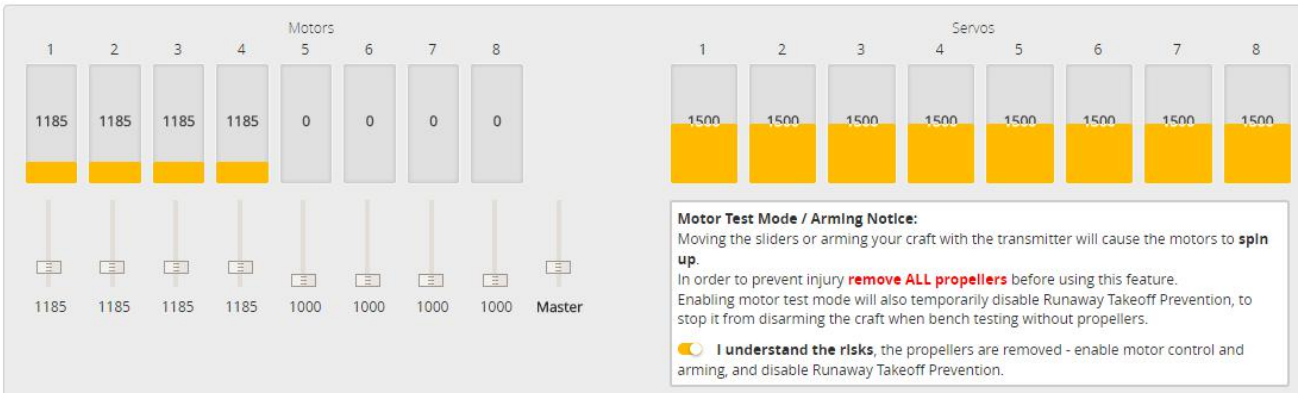
5.UART6 uses ESC telemetry

6.Select aircraft model

1.Click Configuration Select model

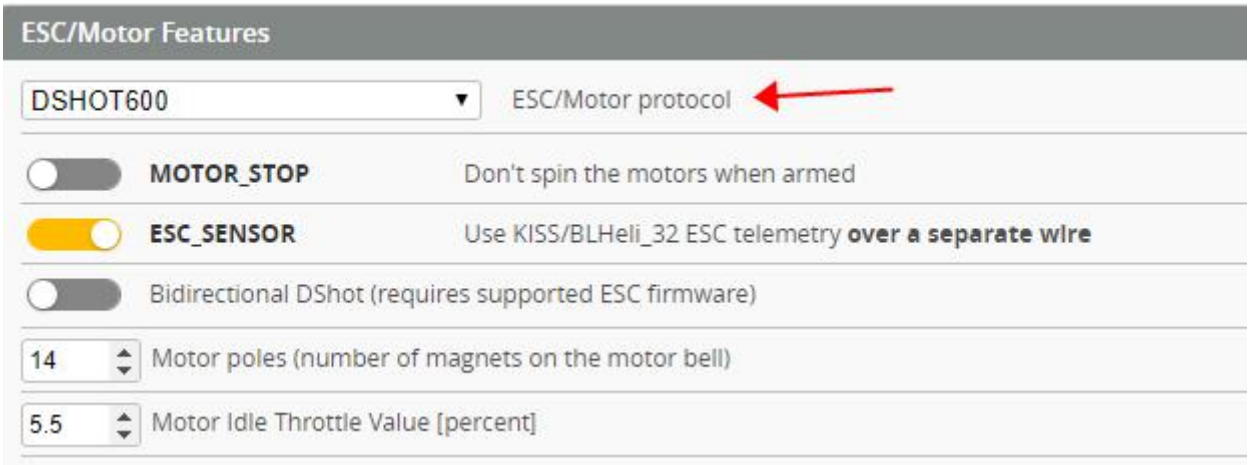


2.Click Motors Click "I understand the risks" Push Master to check motor steering "Master" Steering can be changed at BLHeliSuite



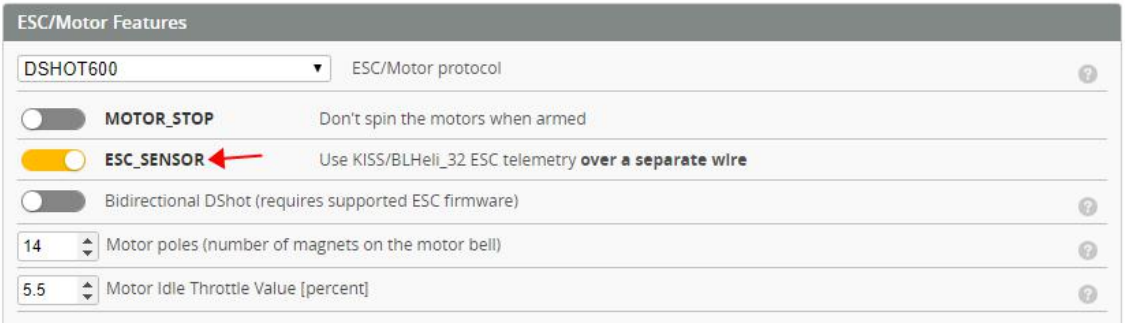
7.Choose ESC protocol

1.Choose the right ESC protocol, the optional universal protocol DSHOT600.

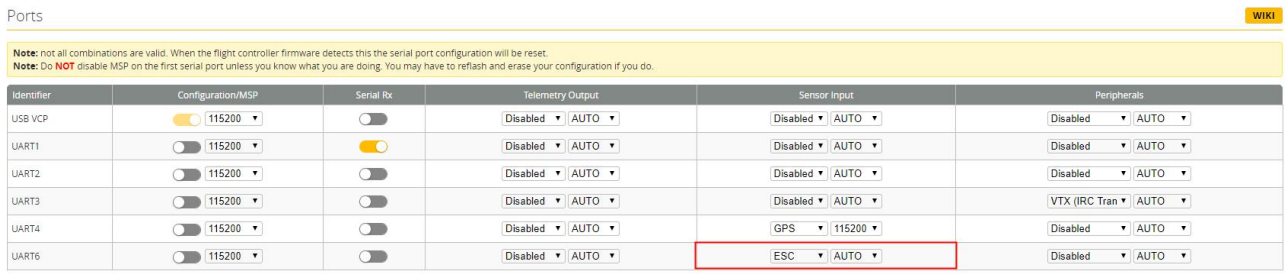


8.Turn on ESC telemetry

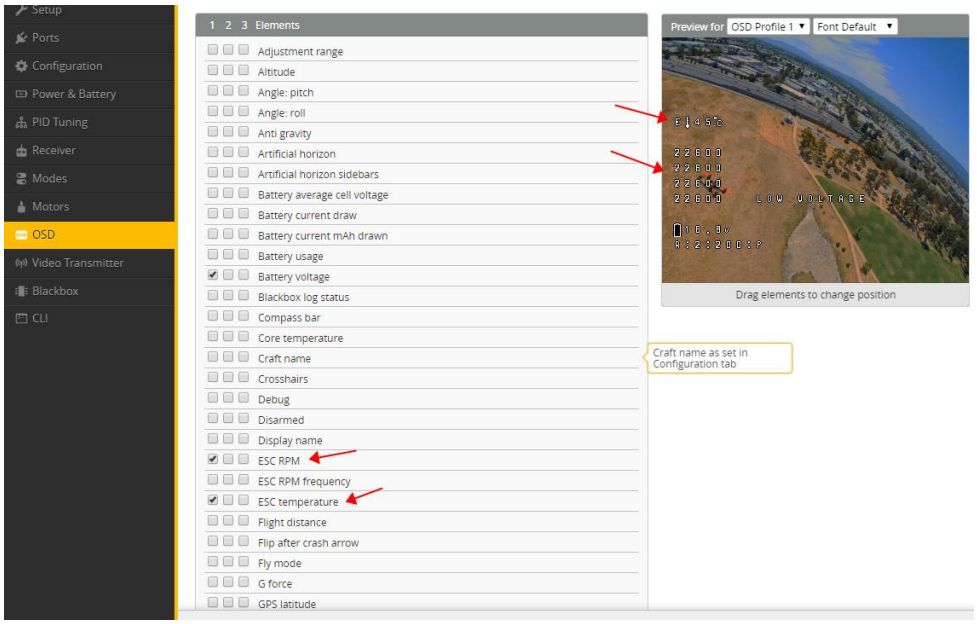
1.Use BLHeli_32 ESC telemetry over a separate wire



2.Open ESC telemetry serial port.TX on the ESC needs to be connected to the RX6 on the flight controller to use the ESC telemetry

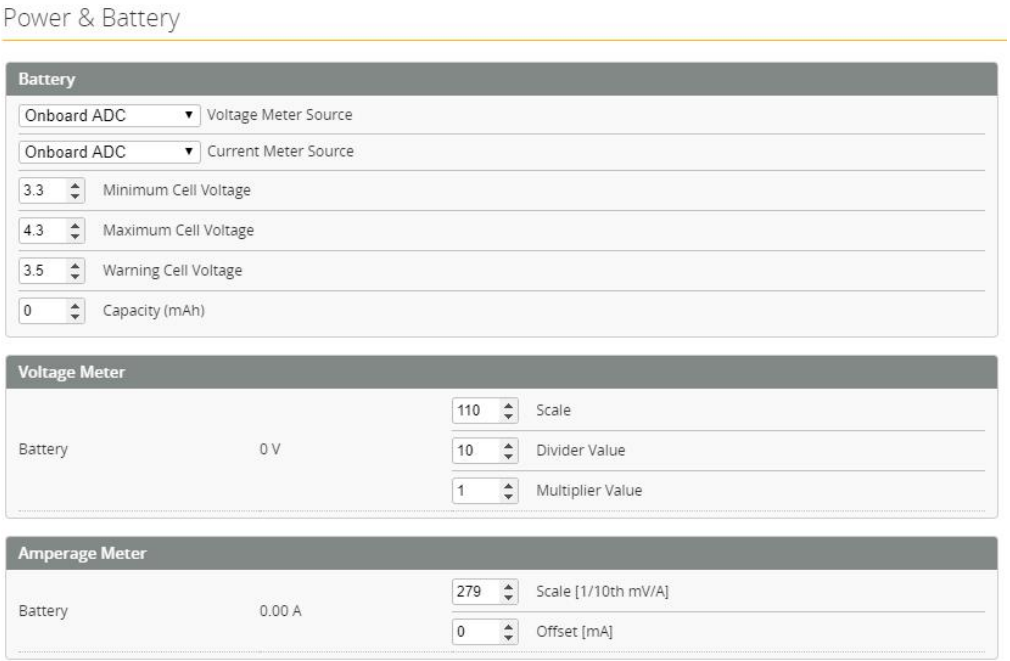


3.View telemetry data on OSD



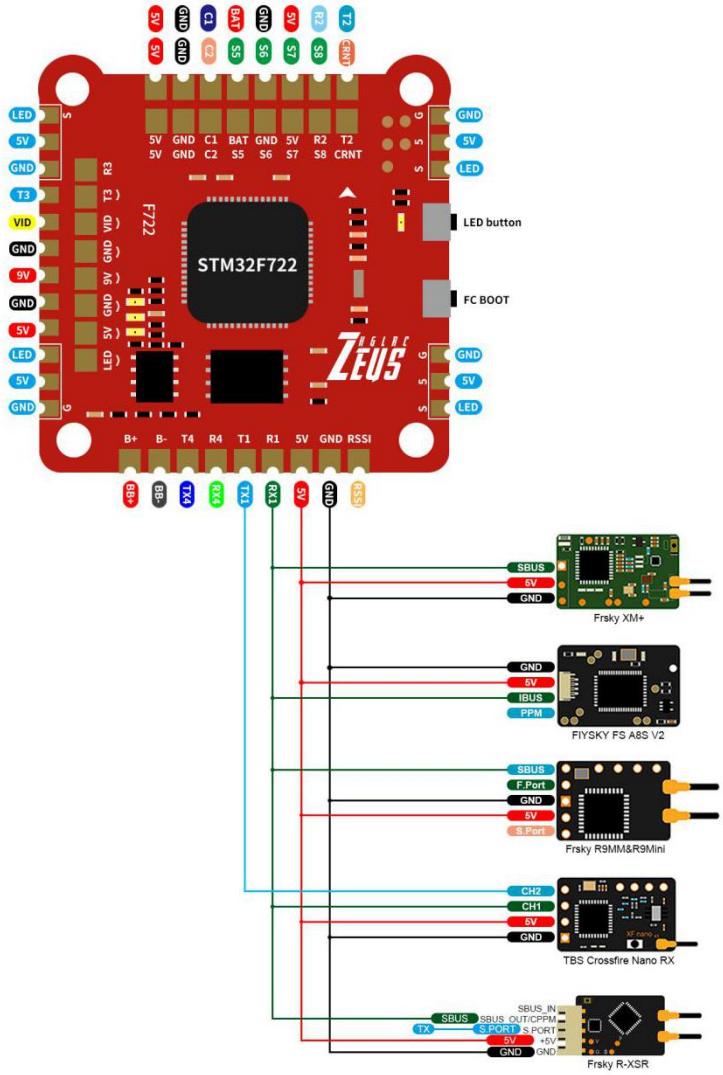
9.Voltage and current parameters setting

1.Click Power & Battery Setting parameters



10.Setting up the receiver

1.Receiver connection diagram



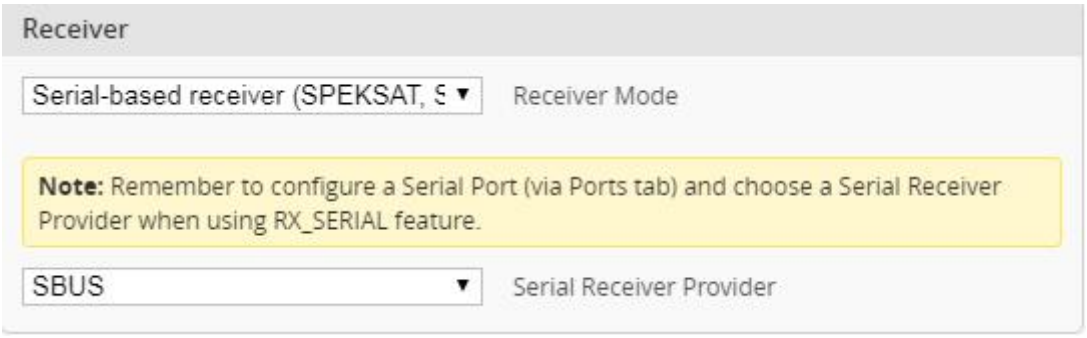
2.Click Ports .have found "UART1" Open the receiver serial port

Ports

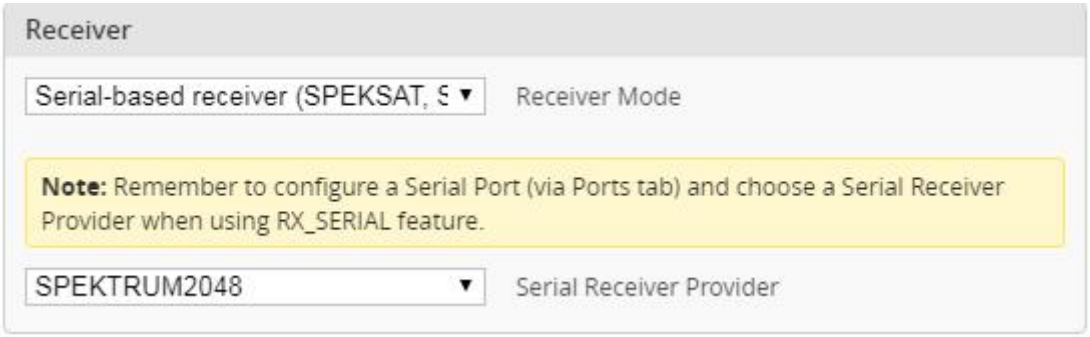
Note: not all combinations are valid. When the flight controller firmware detects this the serial port configuration will be reset.
Note: Do **NOT** disable MSP on the first serial port unless you know what you are doing. You may have to reflash and erase your configuration if you do.

Identifier	Configuration/MSP	Serial Rx	Telemetry Output	Sensor Input	Peripherals
USB VCP	115200		Disabled AUTO	Disabled AUTO	Disabled AUTO
UART1	115200		Disabled AUTO	Disabled AUTO	Disabled AUTO
UART2	115200		Disabled AUTO	Disabled AUTO	Disabled AUTO
UART3	115200		Disabled AUTO	Disabled AUTO	Disabled AUTO
UART4	115200		Disabled AUTO	Disabled AUTO	Disabled AUTO
UART6	115200		Disabled AUTO	Disabled AUTO	Disabled AUTO

3.Set the SBUS receiver



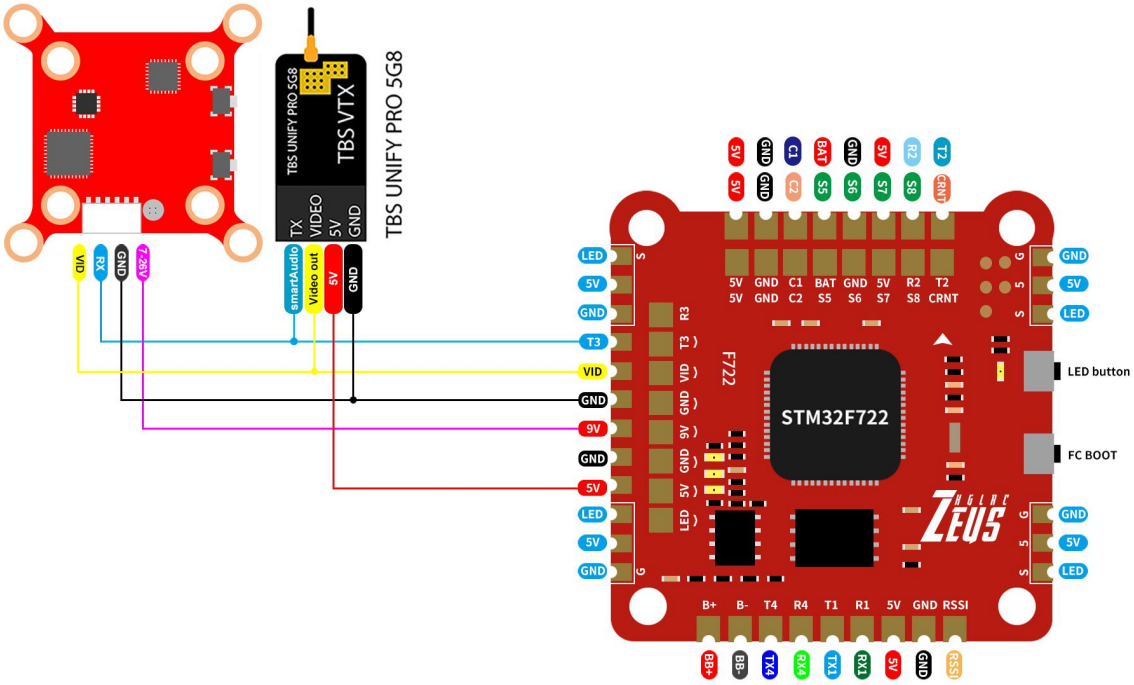
4.Set the DSMX receiver



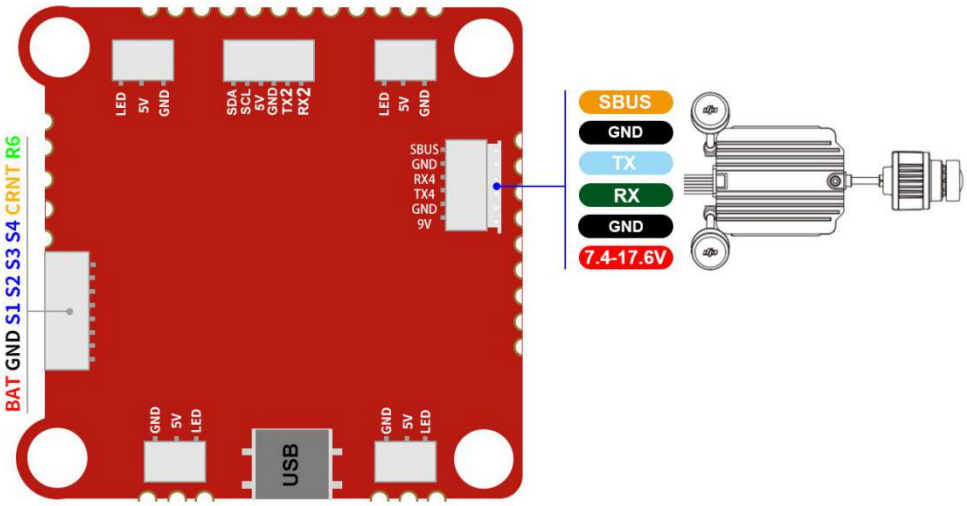
11.VTX serial port use wiring .

DJI serial port use wiring

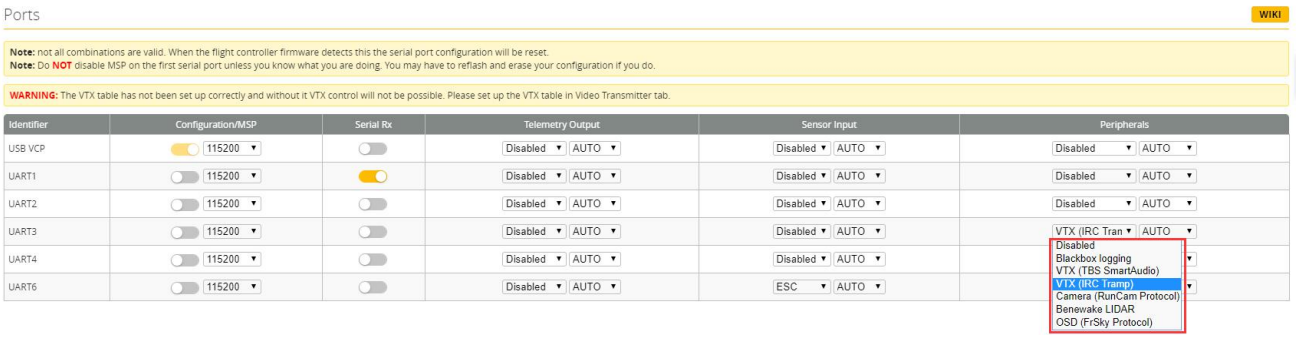
1. 5.8G VTX connection



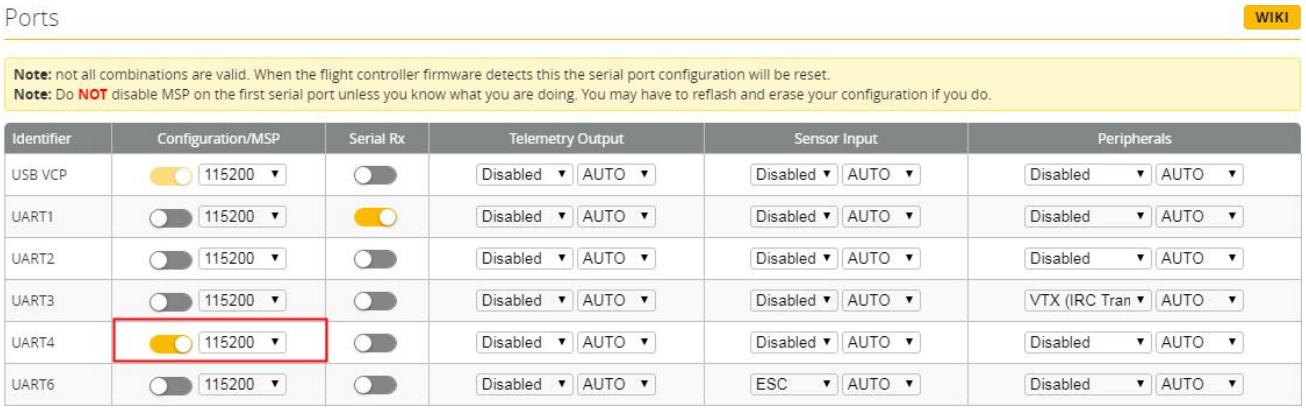
2. DJI FPV Air Unit wiring



3. 5.8G VTX serial port opens. The protocol is selected according to its own VTX protocol.



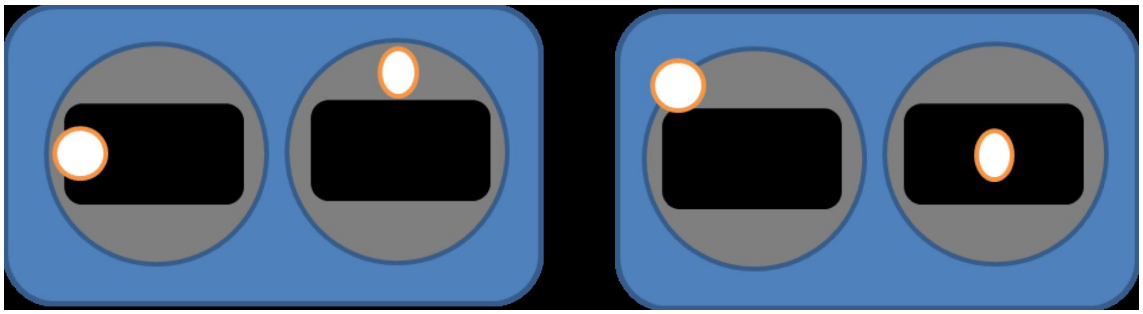
4. DJI serial port opens



5.Use OSD to adjust VTX

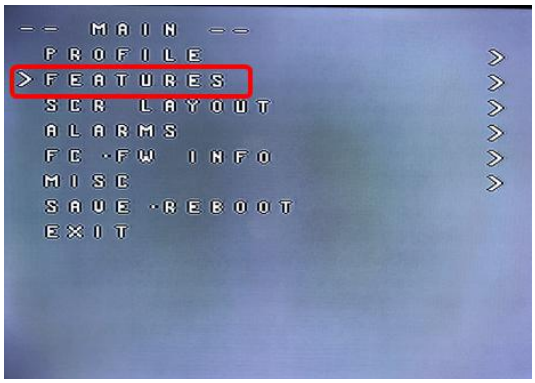
which displays information like battery voltage and mAh consumed while you fly. In addition, the Betaflight OSD can be used to configure the quadcopter, making in-field adjustments and tuning more convenient.

MODE2 MODE1



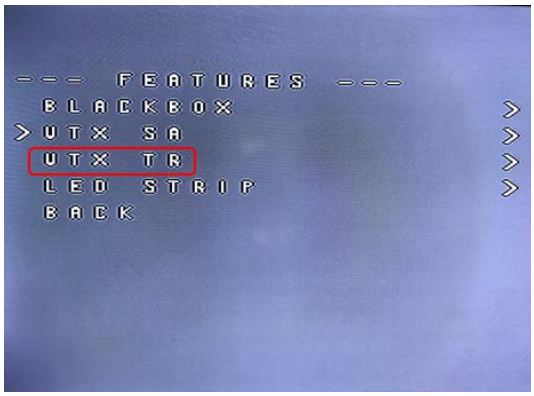
The graphics above show the stick command to bring up the OSD menu. The stick command is: throttle centered, yaw left, pitch forward. The exact stick command therefore depends on which mode your transmitter sticks are in.

In the OSD menu, use pitch up/down to move the cursor between menu items. When a menu option has a > symbol to the right of it, this indicates that it contains a sub-menu.



Roll-right will enter the sub-menu. For example, in the screen to the right, moving the cursor to “Features” and then moving the roll stick to the right will enter the “Features” sub-menu.

If you are using a video transmitter that supports remote configuration, enter the “Features” menu to configure the vTX. From there, enter either “VTX SA” if you are using SmartAudio (TBS Unify) or “VTX TR” if you are using IRC Tramp Telemetry.



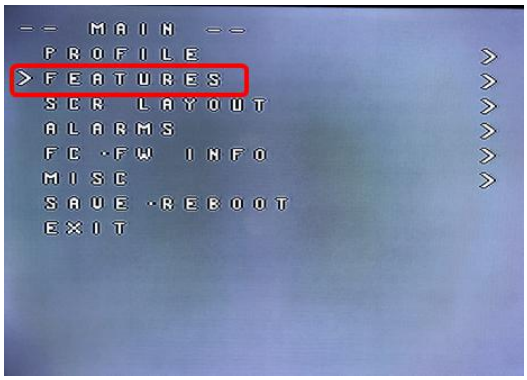
To adjust PIDs, rates, and other tuning-related parameters, enter the “Profile” sub-menu.

In the “Scr Layout” sub-menu, you can move the OSD elements (like battery voltage, mAh, and so forth) around on the screen.

The “Alarms” sub-menu lets you control when the OSD will try to alert you that battery voltage is too low or mAh consumed is too high.

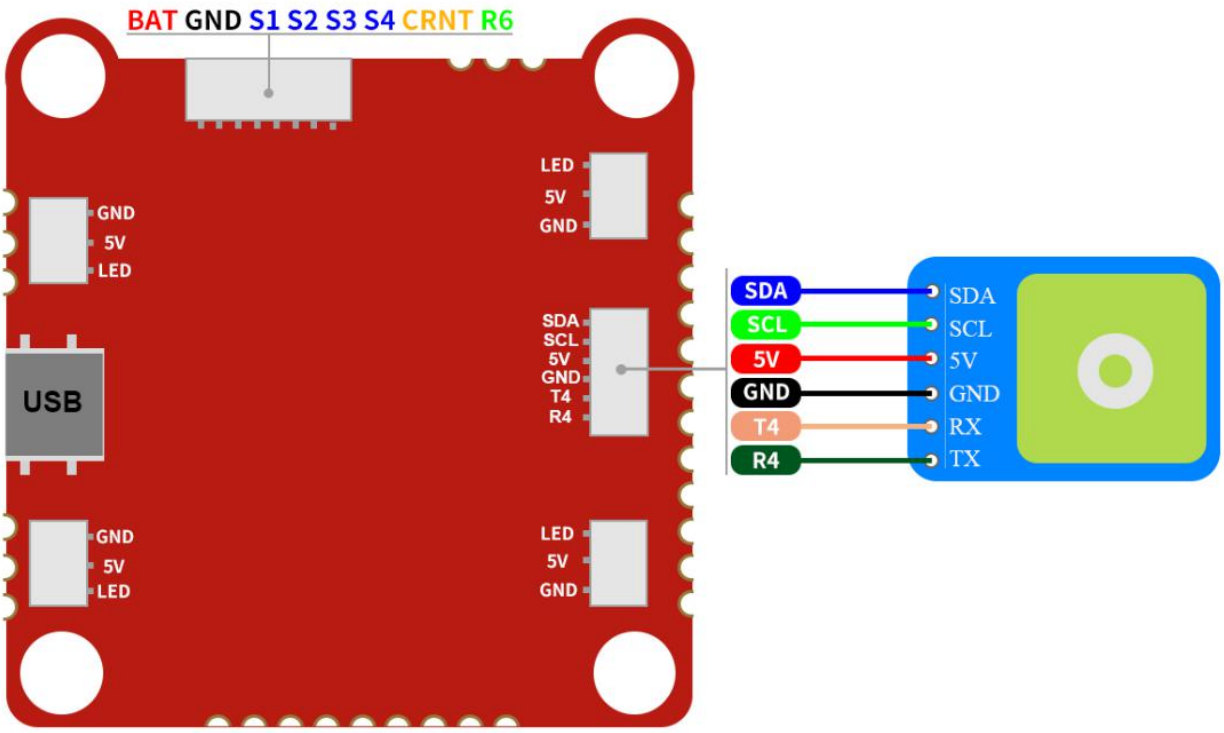
When a parameter can be modified, the parameter’s current value will be shown on the right-hand side of the screen. In this case, roll left/right will adjust the parameter up and down.

The screen to the right shows the current vTX settings. From here, you can change the frequency band, channel, and power level of the video transmitter. After making the changes, move the cursor to “Set” and press roll-right to confirm the settings.



12.GPS parameters setting

1. GPS connection diagram



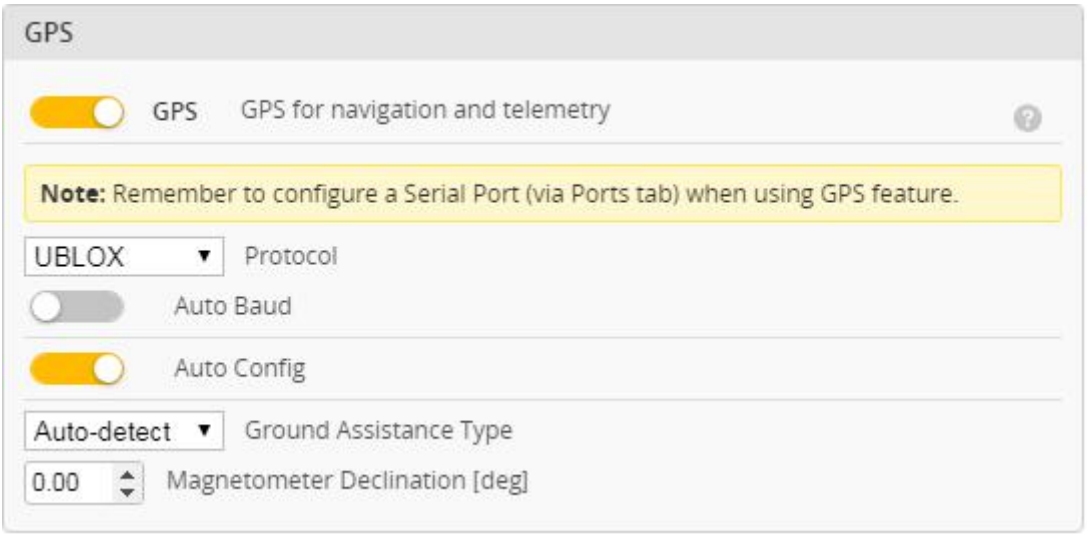
2.Open the GPS serial port

Ports WIKI

Note: not all combinations are valid. When the flight controller firmware detects this the serial port configuration will be reset.
Note: Do **NOT** disable MSP on the first serial port unless you know what you are doing. You may have to reflash and erase your configuration if you do.

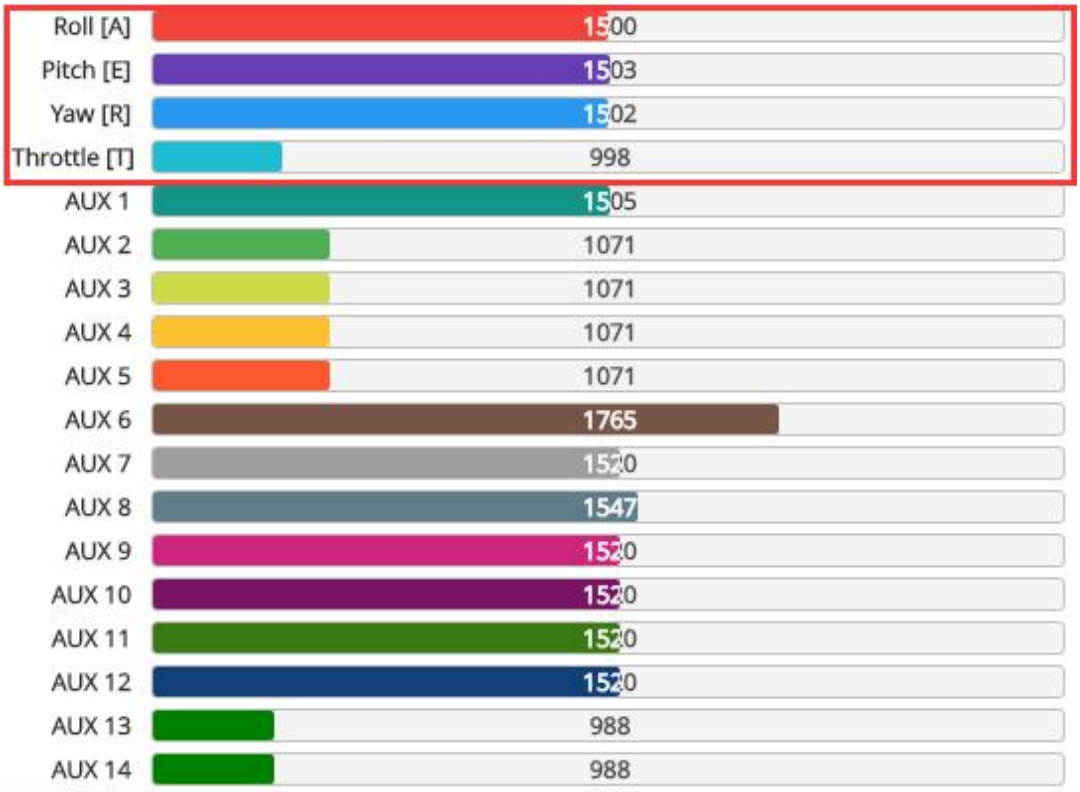
Identifier	Configuration/MSP	Serial Rx	Telemetry Output	Sensor Input	Peripherals
USB VCP	115200		Disabled AUTO	Disabled AUTO	Disabled AUTO
UART1	115200		Disabled AUTO	Disabled AUTO	Disabled AUTO
UART2	115200		Disabled AUTO	GPS 115200	Disabled AUTO
UART3	115200		Disabled AUTO	Disabled AUTO	VTX (IRC Tran AUTO
UART4	115200		Disabled AUTO	Disabled AUTO	Disabled AUTO
UART6	115200		Disabled AUTO	Disabled AUTO	Disabled AUTO

3.When using the GPS function, remember to configure the serial port (via the Ports tab).



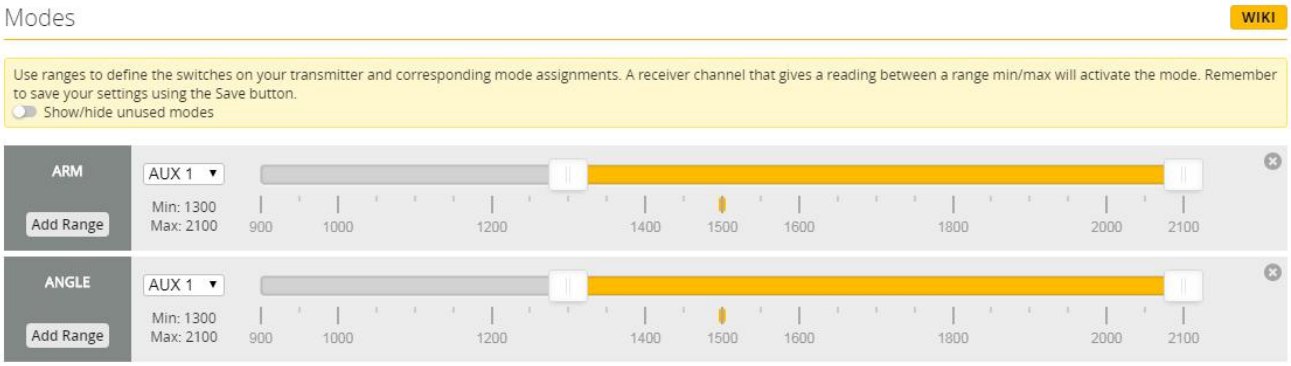
13.Check receiver signal

1.Click Receiver Check the remote control output signal



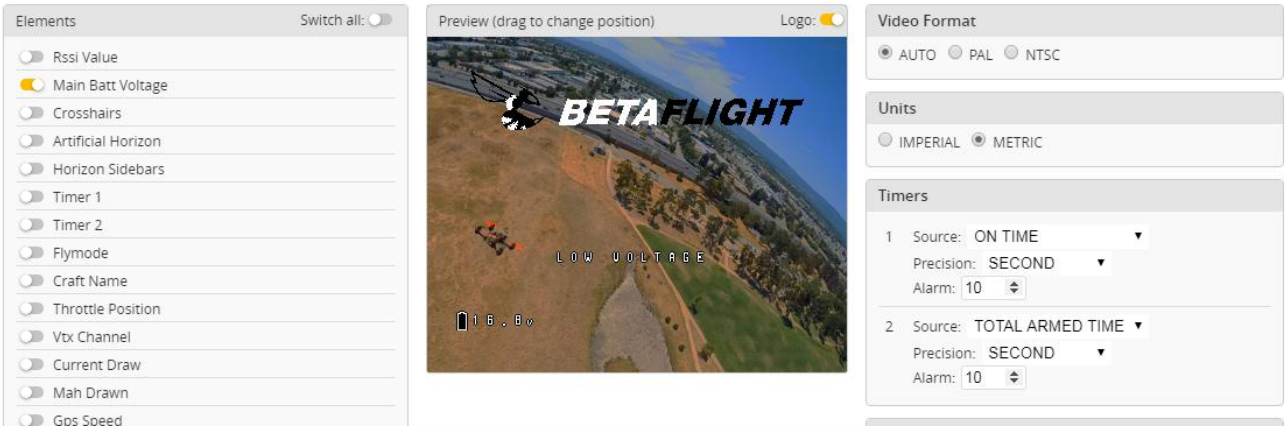
14.Select flight mode startup mode

1.Click Modes set up the function of remote control switch across the channel (below are for reference only)



15.OSD settings

1.Click OSD the OSD Settings, according to the need to choose, drag the OSD schematic diagram of the parameters can be adjusted.



16.LED settings

1.LED function buttons:

Short press to switch colors.

Press and hold for 3 seconds to enter the blinking mode switch

(LED status light is always on)

2.Blinking mode:

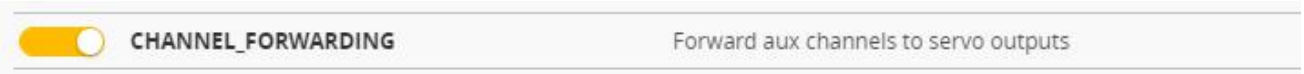
Steady / Fast Flash / Breathing Light / Colorful Slow Flash

3.LED light can be controlled via CH5(AUX1) of transmitter with Channel_Forwarding enabled.

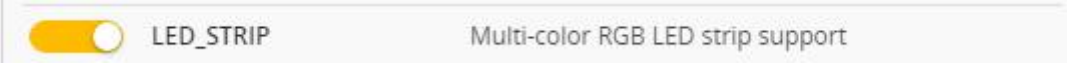
Click CLI enter：

resource servo 1 A08
SAVE

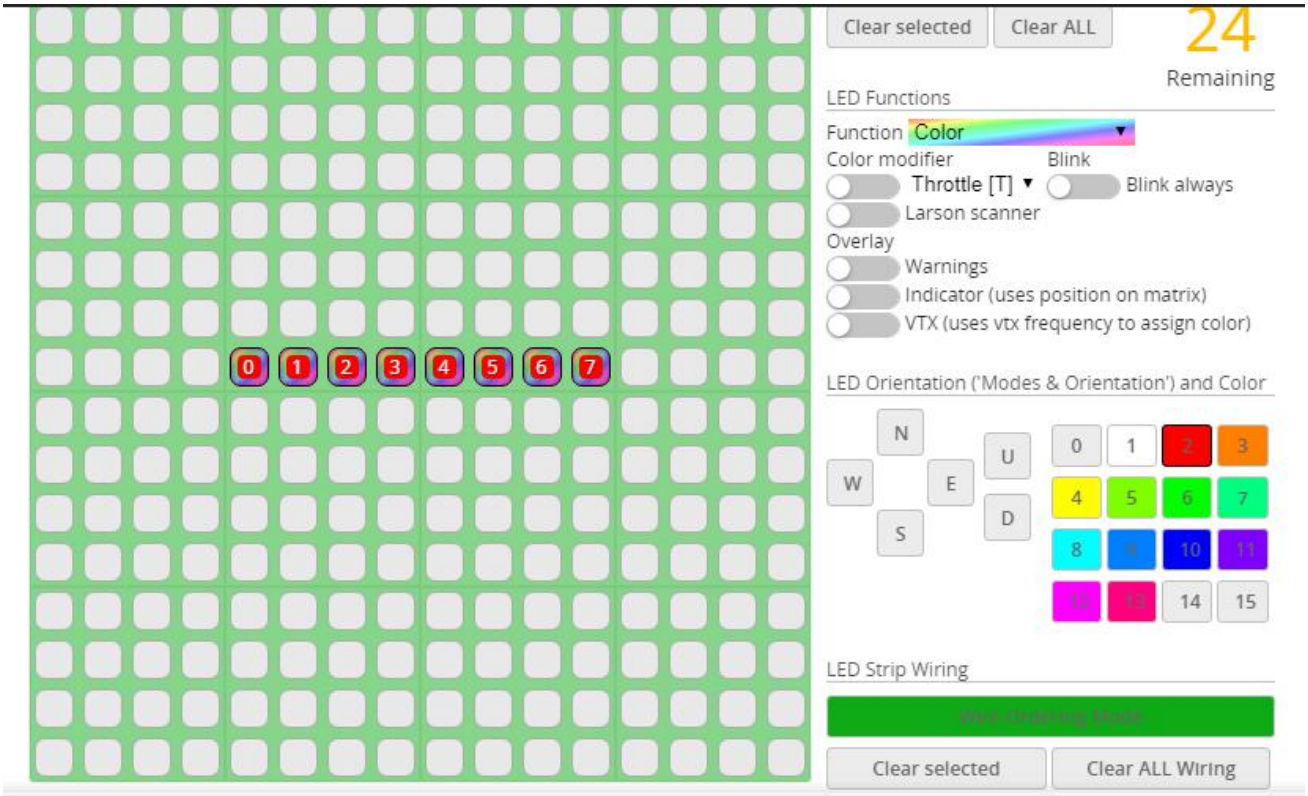
4.Click Configuration Forward aux channels to servo outputs



5.Click Configuration Turn on LED support



6.Click LED Strip .Click Wire Ordering Mode set according to need



17.Troubleshooting

Warning:

Please read the cautions as follows, otherwise stability of your flight controller cannot be ensured, your flight controller will even get damaged.

- Keep focus on the polarity. Check carefully before power supply.
- Cut off the power when you connect, plug and pull anything.
- The refresh rate of PID and Gyroscope is up to 8K/8K.

after sales question:

1. After receiving the goods, it is found that the product can not be used normally. If the return to the factory is a quality problem, the repair service will be provided free of charge.

2. If the product is damaged due to improper operation, the repair service may be provided under the condition that the inspection can be repaired.

3. For domestic customers, please contact the after-sales service personnel. For overseas customers, please contact the official website for after-sales service.

Product daily problems

1.OSD garbled:

If you find garbled characters, please open Betaflight, click “OSD” .and click “Font Manager” clicks on “Upload Font” to update

1. When plugged in the battery, the aircraft does not pass the self-test without "BBB" sound. There is only one sound.

Please check if the ESC agreement is correct

3.The spin of the aircraft keeps spinning

1. Please check if the propeller is correct
2. Please check if the motor direction is correct